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A Framework for Component Based Software Architectures

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Abstract. A framework to design component based software architectures is presented. The framework incorporates concepts from workflow management and object orientation. The notation for defining architectures is based on the Unified Modelling Language. For semantics we use coloured Petri nets with time.

Keywords: UML, Petri nets, software architecture, workflow nets, object-orientation, components

1 Introduction

In systems modelling there is a tendency to describe the essence of systems at higher levels of abstraction. The architecture of a system is such a high-level model. There are many modelling languages to describe systems at a high level of abstraction. These languages consist of a number of diagram techniques to describe a variety of views of a system. An example of such a language is the Unified Modelling Language [3]. A drawback of UML is that the views are not integrated. Therefore, UML does not guarantee that the views are consistent.

A way to prevent these problems is to use an executable model. If a model is executable, a computer can simulate the behaviour of the system; it is unambiguous and complete in the sense that all details to compute the behaviour of the system are defined. Executability of a model does not imply that it is a good description of the real system, however, the behaviour of the modelled system can be compared to the behaviour of the real system by running the executable model. It is an advantage if a language for executable models is based on a formal model, because then the semantics are well-defined and formal verification methods can be developed. There are several well-known modelling tools based on coloured Petri nets, for instance: ExSpect and Design CPN [4], [5]. These tools have no particular domain of application: they can be used to model all discrete dynamic systems. A consequence
of this is that they have no efficient notations for component based architectures that accommodate reuse of components.

In this article we introduce a modelling language to fill this gap. It is based on the formalism underlying ExSpect (see [4]). First, we illustrate how a model in a modelling language, in a formal framework and a programming language are related. In Figure 1 the ellipses have different size, indicating the efficiency of notation. A model expressed in a programming language is larger than in a formal framework and the most efficient one, is the representation in the modelling language.

![Figure 1. A model expressed in three languages](image)

If we use a modelling language based on a formal framework, the steps to good software are relatively small. The first step, (1) in Figure 1, is straightforward since all concepts of the modelling language are defined in terms of the primitives of the formal framework. If the formal model is executable, the difference with the model in the programming language seems to be small. However there are two important differences:

- user friendliness, which is often only an issue for the operational system;
- performance (e.g. response times, reliability, and storage capacity) is important only for the operational system.

In fact an executable model is mainly focussed on the logical functionality of a system.

Component-based software development (CBSD) focuses on constructing software systems by integrating existing software components with new domain specific software components [7]. Reuse and a better overall structure help to reduce development time and therefore to recover costs and to improve time to profit. Flexibility and maintainability can be improved since components can be updated, upgraded or replaced by new components. CBSD is a young field and a number of obstacles have to be removed. To find and select a component that meets the developers needs is a big issue, since the component-market has not yet accomplished its full size. The observable behaviour of a component (message types and interface protocols) should be unambiguously defined. Also, an engineer has to rely on a component; from its description it should be possible to check the component's reliability. Finally, an engineer needs to test a component to see whether it meets its requirements and to see if it's possible to integrate it in a system of components.

Already there is a number of modelling languages that have facilities for component-based software architectures [3]. However these languages lack a formal
base. In terms of Figure 1 this implies that the formal model is missing. Therefore, analysis and simulation are not possible. In our framework for component based software architectures we provide concepts for executable system architectures in which:
- components and their interactions with an environment are formally defined;
- the observable behaviour of components can be described and validated by simulation;
- components can be easily added, removed and replaced by other components.

The component framework we propose is based on coloured Petri nets with time [4, 5]. Timed coloured Petri nets have proven to be eligible for building compact models of complex systems. They have a formal semantics, a graphical notation, high expressiveness and there are many analysis techniques and software tools available. So, it is “proven technology” and is therefore a good start for a modelling language for CBSD. Petri nets are also applied to model workflow management systems, as described in [1]. This resulted in workflow nets (WF-nets).

In our framework, we will use WF-nets because they provide an excellent formalism to describe the dynamics of components, often referred to as transactions, protocols or object life cycles. We will also use the concept of object orientation [3] to describe data aspects of a system and to obtain a structure that integrates encapsulation, polymorphism and inheritance. Moreover, object oriented concepts are a pre-requisite for component technology; it gives the system the structure it requires to be “componentised”.

