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A Queueing Model with Dependence between Service and Interarrival Times

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Abstract

We consider a storage model that can be either interpreted as a certain queueing model with dependence between a service request and the subsequent interarrival time, or as a fluid production/inventory model with a two-state random environment. We establish a direct link between the workload distributions of the queueing model and the production/inventory model, and we present a detailed analysis of the workload and waiting time process of the queueing system.

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1 Introduction

In this paper we consider a storage model that can be interpreted either as a certain queueing model with dependence between a service request and the subsequent interarrival time, or as a fluid production/inventory model with a two-state random environment. The two models are directly related in the sense that the steady-state law of the workload in the queueing interpretation can be expressed in terms of the steady-state law of the buffer content in the fluid interpretation. As a stochastic model, the fluid interpretation may be more natural than the queueing one; however, the queueing interpretation enables to locate the problem in the general setting of queueing models, and to use well-established tools and results from queueing theory for the solution.

Under the fluid interpretation, we consider a manufacturing problem incorporating machine reliability and maintenance. We assume that items are
produced continuously and uniformly by a single machine that is subject to breakdown. During a machine ON time, there is a deterministic net flow into the inventory buffer at rate \( \alpha > 0 \), where \( \alpha \) is the production rate minus the demand rate. If a failure occurs before some time \( T \) has elapsed, then a machine repair operation will start; this results in an OFF period of type 0. However, if a failure does not occur before \( T \), then the controller stops production to initiate a preventive maintenance action; this results in an OFF period of type 1. During an OFF period of either type 0 or type 1, there is a deterministic demand generating a linear outflow from the inventory buffer at a constant rate that, w.l.o.g., is taken to be 1. It is assumed that negative inventory is not allowed, so there is no outflow whenever the buffer is empty.

Perry and Posner [13] have studied the special case in which the threshold \( T \) is a constant and the OFF periods of both types are exponentially distributed. Their analysis is based on the fact (cf. Kella and Whitt [9]) that the conditional steady-state buffer content distribution, given that it is positive, is independent of the inflow rate \( \alpha \). Obviously, the validity of this fact holds for the more general case - to be considered in the present paper - in which the threshold \( T \) is a generally distributed random variable. By setting \( \alpha = \infty \), we generate a sample path in which ON periods are deleted and are represented by upward jumps, while the OFF periods are being glued together.

This brings us to the above-mentioned queueing interpretation, as the resulting process can be interpreted as the workload process of the following queueing model. Customers arrive with a service request at a single server. Service requests of successive customers are independent, identically distributed random variables \( B_i, i = 1, 2, \ldots \). Upon arrival, the service request is registered. If the service request is less than a threshold \( T_i \), then the next interarrival interval is exponentially distributed with rate \( \lambda_0 \) (this corresponds to an OFF period of type 0); otherwise, the service time becomes exactly equal to \( T_i \) (is cut off at \( T_i \)), and the next interarrival interval is exponentially distributed with rate \( \lambda_1 \).

In this paper we concentrate on the queueing interpretation. We present a detailed analysis of the joint distribution of workload and 'state of the arrival process', as well as of the waiting time distribution. We refer to Kella and Whitt [9] for a discussion of the equivalence relation between the workload process of the GI/G/1 queue and the buffer content process of a fluid model with linear flow and a two-state random environment. See [8]
for an extension to the case of non-linear flow, and [3] for several equivalence relationships in the case of a three-state random environment. For related work on production and manufacturing fluid models, in which equivalence relations with queueing models are studied, we refer to Meyer, Rothkopf and Smith [11, 12], Chen and Yao [4], and Vanneste and Van der Duyn Schouten [15].

According to the original production/inventory interpretation, our model is motivated as a replacement model with preventive maintenance. For a detailed survey on replacement policies and preventive maintenance we refer to Beichelt [1] and Voldes-Flores and Feldman [16].

According to the queueing interpretation, our model is a correlated single server queue with Markov arrivals. There are quite a few studies on single server queues in which the service time of a customer depends on the previous interarrival time; see, e.g., Borst et al. [2] that also contains an extensive list of references. But in the present case, as in [13] mentioned above, it is the interarrival time that depends on the service request of the previous arrival. In principle, this kind of dependence is allowed in the Lindley approach to the waiting time process in the $G/G/l$ queue (see Cohen [6], Section 11.6.3). However, the resulting Wiener-Hopf decomposition in general does not yield a very explicit solution – whereas in the present case such an explicit solution is indeed obtained. See Cidon et al. [5] for a detailed analysis of a $M/1$ queue in which the interarrival time depends linearly on the service time of the previous customer.

