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The design and implementation of the FIRE engine:
A C++ toolkit for Finite automata
and Regular Expressions

by

B.W. Watson

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The design and implementation of the FIRE engine: A C++ toolkit for FInite automata and Regular Expressions

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August 15, 1994

Abstract

This paper describes the design and implementation of version 1.2 of the FIRE engine. The FIRE engine is a C++ class library implementing finite automata and regular expression algorithms. The algorithms implemented in the toolkit are almost all of those presented in the taxonomies of finite automata algorithms [Wat93a, Wat93b]. The reader is assumed to be familiar with the two taxonomies and with advanced C++ programming techniques.

The toolkit is implemented largely in an object-oriented style, with finite automata and regular expressions being defined as classes. All of the classes and functions in the toolkit are presented in the same format. For each class (or function) the format includes a short description of its behaviour, details of its implementation, and techniques for improving its performance.
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1 Introduction

The FIRE engine is a class library implementing finite automata and regular expression algorithms. The algorithms implemented are all of the algorithms presented in the taxonomies of finite automata algorithms [Wat93a, Wat93b]. This paper outlines the design and implementation of the class library, which consists of 9000 lines of C++ code. A number of other toolkits (mostly serving different purposes) are available; they are detailed in [Wat94], which also contains an introduction to the FIRE engine.

In order to understand the implementation of the FIRE engine, the reader is assumed to be familiar with the taxonomies [Wat93a, Wat93b], and with C++ terminology and programming techniques. An introduction to the C++ language can be found in [Lip91, Str91] (the language reference appears in [Str91, SE90]), while an introduction to C++ programming techniques can be found in [Bud94]. Advanced C++ programming techniques are presented in [Cop92, MeS92, Mur93]. Object-oriented programming, in general, is discussed in [Bo094, Bud91, MeB88].

The most effective way to understand the implementation of the class library is to read the code and the comments embedded within the code. The explanations given in this paper are intended as an outline, to assist in understanding the code.

This paper is structured as follows:

- Part I provides descriptions of all of the foundations classes — those classes used in the implementations of other classes.
- Part II gives descriptions of all classes related to regular expressions and \( \Sigma \)-algebras.
- Part III gives descriptions of all classes implementing finite automata.
- Part IV presents the functions implementing deterministic finite automata minimization algorithms.

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1.1 Coding conventions and performance issues

The toolkit is coded in a style which makes heavy use of the \texttt{assert} function. For all except the simplest classes, a member function called \texttt{class\_invariant} is defined; this member returns 1 if the object is structurally sound, and 0 otherwise. All member functions which are visible to clients should only be invoked on structurally sound objects and must leave the object in a structurally sound condition. The function call \texttt{assert( class\_invariant() )} is explicitly invoked at the beginning and end of all such member functions (except, of course, the function \texttt{class\_invariant}).

The definition of the class invariant is a useful starting point for understanding the structure and implementation of a particular class.

Additional assertions are used in places where the incorrect values of variables (or relations between variables) will cause catastrophic results (i.e. the machine is likely to crash). Assertions are also used in places where they may be of use in understanding the surrounding code. As mentioned below, \texttt{assert} can be disabled by compiling with the macro \texttt{NDEBUG} defined — meaning that there is no assertion overhead in a production version of the FIRE engine.

Almost all of the classes have an \texttt{ostream} insertion operator defined (an output operator). For implementation classes the output members are mainly for debugging purposes.

Many classes provide a member function called \texttt{reincarnate}. This function clears the object, leaving it in the same condition as it would be in after the argumentless constructor for the object. The only difference is that any memory already allocated by the members of the object is retained for future use.
1.1.1 Performance tuning

There are some general techniques that can be used to improve the performance of the various parts of the FIRE engine toolkit. The easiest method of improving the performance is to compile the toolkit with the macro NDEBUG defined. This will disable the assert function call, and should only be done when the program is functioning correctly and the safety of assertions and class invariants is no longer needed. Before hand-optimizing the code itself, an important first step is to profile the execution of the toolkit. Some preliminary profiling shows that a large amount of time is spent copying and allocating memory. Much of this time can be eliminated by using two techniques:

- Define and use special versions of the new and delete operators for the classes that make extensive use of memory management.
- "Use-count" all classes which copy large amounts of data in their copy constructors or assignment operators. (See any of [Cop92, MeS92, Mur93] for explanations of "use-counting").