2 Components as Petri Nets

Since Petri nets play an important role in defining the semantics of our notation, we summarise some elementary properties of Petri nets. For more details see [4], [5] and [6].

A Petri net is a bipartite graph with two kinds of nodes: transitions (represented as rectangles) and places (represented as circles). Petri nets can be defined in various ways. We define Petri nets such that we can use similar notation to define components. We start with an example. See Figure 2.

\[\text{Figure 2. A Petri net with places and a transition.}\]

In Figure 2 we have a set of places \(P = \{a, b\}\) and a set of a single transition \(T = \{t\}\). For transition \(t\) we describe the incoming arc \(x\) by a function \(I\) that operates on \(t\), hence \(I(t) = \{x\}\). Similarly, for the outgoing arc we have a function \(O(t) = \{y\}\). We call incoming arcs input connectors and outgoing arcs output connectors of \(t\). All connectors are labelled with labels from a fixed, infinite set of labels \(L\). Each transition has one or more connectors, all labelled with a different element of \(L\).
However, two transitions may use the same connector labels. Note that the connectors x and y are attached to places. Places that are attached to input connectors are input places of a transition, likewise, output places are attached to output connectors. The function that matches (or glues) connectors to places is the function $M$. The function $M$ operates on connectors for each transition separately, hence $M(t, \bullet)$ operates on the connectors of $t$. In Figure 2 we have $M(t, x) = a$ and $M(t, y) = b$.

**Definition 1. (Classical Petri net)** A classical Petri net is a five tuple $(P, T, I, O, M)$ where

(i) $P$ is a finite set of places,
(ii) $T$ a finite set of transitions,
(iii) $I$ a function that assigns a set of input connectors to a transition,
(iv) $O$ a function that assigns a set of output connectors to a transition and
(v) $M : T \times L \rightarrow P$ a match-function that ‘glues’ for each transition the in- and output connectors of the transition to places; $M$ is a partial function that is only defined for connectors of transitions,

such that

- $P$ and $T$ are disjoint,
- for all transitions $t$ the match function $M(t, \bullet)$ is defined for all connectors of $t$,
- $\forall t \in T : \forall x \in I(t) \cup O(t) : M(t, x) \in P$,
- $\forall t \in T : I(t) \cap O(t) = \emptyset$.
- each transition has at least one input connector.

In the places of a Petri net tokens may reside. The configuration of all tokens in a net is called the state of the net. If all input places of a transition have at least one token, the transition may fire, which means that the transition consumes from all its input places one token and that it produces for all its output places one token. (In fact it is a little more complicated: for each input connector a token is consumed and for each output connector one is produced and two or more connectors may be connected to the same place.) The firing of a transition determines a state-transition of the net. Given an initial state and a (finite or infinite) sequence of firings, we obtain a trace of the behaviour of the net.

In classical Petri nets, tokens are valueless and therefore transitions do not have logic. In coloured nets tokens have a value (traditionally called a “colour”) and therefore transitions have “logic” to determine the values of the produced tokens as a function of the values of the consumed tokens. They also have “logic” to determine which tokens may be consumed and which tokens may not be consumed by a transition. This is called a pre-condition. It is a Boolean function on the input tokens. If the function value is “true”, the transition may fire. Another feature is that in some output places no token need to be produced. In timed nets all tokens have a timestamp that is interpreted as the earliest moment the token might be consumed. The timestamp is computed in the transition that produces the token.

Apart from a classical Petri net, we will also use the notion of an open Petri net. An open Petri net is a classical Petri net in which at least one of the connectors is not attached to a place. An example of an open Petri net is shown in Figure 3.
Figure 3. An open Petri net.

Note that the match function $M$ is not defined for all connectors of an open Petri net. In Figure 3 $M$ is not defined for the $(s,a)$, $(t,b)$ and $(t,g)$.

In [4] components as Petri nets were first introduced, although in another context (transitions are called processors and components are called actors). A transition is the smallest component. The connectors form the interface of the component with its environment. If a component is placed in an environment then the connectors are hooked onto places in the environment. (Two or more connectors may be hooked onto the same place.) In fact we use hierarchical Petri nets (see [4]), which means that a transition may be refined by a component that has the same connectors as the transition. Figure 4 illustrates these concepts.

Figure 4. Components as Petri nets.