The paper is organized as follows. In Section 2 we present the queueing model in detail. The workload process is analysed in Section 3, and the waiting time process in Section 4. Section 5 contains conclusions and some suggestions for further research.

2 Model formulation

We consider the following queueing model. Customers arrive with a service request at a single server. Service requests of successive customers are independent, identically distributed (i.i.d.) random variables $B_i$, $i = 1, 2, \ldots$ with distribution $B(\cdot)$, mean $\beta$ and Laplace-Stieltjes transform (LST) $\beta(\cdot)$. Upon arrival, the service request is registered. If the service request $B_i$ is less than a threshold $T_i$, then the next interarrival interval is exponentially distributed.
with rate \( \lambda_0 \); otherwise, the service time becomes exactly equal to \( T_i \) (is cut off at \( T_i \)), and the next interarrival interval is exponentially distributed with rate \( \lambda_1 \).

Perry and Posner [13] have studied this model in the case of a deterministic threshold \( T \). In the production/inventory application that motivated their study, the threshold is not necessarily deterministic. In the present study, we assume the threshold \( T_i \) to be i.i.d. random variables with general distribution \( T(\cdot) \) that has mean \( \tau \) and LST \( \tau(\cdot) \). In the sequel, \( B(T) \) shall denote a generic service request (threshold) with distribution \( B(\cdot) \) \( (T(\cdot)) \). It will turn out that a detailed analysis of the steady-state workload process, and of the waiting time, is possible. The workload analysis will be provided in Section 3, and the waiting time analysis in Section 4. We close the present section with some useful additional notation, and two observations. Define, for \( \Re s \geq 0 \):

\[
\chi(s) := \mathbb{E}[e^{-sB(B < T)}] = \int_{x=0}^{\infty} e^{-sx}(1 - T(x))dB(x), \tag{2.1}
\]

\[
\psi(s) := \mathbb{E}[e^{-sT(T < B)}] = \int_{x=0}^{\infty} e^{-sx}(1 - B(x))dT(x). \tag{2.2}
\]

Note that

\[
\chi(s) + \psi(s) = \mathbb{E}[e^{-\min(B, T)}].
\]

It immediately follows that

\[
\mathbb{E}[\min(B, T)] = -\chi'(0) - \psi'(0).
\]

Our first observation concerns the ergodicity condition. This condition is simply that \( \mathbb{E}[\min(B, T)] \) is less than the mean interarrival time \( EA \), where \( A \) denotes a generic interarrival time:

\[
-\chi'(0) - \psi'(0) < \frac{1}{\lambda_0} \chi(0) + \frac{1}{\lambda_1} \psi(0). \tag{2.3}
\]

For the waiting time, this follows immediately from Lindley’s theorem for the ordinary single server queue ([10], cf. also [6], Section II.1.3), as this theorem applies even if an interarrival time depends on the previous service time.

Our second observation is, that interarrival times are negatively (positively) correlated with the previous service request if \( \lambda_1 > (\lambda_0) \), as one would expect:

\[
\mathbb{E}[BA] = \frac{\beta}{\lambda_1} + \left( \frac{1}{\lambda_1} - \frac{1}{\lambda_0} \right) \chi'(0),
\]
and
\[ \text{EBEA} = \beta \left[ \frac{1}{\lambda_0} \chi(0) + \frac{1}{\lambda_1} \psi(0) \right] = \beta \left[ \frac{1}{\lambda_1} + \left( \frac{1}{\lambda_0} - \frac{1}{\lambda_1} \right) \chi(0) \right], \]
and hence
\[ \text{cov}(B, A) = \left( \frac{1}{\lambda_1} - \frac{1}{\lambda_0} \right) (\chi(0)\beta + \chi'(0)). \quad (2.4) \]
The result follows since \( \chi(0)\beta + \chi'(0) = \text{P}\{B < t\}[\text{EB} - \text{E}[B|B < T]] > 0. \)

3 The workload process

For the queueing model described in the previous section, consider the stochastic process \((V(t), J(t)); t \geq 0\), with \(V(t)\) denoting the workload at time \(t\) and \(J(t)\) denoting the status of the interarrival interval at time \(t\): \(J(t) = i\) if the interarrival interval is exponentially distributed with rate \(\lambda_i\), \(i = 0, 1\).