1.2 Presentation conventions

Each class is presented in a standard format. The following items appear in the description of a class:

1. The name of the class, and whether it is a user level class (a class intended for use by program components internal and external to the FIRE engine), or an implementation level class (one used only by other classes within the FIRE engine).

2. The Files clause lists the files in which the class declaration and definition are stored. The names of the files associated with a class are usually the class name, followed by .h for interface (or header) files and .cpp for definition files. All file names are short enough for use under MS-DOS.

3. The Uses clause lists the classes of which this class is an immediate client or from which this class inherits directly. (Most classes use themselves; this is not mentioned.)

4. The Description clause gives a brief description of the purpose of the class.

5. The .h file (if there is one) corresponding to the class is listed.

6. The optional Implementation clause outlines the implementation of the class.

7. The optional Performance clause gives some suggestions on possible performance improvements to the implementation of the class.

8. The .cpp file (if there is one) corresponding to the class is listed.

9. The description ends with the □ symbol.
Part I
Foundation classes

2 Character ranges

The header file extras.h contains inline functions for computing minima and maxima of two numbers. The functions are overloaded to provide versions for types char and int.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
/* $Revision: 1.2 $ */
/* $Date: 1994/08/15 14:00:40 $ */
#ifndef EXTRAS_H
#define EXTRAS_H
inline int min( const int a, const int b ) {
    return( a < b ? a : b );
}
inline int max( const int a, const int b ) {
    return( a < b ? b : a );
}
#endif
```

User class: CharRange

Files: charrang.h, charrang.cpp

Uses:

Description: Sets of characters (denoted by a CharRange) can be used as automata transition labels and as regular expression atoms (unlike most other systems, which use single characters). The sets of characters are limited to a range of characters in the execution character set (no particular character set is assumed, and ASCII or EBCDIC can both be used). The ranges are specified by their upper and lower (inclusive) bounds. The denoted range may not be empty (allowing them to be empty greatly complicates the algorithms). Many member functions are provided, including functions determining if two CharRanges have a character in common, if one is entirely contained in another, or if they denote sets that are adjacent to one another (in the execution character set).

```c
/* (c) Copyright 1994 by Bruce Watson */
/* $Revision: 1.2 $ */
/* $Date: 1994/08/15 14:00:23 $ */
#ifndef CHARRANGE_H
#define CHARRANGE_H
#include "extras.h"
#include <cassert.h>
#include <iostream.h>

// Represent a set of characters (in the alphabet) in a subrange of char.
// Used by most classes as the basis of regular expressions and automata.

class CharRange {
public:
    // Some constructors:
    // The default is the empty range of characters.
    // and this does not satisfy the class invariant.
    inline CharRange();
```
private:
    char lo, hi;
};

// class_invariant() is not satisfied.
inline CharRange::CharRange() :
    lo( 1 ),
    hi( 0 ) {}
inline CharRange::CharRange( const CharRange& r ) :
    lo( r.lo ),
    hi( r.hi ) {
    assert( class_invariant() );
}
# A Sample of Code Snippet

```cpp
inline CharRange::CharRange( const char l, const char h ) :
    lo( l ),  
    hi( h ) {  
    assert( class_invariant() );
}

inline CharRange::CharRange( const char a ) : 
    lo( a ), 
    hi( a ) { 
    assert( class_invariant() );
}

inline int CharRange::contains( const char a ) const { 
    assert( class_invariant() );
    return( (lo <= a) && (a <= hi) );
}

inline char CharRange::low() const { 
    assert( class_invariant() );
    return( lo );
}

inline char CharRange::high() const { 
    assert( class_invariant() );
    return( hi );
}

inline int CharRange::operator==( const CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( (lo == r.lo) && (hi == r.hi) );
}

inline int CharRange::operator!=( const CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( !operator==( r ) );
}

inline int CharRange::operator<=( canst CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( r.lo <= lo && hi <= r.hi );
}

inline int CharRange::operator>=( canst CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( lo <= r.lo && r.hi <= hi );
}

inline int CharRange::operator>( canst CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( lo <= r.lo && r.hi <= hi );
}

inline int CharRange::operator<( canst CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( lo <= r.lo && hi <= r.hi );
}

inline int CharRange::not_disjoint( const CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( (lo <= r.hi) && (hi >= r.lo) );
}

inline int CharRange::overlap_or_adjacent( const CharRange& r ) const { 
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( not_disjoint( r ) 
    