In addition to a Petri net, a component has a name, a set of input connectors $C_i$, and a set of output connectors $C_o$. In Figure 4 not only example is a component, but also the transitions $s$ and $t$ are components. Table 1 gives a table format of these components.
After this informal introduction of a component we will now present the definition we will use in this article.

**Definition 2. (Component)** A component is an 8-tuple 
(name, \(C_\text{in} \cup C_\text{out} \cup P \cup T \cup I \cup O \cup M\)) where

(i) name is the unique name of a component,
(ii) \(C_\text{in}\) is a non-empty set of external input connectors of the component,
(iii) \(C_\text{out}\) is a non-empty set of external output connectors of the component,
(iv) \(P, T, I,\) and \(O\) are as in a classical Petri net (Definition 1), and
(v) \(M : T \times L \rightarrow P \cup C_\text{in} \cup C_\text{out}\) a match-function that 'glues' for each transition the in- and output connectors of the transition to places or to the connectors of the component. \(M\) is a partial function, only defined for the connectors of the transitions of the component,

such that

- \(\forall t \in T: \forall x \in I(t) : M((t,x)) \in (P \cup C_\text{in})\), i.e., each input connector of a transition is glued to either a place or an external connector,
- \(\forall t \in T: \forall x \in O(t) : M((t,x)) \in (P \cup C_\text{in})\), i.e., the same holds for an output connector,
- \(\forall a \in C_\text{in} : \exists t \in T : \exists b \in I(t) : M((t,b)) = a\), i.e., input connectors of components are always internally connected to input connectors of transitions,
- \(\forall a \in C_\text{out} : \exists t \in T : \exists b \in O(t) : M((t,b)) = a\), i.e., output connectors of components are always internally connected to output connectors of transitions.

Transitions from the set \(T\) may be internally decomposed as components (see Figure 4). In fact a real transition is the atomic component. For a decomposable transition \(t\)
we have that $C_n := I(t)$ and $C_m := O(t)$, and we call it an internal component, i.e., a component in a component. In this sense Definition 2 is recursive. If all internal components are atomic, i.e., transitions, and if the sets $C_n$ and $C_m$ are empty, then we have a Petri net as in Definition 1. (For a precise treatment of the transformation of hierarchical nets into classical nets we refer to [4].)

3 Structured Components

We will define structured components that can be used to describe systems architecture in a structured way. Structured components are defined recursively. A structured component is a memory component, a flow component or a complex of structured components. The smallest structured component is the transition. It can either be a memory or a flow component.

Figure 5 shows the relation between component classes.

![Figure 5. Classes of components.](image)

To introduce structured components, we will use an example of a client-server application. Initially, a server-process is started, then client-processes follow. To start a client process, a user has to login by entering its name and password. The server validates the data and replies the privileges of the user. Messages, triggered by users, can be exchanged between client and server. To terminate client processes users logout. The server process finishes when all the clients are logged off and it receives an instruction to switch off.

3.1 Memory Component

Memory components are used to store and update persistent data and to perform calculations. Figure 6 shows the user memory component of the example.

![Figure 6. The memory component: user.](image)
This component, stores and updates data of all registered system users in the place UserStore. This place is special in the sense that it always contains precisely one token and that it is always connected to exactly one input and one output connector for each transition to which it is connected. Places of this type are called stores. The transitions Login and Logout perform updates on the value of the token in the place UserStore. (Note that transitions to initialise UserStore are omitted in this example.)

The connectors \( m_\text{in} \) and \( m_\text{out} \) are both internally connected to the connectors of Login (\( m_\text{in1} \) and \( m_\text{out1} \)) and Logout (\( m_\text{in2} \) and \( m_\text{out2} \)). Stores are connected to transitions with one two-headed-arrow. This arrow has the same meaning as two one-headed-arrows. A cross marks store places.

In general, we have the following structure for a memory component.

**Definition 3. (Memory component)** A memory component \( MC \) is a component (Def. 2) \((\text{name, } C_\text{in}, C_\text{out}, P, T, I, O, M)\) such that

- \( C_\text{in} \) and \( C_\text{out} \) are singletons,
- \( \forall t \in T : \exists ! x \in I(t) : M(t,x) \in C_\text{in} \) and \( \forall t \in T : \exists ! x \in O(t) : M(t,x) \in C_\text{out} \), i.e., each transition is connected to the input-connector and the output connector of the component,
- \( \forall p \in P : \exists t \in T : \exists x \in I(t) : M(t,x) = p \), i.e., all places in a memory component are connected to, at least, one transition,
- \( \forall p \in P, \forall t \in T : (\exists x \in I(t) : M(t,x) = p) \Leftrightarrow (\exists y \in O(t) : M(t,y) = p) \), i.e., all places in a memory component are stores.