Note that the above stochastic process is a Markov process. We assume that the ergodicity condition (2.3) is satisfied. Consider the steady-state distribution
\[ F_i(x) := \lim_{t \to \infty} \text{P}\{V(t) < x, J(t) = i\}, \quad x \geq 0, \ i = 0, 1. \quad (3.1) \]

Using level crossing theory [7], or using the integro-differential method of Táckcs [14] (cf. also [6], Section II.4.5), we obtain for \(x > 0\):
\[ \frac{dF_0(x)}{dx} = \lambda_0 F_0(x) - \lambda_0 \int_0^x \int_0^{x-y} (1 - T(b)) dB(b) dF_0(y) - \lambda_1 \int_0^x \int_0^{x-y} (1 - T(b)) dB(b) dF_1(y), \quad (3.2) \]
\[ \frac{dF_1(x)}{dx} = \lambda_1 F_1(x) - \lambda_0 \int_0^x \int_0^{x-y} (1 - B(z)) dT(z) dF_0(y) - \lambda_1 \int_0^x \int_0^{x-y} (1 - B(z)) dT(z) dF_1(y). \quad (3.3) \]

Let
\[ \phi_i(s) := \int_0^\infty e^{-sx} dF_i(x), \quad \text{Re} \ s \geq 0, \ i = 0, 1. \quad (3.4) \]
It follows from (3.2) and (3.3) that, for $\Re s \geq 0$ (note that we assume that $P(B > 0) = P(T > 0) = 1$; otherwise a minor change is required),

$$
\phi_0(s) - F_0(0+)= \lambda_0 \frac{\phi_0(s)}{s} - \lambda_0 \frac{\phi_0(s)}{s} \chi(s) - \lambda_1 \frac{\phi_1(s)}{s} \chi(s),
$$

$$
\phi_1(s) - F_1(0+) = \lambda_1 \frac{\phi_1(s)}{s} - \lambda_0 \frac{\phi_0(s)}{s} \psi(s) - \lambda_1 \frac{\phi_1(s)}{s} \psi(s).
$$

Eliminating $\phi_1(s)$ from these two equations, it follows that

$$
\phi_0(s)[s - \lambda_0 + \lambda_0 \chi(s)] = sF_0(0+) - \lambda_1 \chi(s)sF_1(0+) - \lambda_0 \psi(s)\phi_0(s)
$$

$$
= \frac{sF_0(0+) - \lambda_1 \chi(s)sF_1(0+)}{s - \lambda_1 + \lambda_1 \psi(s)}, \quad \text{(3.5)}
$$

or, for $\Re s \geq 0$:

$$
\phi_0(s)[s - \lambda_0 + \lambda_0 \chi(s) - \lambda_0 \lambda_1 \frac{\chi(s)\psi(s)}{s - \lambda_1 + \lambda_1 \psi(s)}] = sF_0(0+) - \frac{\lambda_1 \chi(s)sF_1(0+)}{s - \lambda_1 + \lambda_1 \psi(s)}.
$$

Similarly, for $\Re s \geq 0$:

$$
\phi_1(s)[s - \lambda_1 + \lambda_1 \psi(s) - \lambda_0 \lambda_1 \frac{\chi(s)\psi(s)}{s - \lambda_0 + \lambda_0 \chi(s)}] = sF_1(0+) - \frac{\lambda_0 \psi(s)sF_0(0+)}{s - \lambda_0 + \lambda_0 \chi(s)}.
$$