    (
    (lo == hi + 1) 
    || (lo == hi + 1));

inline CharRange& CharRange::merge( const CharRange& r ) {
```
assert( overlap_or_adjacent( r ) );
lo = (char)min( lo, r.lo );
hi = (char)max( hi, r.hi );
return( *this );
}

inline CharRange& CharRange::intersection( const CharRange& r ) {
    lo = (char)max( lo, r.lo );
    hi = (char)min( hi, r.hi );
    return( *this );
}

inline CharRange CharRange::left_excess( const CharRange& r ) const {
    auto CharRange ret( min( lo, r.lo ), max( lo, r.lo ) - 1 );
    return( ret );
}

inline CharRange CharRange::right_excess( const CharRange& r ) const {
    auto CharRange ret( min( hi, r.hi ), max( hi, r.hi ) + 1 );
    return( ret );
}

inline int CharRange::class_invariant() const {
    // This could possibly be wrong if something goes weird with char being
    // signed or unsigned.
    return( lo <= hi );
}
#endif

Implementation: CharRanges are represented as a pair of characters: the upper and lower (inclusive) bounds. There is a potential for problems caused by the fact that the language standard does not specify whether char is signed or unsigned.

Performance: In most functions that take a CharRange, the parameter passing is by value (since a pair of characters fit into the parameter passing registers on most processors). On some machines, performance can be improved by passing a const reference.
Implementation class: CRSet

Files: crset.h, crset.cpp

Uses: CharRange

Description: A CRSet is a set of CharRanges, with a restriction: all CharRanges in a CRSet are pairwise disjoint. When a new CharRange is added to a CRSet, some CharRanges may be split to ensure that the disjointness property is preserved. Members are provided to check if two CRSets cover the same characters, and to combine two CRSets.

```cpp
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:25 $
#ifndef CRSET_H
#define CRSET_H
#include "charrang.h"
#include <assert.h>
#include <iostream.h>

class CRSet { public:
  // Some basic constructors.
  // Create the emptyset:
  inline CRSet();

  // The singleton set:
  CRSet( const CharRange a );
  CRSet( const CRSet& r );

  // Also need a destructor and an operator=
  inline ~CRSet();
  const CRSet& operator=( const CRSet& r );

  // Some basic operations.
  // Add a CharRange to this set, splitting it as required.
  // It's not possible to add the empty CharRange to a CRSet!
  inline CRSet& add( CharRange a );

  // Append a CharRange onto the end of this set, knowing that a is disjoint with
  // any others in the set.
  inline CRSet& append( const CharRange a );

  // Combine two CRSet's, splitting CharRange's to maintain their pairwise
  // disjointness.
  CRSet& combine( const CRSet& a );

  // Does *this and r cover the same set of characters?
  int equivalent_cover( const CRSet& r ) const;

  // How many CharRanges are in *this?
  inline int size() const;