The memory component shown in Figure 6 has a simple structure. Definition 1 allows more complex structures, for instance components with transitions that are connected to multiple stores. In Figure 7 we extend the User memory component with an extra store and an extra transition.

**Figure 7.** MC – DepartmentUser

In the UserStore each user has a reference to a department. The transition Department-users is able to give the total number of users that are part of a specific
Note that the interface (\$m\textunderscore in\$ and \$m\textunderscore out\$) of the component is not
changed.

3.2 Flow Component

Flow components are elementary components that are used to describe dynamic
behaviour. We call this the process, but sometimes it is called transaction, life cycle or
protocol. A process can reflect the business process (or workflow [1]) the component
supports, or transactions according to use cases [3]. Properties of flow components
are a complex life cycle allowing parallel processing, a complex communication
protocol with their environment, and non-persistency. The latter means that a flow
component does not store data; it has no stores and if the process has reached its end-
state then there is no process-data left in the component. This is called the soundness
property [1]. There are necessary and sufficient conditions for a net to be sound but
these are not so easy to verify. Therefore we restrict ourselves to WF-nets that are
sound by construction, which means that no verification is required.

Figure 8 depicts the flow component ServerFlow from the example.

![Figure 8. Flow component: ServerFlow.](image)

Note that in Figure 8 the names of internal connectors that are glued to external
connectors are the same. In the example we choose to give the connectors that are
used to pass messages between components "\$m\$" in their labels. Except for the
connectors start and stop, these are used to initiate the process and to report that the
process has stopped. If we compare flow components to memory components we
find, apart from a more complex structure and the absence of stores, that the number
of external connectors is not restricted to two.
A flow component is defined by a construction method. From a simple net, it is constructed by fitting in a number of times a 'sound' building block according to a certain rule that guarantees the correctness of the construction step. Using this method we obtain the desired flow component. In fact the 'rule' is a substitution function that substitutes in a net a building block for a transition, which results in a new net. We will now subsequently define the start net, the building blocks, the substitution function and the flow component.

The latter will be introduced in two steps, first an isolated flow component and then the flow component itself. An isolated component is a component without external connectors ($C_u = \emptyset$ and $C_m = \emptyset$).

**Definition 4. (The start net)** The start-net $s_0$ is a net with only one transition. Figure 9 depicts this net.

![Figure 9. The start-net.](image)

The essence of a process is to define the routing control. In a flow component we want to support a sequence, a split (i.e., the flow is split into parallel sub-flows), a join (i.e., to synchronise sub-flows), a choice, a repetition of a part of the flow and a construction used to execute an arbitrary number of sub-flows. For each of these routing controls we define a building block. $B$ is the set of all building blocks.

**Definition 5. (Building blocks)** $B_s$ is the sequence block. It is defined by Figure 10. Sequence blocks are used when a transition $t_o$ (i.e., $t$-out) may not start before transition $t_i$ ($t$-in) is completed.

![Figure 10. The sequence-block.](image)

$B_p$ is the parallelism block. It is defined by Figure 11. This block is used when multiple transitions (sub-flows) need to be executed in parallel or if the order of transitions (sub-flows) is not important. After transition $t_i$ the process is split-up in parallel sub-processes. At the end $t_o$ synchronises the parallel threads.

![Figure 11. The parallelism-block.](image)
B_i is the choice block, defined in Figure 12. It makes a choice between two or more transitions. Choices typically depend on token values or on incoming communication (triggers).

*Figure 12. The choice-block.*

B_j is the iteration block, defined in Figure 13. It is used to repeat a specific transition (or a number of transitions) a number of times until a specific condition becomes false (or some other event occurs).

*Figure 13. The iteration-block.*

Finally, we define block B_k: the repeater block. It starts an arbitrary number of similar transitions or sub-flows simultaneously. A classical example where this kind of construction is applied is in handling an order for a customer (flow) in which several order-lines (sub-flows) have to be processed. The repeater block is defined in Figure 14.