After some calculations, in which $s$ is factored out in numerator and denominator, we rewrite (3.6) and (3.7) into: For $\Re s \geq 0$,

$$
\phi_0(s) = \frac{(s - \lambda_1 + \lambda_1 \psi(s))F_0(0+) - \lambda_1 \chi(s)F_1(0+)}{s - \lambda_0 - \lambda_0 \chi(s) + \lambda_1 \psi(s) + \lambda_0 \lambda_1 \frac{1 - \chi(s) - \psi(s)}{s}}, \quad \text{(3.8)}
$$

$$
\phi_1(s) = \frac{(s - \lambda_0 + \lambda_0 \chi(s))F_1(0+) - \lambda_0 \psi(s)F_0(0+)}{s - \lambda_0 - \lambda_1 + \lambda_0 \chi(s) + \lambda_1 \psi(s) + \lambda_0 \lambda_1 \frac{1 - \chi(s) - \psi(s)}{s}}. \quad \text{(3.9)}
$$

Let us now determine the constants $F_0(0+)$ and $F_1(0+)$. Obviously, we have the normalizing equation

$$
F_0(\infty) + F_1(\infty) = 1, \quad \text{(3.10)}
$$

6
i.e.,
\[ \phi_0(0) + \phi_1(0) = 1. \] (3.11)
Substitution of \( s = 0 \) in (3.8) and (3.9) yields, after a straightforward calculation:
\[ F_0(0+) + F_1(0+) = \frac{\lambda_0 \psi(0) + \lambda_1 \chi(0) + \lambda_0 \lambda_1 [\chi'(0) + \psi'(0)]}{\lambda_0 \psi(0) + \lambda_1 \chi(0)}. \] (3.12)

**Remark 3.1.** Note that \( F_0(0+) + F_1(0+) \) is positive iff the ergodicity condition (2.3) holds. In fact, dividing both numerator and denominator of the righthand side of (3.12) by \( \lambda_0 \lambda_1 \) shows that
\[ F_0(0+) + F_1(0+) = 1 - \mathbb{E}[\min(B,T)]/EA. \]

A second equation for \( F_0(0+) \) and \( F_1(0+) \) is obtained by observing that the denominator of the righthand side of (3.8) (which coincides with the denominator of the righthand side of (3.9)) has exactly one zero in \( \text{Re} \ s > 0 \) (we outline the proof in Remark 3.2 below). Call this zero \( \sigma \). Since the LST’s \( \phi_0(s) \) and \( \phi_1(s) \) are analytic functions for \( \text{Re} \ s > 0 \), the numerators of the righthand sides of (3.8) and (3.9) must also be zero for \( s = \sigma \). In both cases, this yields the same relation between \( F_0(0+) \) and \( F_1(0+) \) (the equality of these two relations is most easily seen by observing that the lefthand side of (3.6), and of (3.7), is zero for \( s = \sigma \)):

\[ F_0(0+) = \frac{\sigma - \lambda_0 + \lambda_0 \chi(\sigma)}{\lambda_0 \psi(\sigma)} F_1(0+) = \frac{\lambda_1 \chi(\sigma)}{\sigma - \lambda_1 + \lambda_1 \psi(\sigma)} F_1(0+). \] (3.13)

This completes the determination of \( \phi_i(s), i = 0, 1. \)

**Remark 3.2.** The fact that the denominator of the righthand side of (3.8), to be called \( h(s) \), has exactly one zero in \( \text{Re} \ s > 0 \) can be shown by application of Rouché’s theorem to \( h(s) \). Write \( h(s) = h_1(s) + h_2(s) \), with \( h_1(s) := s - \lambda_0 - \lambda_1 \) and \( h_2(s) := \lambda_0 \chi(s) + \lambda_1 \psi(s) + \lambda_0 \lambda_1 \frac{1-\chi(s)-\psi(s)}{s} \). It is useful to observe that
\[ \frac{1-\chi(s)-\psi(s)}{s} \] is the LST of the residual service time, where service time is \( \min(B,T) \). Take \( R \) to be a closed contour, consisting of the imaginary axis from \(-ir\) to \(+ir\) and a semi-circle in the right halfplane with radius \( r \) and origin \( O \); we’ll let \( r \to \infty \). We observe that \( h_1(s) \) and \( h_2(s) \) are analytic inside \( R \), and that \( h_1(s) \) has exactly one zero inside \( R \) for \( r \) large enough.
On the boundary, \(|h_1(s)| > |h_2(s)|\). This is obviously true on the semi-circle; on the imaginary axis, one has \(|h_1(s)| \geq \lambda_0 + \lambda_1\) and