  // Some iterators:
  // Fetch the i'th CharRange in *this.
  inline const CharRange& iterator( const int it ) const;
```

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2 CHARACTER RANGES

// Is there even an it'th CharRange?
inline int iter_end( const int it ) const;

// Some special members:
inline int class_invariant() const;
friend ostream& operator<<<( ostream& os, const CRSet& r );

private:
// A simple helper.
void ensure_min_size( int s );

// Add a CharRange to this set, splitting it as required.
// Adding begins at i. This is used in CRSet::add().
void add_at( CharRange a, int i );

// Is r covered by this set?
int covered( const CharRange r ) const;

// A class constant:
// must be at least 1.
enum { expansion_size = 5 };

// Some implementation details:
int howmany;
int in_use;
CharRange *data;

};

inline CRSet::CRSet() :
    howmany( 0 ),
    in_use( 0 ),
    data( 0 )
{    
    assert( class_invariant() );
}

inline CRSet::~CRSet() {
    assert( class_invariant() );
    delete [] data;
}

// Insert a without checking to see if it overlaps with any of them already.
inline CRSet& CRSet::append( const CharRange a ) {
    assert( class_invariant() );
    assert( a.class_invariant() );
    ensure_min_size( in_use + 1 );
    data[in_use++] = a;
    assert( class_invariant() );
    return( *this );
}

// Add a CharRange to this set, splitting it as required.
// It's not possible to add the empty CharRange to a CRSet!
inline CRSet& CRSet::add( CharRange a ) {
    assert( class_invariant() );
    add_at( a, 0 );
    return( *this );
}

inline int CRSet::size() const {
    assert( class_invariant() );
    return( in_use );
}

inline const CharRange& CRSet::iterator( const int it ) const {
    assert( class_invariant() );
Implementation: A CRSet contains a pointer to a dynamically allocated array of CharRanges, an integer representing the size of the array, and an integer representing the number of elements in the array that are in use. The member add_at is a good candidate for optimization.
auto CharRange &d( new CharRange {howmany = r.in_use + expansion_size} );
delete [] data;
data = d;
}
assert( r.in_use <= howmany );

auto int i;
for( i = 0; i < r.in_use; i++ ) {
data[i] = r.data[i];
}
in_use = r.in_use;

assert( class_invariant() );
return( *this );
}

void GRSet::add_at( CharRange a, int i ) {
assert( class_invariant() );
assert( a.class_invariant() );

// Go through data[i] to see if a can be coalesced with data[i].
for( ; i < in_use && !data[i].not_disjoint( a ); i++ );

// Perhaps this is a coalescing candidate.
// There are several possibilities, namely:
// a and data[i] are disjoint
// a <= data[i] (a is entirely contained in data[i]
// data[i] <= a
// a and data[i] are not disjoint (but no containment holds).
// In this case, we have three pieces: the intersection,
// and a slice each from a, data[i].

if( i < in_use ) {
assert( data[i].not_disjoint( a ) );
if( data[i] == a ) {
// Nothing to do.
} else {
assert( data[i].not_disjoint( a ) && (data[i] != a ) );

// a needs some splitting. We know that the excess
// does not fall into data[0 .. i], we begin adding the excess
// at data[i+1].
// For efficiency (not implemented here), we could just
// append any part of data[i] that doesn't fall within
// a, since data[i] is pairwise disjoint with all other
// elements in array data[].

auto CharRange old( data[i] );
data[i].intersection( a );
// data[i] now contains old intersection a.

// Now deal with the left and right excesses of old with a.
// There are a few possibilities:
if( a.low() != old.low() ) {
// Then there is a left excess
add_at( a.left_excess( old ), i + 1 );
}
if( a.high() != old.high() ) {
// Then there is a right excess
add_at( a.right_excess( old ), i + 1 );
}
}
else {
assert( i >= in_use );

// There may still be something left to put in data[].
append( a );
assert( class_invariant() );
return;
}

CRSet& CRSet::combine( const CRSet& r ) {
assert( r.class_invariant() );
assert( class_invariant() );
auto int i;
for( i = 0; i < r.in_use; i++ ) {
    add( r.data[i] );
}
assert( class_invariant() );
return( *this );
}

// Does *this and r cover the same set of letters?
int CRSet::equivalent_cover( const CRSet& r ) const {
assert( class_invariant() );
auto int i;
auto int result( 1 );
for( i = 0; (i < in_use) && result; i++ ) {
    result = r.covered( data[i] );
}
return( result );
}

// Is r covered by this set?
int CRSet::covered( const CharRange r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
auto int i;
for( i = 0; (i < in_use) && !r.not_disjoint( data[i] ); i++ );
if( i < in_use ) {
    assert( r.not_disjoint( data[i] ) );
    // They have something in common.
    if( r <= data[i] ) {
        // r is completely covered by data[i]
        return( 1 );
    } else {
        // Now, figure out if the excesses are
        // also covered.
        // This could be made more efficient!
        auto int ret1{ 1 };
        auto int ret2{ 1 };
        if( r.low() != data[i].low() ) {
            // There actually is a left excess:
            ret1 = covered( r.left_excess( data[i] ) );
        } else {
            // There actually is a right excess:
            ret2 = covered( r.right_excess( data[i] ) );
        }
        return( ret1 && ret2 );
    }
} else {
    assert( i >= in_use );
    // r is not covered by *this.
    return( 0 );
}

// Make sure that data is at least s (adjusting howmany, but not in_use).
void CRSet::ensure_min_size(int s) {
    assert(class_invariant());
    // May need to allocate some new memory.
    if( s > howmany ) {
        auto CharRange *d = new CharRange[howmany + expansion_size];
        auto int i;
        for( i = 0; i < in_use; i++ ) {
            d[i] = data[i];
        }
        delete[] data;
        data = d;
    }
    assert(class_invariant());
}

ostream& operator<<(ostream& os, const CRSet& r) {
    os << '{';
    auto int i;
    for( i = 0; i < r.in_use; i++ ) {
        os << r.data[i];
    }
    return( os << '}' );
}
3 Bit vectors

Implementation class: BitVec

Files: bitvec.h, bitvec.cpp

Uses: extras.h

Description: Bit vectors wider than a single word are used in implementing sets without a compiled-in size bound. In addition to many of the standard bit level operators, iterators are also provided. The vectors have a width that is adjustable through a member function. Binary operators on vectors must have operands of the same width, and such width management is left to the client. When a vector is widened, the newly allocated bits are assumed to be zero.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2$
// $Date: 1994/08/15 14:00:23$
#ifndef BITVEC_H
#define BITVEC_H

#include <iostream.h>
#include <assert.h>

class BitVec { 10
  public:
    // Constructors, destructors, operator=:
    // Default constructor creates the empty set, with little effort.
    // This assumes that delete [] 0 is okay (when it is deleted later).
    inline BitVec();

    // Normal copy constructor.
    BitVec( const BitVec& r );

    // Normal non-virtual destructor.
    inline ~BitVec();

    // Needs a special operator=.
    const BitVec& operator=( const BitVec& r );

    // Tests:
    // A special equality operator.
    int operator==( const BitVec& r ) const;

    // Inequality operator.
    inline int operator!=( const BitVec& r ) const;

    // Is there a bit set?
    int something_set() const;

    // How many bits are set?
    int bits_set() const;

    // Bit vector operators:
    // set a bit
    inline BitVec& set_bit( const int r );