*Figure 14. The repeater-block.*

The repeater block requires explanation. It is a net in which the transition t_1 fires initially. Thereafter, a token in place p_1 may be consumed by transition t_1 or transition t_2. Which of these transitions consumes the token depends on the token value or on tokens that are send to t_1 or t_2 by communication connectors of t_1 and t_2. These connectors are not visible in Figure 14. Suppose t_2 fires. The token of p_1 is immediately placed back in p_1. In p_3 and p_4 also tokens are produced. P_4 is the input place of transition t_4, which can be extended to a sub-flow. Now only t_2 and t_4 may fire. T_1 may not fire because the connection between t_1 and p_3 is an inhibitor arc; this
means that \( t_1 \) may only fire if \( p_3 \) is empty! Suppose \( t_4 \) fires, then \( t_3 \) is enabled. If \( t_3 \) fires then place \( p_3 \) is empty and \( t_1 \) and \( t_2 \) may subsequently fire to stop the flow. Note that as long as \( t_1 \) did not fire it is possible by \( t_2 \) to start new sub-flows. All sub-flows need to end before the main flow can end.

The grey transitions in the repeater block are transitions that may not be replaced (see Def. 6) by other building blocks, replacement of these transitions would violate correct behaviour of the repeater block.

Note that:
- building blocks have precisely one start and one stop transition, denoted by \( t_1 \) and \( t_2 \). (This notation will be used in the definition of the substitution function.)
- building blocks are defined for the case \( n=2 \) (two parallel paths, two choices, one way there and one way back in a repetition). The construction method allows that the blocks are more generally defined for an arbitrary number of parallel paths, choices and repetitions,
- the inhibitor is only introduced in the net by block \( B \).

We now use the previous definitions to introduce the substitution function. The substitution function operates on an isolated component, therefore \( C_\alpha = \emptyset \) and \( C_\alpha = \emptyset \). We omit them in the following definition.

**Definition 6. (Substitution function)** Let \((a, \mathcal{P}, \mathcal{T}, I, O, M)\) be an isolated component, and let \((b, \mathcal{T}', I', O', M') \in B \) and choose \( \tilde{t} \in \mathcal{T}_b \) (the set of replaceable transitions of the net \( a \)). We define the substitution function

\[
G(a, \tilde{t}, b) := (d, \mathcal{P}_d, \mathcal{T}_d, I_d, O_d, M_d),
\]

with
- name = \( d \),
- \( \mathcal{P}_d = \mathcal{P}_a \cup \mathcal{P}_b \), i.e., the set of places is the union of the set of places of component \( a \) and block \( b \),
- \( \mathcal{T}_d = (\mathcal{T}_a \setminus \{\tilde{t}\}) \cup \mathcal{T}_b \), i.e., the set of transitions is the union of the set of transitions of component \( a \) and block \( b \), but since \( t_1 \) and \( t_2 \) replace \( \tilde{t} \) we skip \( \tilde{t} \),

\[
\begin{align*}
I_d(t) &= I_a(t) & \text{for } t \in \mathcal{T}_a \setminus \{\tilde{t}\} \\
&= I_b(t) & \text{for } t \in \mathcal{T}_b \setminus \{t_1\} \\
&= I_b(\tilde{t}) & \text{for } t = t_2.
\end{align*}
\]

i.e., the input connectors remain attached to same transition except for the connectors of \( \tilde{t} \), these are re-defined for \( t_2 \),

\[
\begin{align*}
O_d(t) &= O_a(t) & \text{for } t \in \mathcal{T}_a \setminus \{\tilde{t}\} \\
&= O_b(t) & \text{for } t \in \mathcal{T}_b \setminus \{t_1\} \\
&= O_b(\tilde{t}) & \text{for } t = t_2.
\end{align*}
\]

i.e., \( O_d \) is defined in a similar way as \( I_a \).
- $M$, a match function defined by
  
  $M_{n}(t, x) = M_{n}(t, x)$ for $t \in T_{n} \setminus \{t\}$ and $x \in I_{n}(t) \cup O_{n}(t)$
  
  $M_{n}(t, x) = M_{n}(t, x)$ for $t \in T_{n} \setminus \{t, \bar{t}\}$ and $x \in I_{n}(t) \cup O_{n}(t)$
  
  $M_{n}(t, x) = M_{n}(t, x)$ for $t = \bar{t}$ and $x \in I_{n}(t)$
  
  $M_{n}(t, x) = M_{n}(t, x)$ for $t = t_{o}$ and $x \in O_{n}(t)$
  
  $M_{n}(t, x) = M_{n}(t, x)$ for $t = t_{o}$ and $x \in O_{n}(t)$

  note that for isolated components $M_{i} \in P_{i}$, i.e., all connectors are attached to places; in fact the match function remains the same in the sense that the connectors are still glued to the same places, the awkward expression arises because the domain of $M$ is re-defined.