\[
|h_2(s)| \leq |\lambda_0 \chi(0)| + |\lambda_1 \psi(0)| + \lambda_0 \lambda_1 \mathbb{E}[\min(B, T)] < \lambda_0 \chi(0) + \lambda_1 \psi(0) + (\lambda_1 \chi(0) + \lambda_0 \psi(0)) = \lambda_0 + \lambda_1,
\]

the last inequality following from the ergodicity condition (2.3). Rouche's theorem now implies that \(h(s)\) has for \(\text{Re } s > 0\) just as many zeros as \(h_1(s)\), viz., one zero. Note that, on the imaginary axis, \(s = 0\) is a removable singularity.

The unique zero \(\sigma\) is real and lies between \(\lambda_0\) and \(\lambda_1\). Indeed, substitution of \(s = \lambda_0\) and \(s = \lambda_1\) in \(h(s)\) immediately shows that, since \(h(\lambda_0) = (\lambda_0 - \lambda_1)\chi(\lambda_0)\) and \(h(\lambda_1) = (\lambda_1 - \lambda_0)\psi(\lambda_1)\):

\[
\min(\lambda_0, \lambda_1) \leq \sigma \leq \max(\lambda_0, \lambda_1).
\]

**Remark 3.3.** If the threshold is infinite, then \(\psi(s) \equiv 0\) and \(\chi(s) \equiv \beta(s)\). It is not hard to check, using (3.9), that then \(F_1(0+) = 0\) (e.g., by substituting \(s = \sigma\)). So \(\phi_1(s) = 0\), and \(\phi_0(s)\) reduces to the Pollaczek-Khintchine expression \(s F_0(0+)/\left(s - \lambda_0 + \lambda_0 \beta(s)\right)\). Hence the system now behaves like an \(M/G/1\) queue with arrival rate \(\lambda_0\) and service time distribution \(B(\cdot)\) — as it should.

Summation of the two expressions (3.8) and (3.9) for \(\phi_0(s)\) and \(\phi_1(s)\) gives the LST of the distribution of the steady-state workload \(V\). We present this result, plus an expression for the mean workload, in the next theorem. Remember that \(h(s)\) is the denominator of (3.8) and (3.9).

**Theorem 3.1.** For \(\text{Re } s > 0\),

\[
E[e^{-sV}] = \frac{\left[s - \lambda_1 + (\lambda_1 - \lambda_0)\psi(0)\right]F_0(0+) + \left[s - \lambda_0 + (\lambda_0 - \lambda_1)\chi(0)\right]F_1(0+)}{s - \lambda_0 - \lambda_1 + \lambda_0 \chi(s) + \lambda_1 \psi(s) + \lambda_0 \lambda_1 \frac{1 - \chi(s) - \psi(s)}{s}};
\]

\[
E[V] = -\frac{\left[1 + (\lambda_1 - \lambda_0)\psi'(0)\right]F_0(0+) + \left[1 + (\lambda_0 - \lambda_1)\chi'(0)\right]F_1(0+)}{h'(0)} + \frac{h'(0)}{h(0)}.
\]

**Remark 3.4.** For \(\lambda_0 = \lambda_1\), it is easily checked that (3.14) reduces to the LST of the steady-state workload distribution in the \(M/G/1\) queue with arrival rate \(\lambda_0 = \lambda_1\) and service time LST \(\chi(s) + \psi(s)\), which is the LST of
\[ \min(B, T). \]

Note that one can easily express \( E[V] \) into the model parameters. For example,

\[
h(0) = -\lambda_0 - \lambda_1 + \lambda_0 \chi(0) + \lambda_1 \psi(0) + \lambda_0 \lambda_1 E[\min(B, T)]
= \lambda_0 \lambda_1[E[\min(B, T)] - EA]. \tag{3.16}
\]