```
// unset a bit
inline BitVec& unset_bit( const int r );

BitVec& bitwise_or( const BitVec& r );

BitVec& bitwise_and( const BitVec& r );

BitVec& bitwise_unset( const BitVec& r );

BitVec& bitwise_complement();

// Bitwise containment.
int contains( const BitVec& r ) const;

// Is a bit set?
inline int contains( const int r ) const;

// Does *this have a bit in common with r?
int something_common( const BitVec& r ) const;

// Make *this the empty vector.
void clear();

// What is the set bit with the smallest index in *this?
int smallest() const;

// Some width related members:
inline int width() const;

void set_width( const int r );

// Recycle this BitVec.
inline void reincarnate();

// Shift *this left, zero filling.
BitVec& left_shift( const int r );

// Append another bit-vector.
BitVec& append( const BitVec& r );

// Iterators:

// Place the index of the first set bit in the iteration in reference r.
// r == -1 if there is no first one.
inline int iter_start( int& r ) const;

// Is r the last set bit in an iteration sequence.
inline int iter_end( int r ) const;

// Place the next set bit, after r (in the iteration sequence), in reference r.
int iter_next( int& r ) const;

// Other special members:

friend ostream& operator<<( ostream& os, const BitVec& r );

// Structural invariant on the BitVec.
inline int class_invariant() const;

private:

// Some trivial helpers:

// Compute the number of words required to hold st bits.
inline int words_required( const int st ) const;

// Compute the word index of a particular bit r.
inline int word_index( const int r ) const;

// Compute the hit index (from the LSB) of a bit r.
inline int bit_index( const int r ) const;

// Actual representation:
int bits_in_use;
int words;
unsigned int *data;

// A class constant, used for bit-vector width.
enum { bits_per_word = (sizeof( unsigned int ) * 8) };