Definition 7. (Isolated flow-component) An isolated flow-component $s$ is a component (Def. 2) for which there is a natural number $n$ and a sequence

$(s_{0}, t_{c}, b_{c}) \ldots (s_{n}, t_{c}, b_{c})$

where

- $s_{0}$ is the start component (Def. 4),

- for all $k = 0, \ldots, n-1$ component $s_{k+1}$ is defined by $s_{k+1} = G(s_{k}, \bar{t}_{k}, b_{k})$, where $\bar{t}_{k}$ is a replaceable transition in $s_{k}$ and $b_{k}$ a building block from the set $B$ (Def. 5), such that

  $s = s_{n}$

Definition 8. (Flow-component) A flow-component is a component for which the isolated part is an isolated flow component and for which there exists a connector start $\in C_{u}$ that is internally connected to the first transition and a connector stop $\in C_{o}$ that is internally connected to the last transition of the component. (In fact the labels for these connectors may be chosen freely $\in L$, but we will refer to them as $\text{start}$ and $\text{stop}$ connector.)

To illustrate the previous definitions we extend the start-net with the sequence block, thereafter we add four external connectors and their internal counterparts: start, stop, trigger_m and signal_m. We obtain the component shown in Figure 15.

Figure 15. Extend the start-net.

A more complicated example is the ServerFlow depicted in Figure 8. The building blocks that are used for this flow are, in order of substitution: Repeater, Choice, Iteration (2x) and Sequence. The external connectors and their internal counterparts were added afterwards.
Flow components are very close to WF-nets [1]. Differences are that:
- flow components are components, they are open nets and not Petri nets;
- only nets that can be constructed by a graph grammar (building blocks) are allowed, there are constructions that can not be made with the graph grammar but that do exist in WF-nets;
- the repeater is a construction that is not allowed in WF-nets, because of the inhibitor arc;
- flow components have connectors to support communication between the flow component and its environment.

3.3 Structured Component

A structured component may encapsulate other structured components according to certain rules. To the environment, this new structured component defines an interface and inside the component the nested components are glued together by adding places between them. Components from the outside may not communicate directly with the nested components, but need to use the interface.

Figure 16 shows the example of the structured component Server in which the memory component User and the flow component ServerFlow are nested.

![Figure 16. The structured component Server.](image)

The memory component User does not communicate with components outside the Server component, this is a task that is exclusive for flow components! In the example only ServerFlow communicates with the environment. All places in the structured component are used for communication between components.

Before we define structured components recursively, we introduce an important relationship between components: the *invoke*. The invoke-relation can only be defined for components with a start and a stop connector. We already defined the start and stop connector of flow components, for memory components their only connectors are the start and stop connector.

**Definition 9. (Invokes directly)** Let \( t_1 \) and \( t_2 \) be internal components of the component \( (\text{name}, C_{t_1}, C_{t_2}, P, T, I, O, M) \) and let start and stop be the start and stop connector of \( t_2 \).
tl invokes directly t2 ⇔ (∃ a1 ∈ O(t1): ∃ p1 ∈ P: M(t1, a1) = M(t2, start) = p1) ∧
(∃ a2 ∈ I(t1): ∃ p2 ∈ P: M(t1, a2) = M(t2, stop) = p2),

i.e., an output connector of tl is glued to the same place as an input connector of t2
and vice versa an input connector of tl is glued to the same place as an output
connector of t2.

Definition 10. (Invokes) Let tl and t2 be internal components.

- tl invokes t2 ⇔
  - tl invokes directly t2, OR
  - there exists an internal component t3 (tl "→ t3 "→ t2) such that tl invokes directly t3
    and t3 invokes t2.

In the example the component ServerFlow invokes the component User (Figure 16).