**Remark 3.5.** As mentioned in the Introduction, the workload process of the queueing model and the content process of the production/inventory fluid model have the same conditional steady-state law, given that the processes are positive. It is also easy to see that both processes are regenerative processes. This enables one to express the steady-state law of each process in terms of the steady-state law of the other process. More specifically, let \( F_W(\cdot) \) and \( F_C(\cdot) \) denote the steady-state distributions of the workload process and the content process, respectively. Then

\[
F_W(x) = \pi_W + \int_0^x f_W(y)dy, \quad F_C(x) = \pi_C + \int_0^x f_C(y)dy, \tag{3.17}
\]

where \( \pi_W \) and \( \pi_C \) are the respective atoms at 0 of the workload and the content process, and \( f_W(\cdot) \) and \( f_C(\cdot) \) are the respective absolutely continuous densities. The fact that the conditional steady-state laws are the same simply says that for all \( x > 0 \):

\[
\frac{f_W(x)}{1 - \pi_W} = \frac{f_C(x)}{1 - \pi_C}. \tag{3.18}
\]

Since both processes are regenerative, we have:

\[
\pi_W = \frac{E[\text{idle period}]}{E[\text{idle period}] + E[\text{busy period}]},
\]

\[
\pi_C = \frac{E[\text{silence period}]}{E[\text{silence period}] + E[\text{activity period}]},
\]

where by 'idle period' and 'busy period' we mean that the queueing system is empty and not empty, respectively. Similarly, the 'silence period' and the 'activity period' are the time periods in which the production/inventory system is empty and not empty, respectively.

By the construction of the workload process from the content process,

\[
E[\text{idle period}] = E[\text{silence period}],
\]

9
and (remember that $\alpha$ is the net inflow rate during machine ON times)

$$(1 + \alpha)E[\text{busy period}] = E[\text{activity period}],$$

so that

$$f_C(x) = f_W(x)(1 + \alpha) \frac{E[\text{idle period}] + E[\text{busy period}]}{E[\text{idle period}] + (1 + \alpha)E[\text{busy period}]}.$$ (3.19)

4 The waiting time

Let $W_n$ denote the waiting time of the $n$th arriving customer, $n = 1, 2, \ldots$. In the present section we determine the steady-state waiting time distribution, by using a Wiener-Hopf approach. This is a classical approach for the $G/G/1$ queue, cf. Lindley [10]; see also Section II.6.3 of [6]. A nice feature of the model under consideration is, that the Wiener-Hopf decomposition can be worked out in detail here, leading to quite explicit results.

Starting-point is the following recurrence relation (below, $[x]^+$ denotes max$(0, x)$ and $[x]^-$ denotes min$(0, x)$):

$$W_{n+1} = \begin{cases} [W_n + B_n - A_{n+1}^{(0)}]^+ & \text{if } B_n < T_n, \\ [W_n + T_n - A_{n+1}^{(1)}]^+ & \text{if } B_n \geq T_n. \end{cases}$$ (4.1)

Here $A_{n+1}^{(i)}$ denotes an interarrival interval that is exponentially distributed with rate $\lambda_i$, $i = 0, 1$. Taking LST’s and using the identity

$$e^{-s[x]^+} + e^{-s[x]^-} = 1 + e^{-sx},$$

we obtain for Re $s = 0$:

$$E[e^{-sW_{n+1}}] = 1 - E[e^{-s(W_n + B_n - A_{n+1}^{(0)})^-}(B_n < T_n)] \\ - E[e^{-s(W_n + T_n - A_{n+1}^{(1)})^-}(B_n \geq T_n)] + E[e^{-s(W_n + B_n - A_{n+1}^{(0)})(B_n < T_n)}] + E[e^{-s(W_n + T_n - A_{n+1}^{(1)})(B_n \geq T_n)}].$$ (4.2)

Now we assume that the ergodicity condition (2.3) holds, and we restrict ourselves to the steady-state waiting time distribution. $W$ shall denote a
random variable with this steady-state distribution. After a brief calculation, Formula (4.2) leads to the following identity: For \( \Re s = 0 \),

\[
E[e^{-sW}] = \zeta^-(s) + E[e^{-sW}] \frac{\lambda_0}{\lambda_0 - s} \chi(s) + E[e^{-sW}] \frac{\lambda_1}{\lambda_1 - s} \psi(s),
\]  

(4.3)

where

\[
\zeta^-(s) := 1 - E[e^{-s[W+B-A(\theta)]}(B < T)] - E[e^{-s[W+T-A(1)]}(B \geq T)].
\]

Note that \( \zeta^-(s) \) is analytic in \( \Re s < 0 \).