Definition 11. (Structured component) A structured component is a component that
is either a flow component or a memory component, or a component (name, C, C_m,
P, T, I, O, M) that is built of a set SF of parallel flow components and a set SC of
structured components, such that,
- T = SF \cup SC, SF \cap SC ≠ Ø and SF ≠ Ø,
- \forall c ∈ C_m: \exists t ∈ SF: \exists d ∈ I(t): M(t, d) = c, i.e., the external input connectors are
  internally glued to the input connectors of a flow component,
  - in particular \exists start ∈ C_m: \forall t ∈ SF: M(t, start) = start, i.e., the start
    connectors (start) of the flow components (t) are glued to the start
    connector (start) of the encapsulating component,
- \forall c ∈ C_m: \exists t ∈ SF: \exists d ∈ O(t): M(t, d) = c, i.e., idem for output,
  - in particular \exists stop ∈ C_m: \forall t ∈ SF: M(t, stop) = stop,
- \forall t ∈ SC:
  - \forall d ∈ I(t): \exists p ∈ P: M(t, d) = p,
  - \forall d ∈ O(t): \exists p ∈ P: M(t, d) = p, i.e., the connectors of nested
    components are attached to places,
- all components from SC are invoked by a flow component from SF.

Note that the invoke-relation is in fact a necessary condition for an invoke but not yet
sufficient. Also, the internal structure of a component and the token values determine
whether a component is really invoked.

3.4 Correctness of Structured Components

Not all structured components are sound by construction. Errors can be introduced in
communication protocols between components. A transaction is called correct if it
behaves like a sound workflow, i.e., it is always possible to end and when it ends, no
“garbage” in the form of rest tokens, remains. Correctness of transactions over two or more components can be assured if the union of isolated components and their communication places is an isolated flow component itself!

The flow components A and B of Figure 17 (1) are sound by definition. The ‘union’ of both components and their communication places is again a flow component, constructed from the start-net by substituting the iteration, the parallelism and the sequence (2x) blocks. Therefore the transaction over both components is sound!

Figure 17. Correctness by construction.

Figure 17 (2) is another example of a sound structured component: A, B and C only have start and stop connectors. In fact they are parallel paths of one flow.

In Figure 17 (3) correctness cannot be guaranteed, but the components B, C and D have an interesting property: they all communicate via the flow component A. Therefore, communication errors are easy to find.

3.5 Data Type and Transition Language

As we stated in the Section 2, components are based on coloured Petri nets. In coloured Petri nets tokens may have a value of a certain type. We will not discuss the type set and the typing of components in detail. Instead we make the following remarks:
- all places and connectors of a component have a type;
- if we want to glue a connector to another connector or a place then we have to check if the types are equal, i.e., if M(t,x) = a then the types of x and a should match.

Elementary transitions in a component have an input-output relation, which determines their consumption-production behaviour. To specify the logic of transitions we use a language. Various choices can be made. For instance we can use a subset of the Z-language that is defined in [4] or, close to this typed functional language, we can use the ExSpect-language. But also other choices can be made: there is a version of ExSpect that uses the C*-language. Since components are often distributed over various hardware platforms it is interesting to investigate whether it is advantageous to use a subset of Java.
4 Classes and Objects

There is a relation between the static structure and the dynamic behaviour of components on one hand and classes and objects on the other hand. We will discuss this analogy.

Flow components handle transactions or cases of a particular type. Therefore, all places of one flow component are of the same type; we call it the flow type of the component. The flow component is considered as a class of this type. Each method of this class corresponds to a transition. Objects in this class are called flow objects. They refer to the transaction-data and are represented in the semantic model by a set of tokens of the same transaction (possibly more than one because of parallel paths). Note that flow objects have a life cycle and describe the dynamic structure of the component. They have a relatively short life and live exclusive in a flow component. If the flow reached its end state, they cease to exist.

Memory components operate on data objects (i.e., entities that have significance in the 'real' world, for instance customer data or invoices), on case data (i.e., the subject of a case, a case-owner, a date, decisions made) or on other persistent entities. A memory component offers the opportunity to access data of various types. Each store in the memory component may correspond to a different type and a transition may update multiple stores. Therefore, a memory component is more general than a class. A class method is only allowed to operate on objects of one type. A transition in a memory component corresponds to a method or a sequence of methods invoking each other, and so a memory component may represent more than one class. The objects of the classes are called memory objects. A set of memory objects of the same class is represented by a single token in a store. Memory objects have a relatively long life and live exclusively in memory components. They remain in a store even when the component is idle. In other words they are persistent. Memory object may have links to other objects in the same or different classes.