Remembering the definition of \( h(s) \) in Remark 3.2 – note that \( h(s) \) is the denominator of the righthand side of both (3.8) and (3.9) – we can rewrite (4.3) into:

\[
h(s)E[e^{-sW}] = \frac{(s - \lambda_0)(s - \lambda_1)}{s} \zeta^-(s), \quad \Re s = 0.
\]  

(4.4)

We now have the appropriate formulation for a Wiener-Hopf boundary value problem. The lefthand side of (4.4) is bounded and analytic in \( \Re s > 0 \), and the righthand side of (4.4) is bounded and analytic in \( \Re s < 0 \), and both sides are equal on the boundary \( \Re s = 0 \). Note that \( s = 0 \) is a removable singularity of the righthand side. In view of the linear behaviour in \( s \) at infinity, Liouville’s theorem implies that the lefthand side should equal a first-order polynomial, say \( as + b \), for \( \Re s \geq 0 \). In fact the same holds for the righthand side in \( \Re s \leq 0 \), but we are not interested in determining \( \zeta^-(s) \). Remembering that \( s = \sigma \) is the only zero of \( h(s) \) in \( \Re s > 0 \), cf. Remark 3.2, it follows that \( b = -a\sigma \). Substitution of \( s = 0 \) yields that

\[
h(0).1 = -a\sigma,
\]

so (see (3.16))

\[
a = \frac{\lambda_0\lambda_1}{\sigma}(EA - E[\min(B,T)]).
\]  

(4.5)

Finally we obtain the following expression for the LST of the steady-state waiting time distribution:

**Theorem 4.1.** For \( \Re s \geq 0 \),

\[
E[e^{-sW}] = \frac{\frac{\lambda_0\lambda_1}{\sigma}(EA - E[\min(B,T)])(s - \sigma)}{s - \lambda_0 - \lambda_1 + \lambda_0\chi(s) + \lambda_1\psi(s) + \lambda_0\lambda_1 \frac{1 - \chi(s) - \psi(s)}{s}}.
\]  

(4.6)
Remark 4.1. Note that the steady-state distributions of $V$ and $W$ differ; although the arrivals occur at exponentially distributed intervals, PASTA does not hold.

Remark 4.2. The LST's of $V$ and $W$ appear to be relatively simple functions of the LST's $\chi(s)$ and $\psi(s)$. The latter functions are easily expressed in the LST of $T$ when service requests are exponentially distributed, and in the LST of $B$ when thresholds are exponentially distributed. In the former case,

$$\chi(s) = \frac{1 - \tau(s + 1/\beta)}{1 + \beta s}, \quad \psi(s) = \tau(s + 1/\beta), \quad \text{Re } s \geq 0,$$

with $\tau(\cdot)$ the LST of the threshold distribution; in the latter case,

$$\chi(s) = \beta(s + 1/\tau), \quad \psi(s) = \frac{1 - \beta(s + 1/\tau)}{1 + \tau s}, \quad \text{Re } s \geq 0,$$

with $\beta(\cdot)$ the LST of the service request distribution.

5 Conclusions and suggestions for further research

In this paper we have presented a detailed analysis of the workload and waiting time process of a queueing model with dependence between a service request and the subsequent interarrival time. We have also established a link between this model and a certain production/inventory model, that provided the initial motivation for the present study.

We have taken exponentially distributed interarrival intervals, with rate depending on the previous service request. It should be possible to extend the analysis of Sections 3 and 4 to the case of interarrival intervals with distributions that have a rational LST; cf. the analysis of the $K_m/G/1$ queue in Section II.5.11 of [6]. For example, in (4.3) the terms $\lambda_i/(\lambda_i - s)$ then have
to be replaced by more complicated quotients of polynomials, after which all the zeros of the resulting new function \( h(s) \) in \( \text{Re } s > 0 \) must be determined.

The results of the present study might be used for optimization purposes. In the production/inventory version of the model, e.g., the goal could be to choose the production rate \( 1 + \alpha \) such that some cost function is minimized. E.g., with respect to the choice of \( \alpha \) there should be a trade-off between holding costs (which are linear in the mean buffer content and then increasing in \( \alpha \)) and unsatisfied demand costs (which are linear in the probability \( \pi_C \) of having an empty buffer, and then decreasing in \( \alpha \)).

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References