Communication places are used to connect components. They are attached to two transitions, one of each component: the first produces a token and second consumes a token. This corresponds to communication classes with a create- and a destroy-method only (no updates). The objects of this class are messages and are of the same type as the type of the place. Each message is represented by only one token. Messages have a very short life and they live exclusively between components. Flow or memory objects create them during a transaction.

5 Integrated Views and UML

Consistency of system views can be assured when they are based on an integrated model. This means that they can be derived by fixed rules or generated by running a simulation. From a structured component model we derive a number of views that are supported graphically by UML: the component view, the sequence diagram and the class diagram. Other views from UML such as activity diagrams and state diagrams are omitted because they are less general than coloured Petri nets.
5.1 The Component View

The component view describes graphically relations between components. These relations may concern knowledge about the dynamic behaviour or structural properties of components. We distinguish the following relations:

(i) the \textit{is-part-of relation}; this relation describes the static structure, often denoted by the inclusion sign; in the example: ServerFlow $\subseteq$ Server. Figure 18 illustrates this view for the Client-Server example.

(ii) the \textit{inheritance relations}; this relation is defined for WF-nets in [2], for components in general it is not yet fully defined. Nevertheless, inheritance for a memory component occurs if we add an extra attribute to one of the store places and reuse the old structure. For instance suppose the UserStore of Figure 7 is extended to make the users either PC or Mac users. Then we can describe this specialisation by the relation in Figure 19 (1).

(iii) the \textit{invoke relation} (see Definition 9); it means that flow objects in one component may create flow objects in another component. There are two possibilities: a parent object may not vanish before all its children vanished (Figure 19: 2a), or a parent object may vanish independently of its children (Figure 19: 2b). In the example Protocol objects may create Client objects and Server objects. In (b) the Server may go down while Clients are still active.

(iv) the \textit{know relation}; it means that a flow object has an attribute that refers to the ID of another flow object. This relation only makes sense if we assume that two flow objects may only communicate if they know each other. For memory components this means that an object could refer to another memory object possibly in another memory component. Figure 19 (3) illustrates the notation.

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{diagram.png}
\caption{The is-part-of relation.}
\end{figure}

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{diagram2.png}
\caption{The inheritance (1), the invoke (2a, 2b) and the know relation (3).}
\end{figure}
5.2 The Sequence Diagram

In fact, the UML Sequence Diagram existed long before UML, as Message Sequence Charts. They can be useful to evaluate particular scenarios of communication between components. They can be derived from the component model by monitoring the communication places between components. For instance, ExSpect has the possibility to generate Message Sequence Charts during a simulation. Figure 20 illustrates the client-server protocol of the example.

![Sequence Diagram Example](image)

Figure 20. Generating Sequence Diagrams.

Each time a message object is present in one of the message places, it is monitored: the sender and receiver of the object are registered. This results in an arrow in the sequence diagram at the right-hand side of Figure 20. A difference between a Petri net and a Sequence Diagram is that the firing sequence of the Petri net can not be determined without investigating the flattened net. In Figure 20 the sequence of the places accidentally coincides with that of the messages.

5.3 The Class Diagram

In Section 4 we discussed the relation between components and transactions and classes and objects. This enables us to make a class diagram for each type of component. We will not discuss this in detail but Figure 21 illustrates the concept. It is the class diagram of the memory component User of Figure 7. It indicates that there is a one-to-many relation between objects in the Department and the User store. Transitions use this relation to access linked objects simultaneously.

![Class Diagram Example](image)

Figure 21. The class diagram of the MC user.
6 Conclusions

In this paper we have demonstrated a way to describe components and the interaction between components in a formal way using coloured Petri nets. We distinguished three kinds of components namely flow components, memory components and structured components. Concepts from workflow management and object orientation are incorporated in these components and give them a well-founded structure. Together the components form a framework to describe and evaluate component-based (software) architectures. Important advantages of the framework are that it can be used to define system views formally and to extend inheritance concepts to components. In this way the framework forms a formal basis under (view) languages like UML. The tool ExSpect is suitable to develop and test structured components, but it does not support system views and correctness checks. It would be useful to extend ExSpect with these features.

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