// Now for the inline versions of the member functions:
inline BitVec::BitVec() :
    bits_in_use( 0 ),
    words( 0 ),
    data( 0 )
{ assert( class_invariant() ); }

inline BitVec::~BitVec() {
    assert( class_invariant() );
    delete [] data;
}

inline void BitVec::reincarnate() {
    assert( class_invariant() );
    clear();
    bits_in_use = 0;
    assert( class_invariant() );
}

inline int BitVec::words_required( const int st ) const {
    // This may be a little more complicated than it has to be.
    return( (st / bits_per_word) + (st % bits_per_word) != 0 ? 1 : 0 );
}

inline int BitVec::word_index( const int r ) const {
    return( r / bits_per_word );
}

inline int BitVec::bit_index( const int r ) const {
    return( r % bits_per_word );
}

inline int BitVec::operator!=( const BitVec& r ) const {
    return( *operator==( r ) );
}

inline int BitVec::width() const {
    return( bits_in_use );
}

inline BitVec& BitVec::set_bit( const int r ) {
    assert( 0 <= r ) && ( r < width() );
    assert( class_invariant() );
    data[word_index( r )] |= (1U << bit_index( r ));
    return( *this );
}
inline BitVec& BitVec::unset_bit( const int r ) {  
  // Unset the r'th bit.
  assert( (0 <= r) && (r < width()) );
  assert( class_invariant() );
  data[word_index(r)] &= ~(1U << bit_index(r));
  return(*this);
}

inline int BitVec::contains( const int r ) const {
  // Check if the r'th bit is set.
  assert(r < width());
  assert(class_invariant());
  return(data[word_index(r)] & (1U << bit_index(r))) != 0U;
}

inline int BitVec::iterate_start( int& r ) const {
  assert(class_invariant());
  return(r = smallest());
}

inline int BitVec::iterate_end( int r ) const {
  return(r == -1);
}

inline int BitVec::class_invariant() const {
  return((width() <= words * bits_per_word)
          && (width() >= 0)
          && (words >= 0)
          && (words == 0 ? data == 0 : data != 0));
}

#endif

Implementation: The implementation is largely replaceable by any standard library providing the same functionality. The width is stored as an integer in the object, along with the number of words allocated. The vector itself is stored as a pointer to an allocated block of unsigned int. The width can only grow (except in the case of a reincarnate member function call; it will then shrink to zero).

Performance: The low level bit operations could benefit from being written in assembler. The copying of the data area that occurs in the copy constructor and assignment operator can be avoided by use-counting. The left shift operator and the iteration operators could be implemented more efficiently.
assert( r.class_invariant() );
// Check against assignment to self.
if( this != &r ) {
    // The data area may need to be grown.
    if( words < words_required( r.width() ) ) {
        words = words_required( r.width() );
        // Wipe out previously used memory.
        // Assume delete [] 0 is okay.
        delete [] data;
        // Could probably benefit from a specialized operator new.
        data = new unsigned int [words];
    }
    assert( words >= words_required( r.width() ) );
    bits_in_use = r.bits_in_use;
    auto int i;
    for( i = 0; i < words_required( r.width() ); i++ ) {
        data[i] = r.data[i];
    }
    // Make sure that nothing extraneous is in the vector.
    for( ; i < words; i++ ) {
        data[i] = 0U;
    }
}
assert( class_invariant() );
return( *this );
// General-purpose counter.
auto int i;
for( i = 0; i < min( words, r.words ); i++ ) {
    data[i] = r.data[i];
}
return( *this );
}

BitVec& BitVec::bitwise_and( const BitVec& r ) {
    assert( class_invariant() && r.class_invariant() );
    assert( width() == r.width() );
    auto int i;
    for( i = 0; i < min( words, r.words ); i++ ) {
        data[i] &= r.data[i];
    }
    return( *this );
}

BitVec& BitVec::bitwise_unset( const BitVec& r ) {
    assert( class_invariant() && r.class_invariant() );
    assert( width() == r.width() );
    auto int i;
    for( i = 0; i < min( words, r.words ); i++ ) {
        data[i] &= ~r.data[i];
    }
    return( *this );
}

BitVec& BitVec::bitwise_complement() {
    assert( class_invariant() );

    // Do a bitwise complement of all of data that's in use.
    auto int i;
    auto int w( words_required( bits_in_use ) );
    for( i = 0; i < w; i++ ) {
        data[i] = ~data[i];
    }

    // Now make sure that only bits that the only 1 bits are those that fall
    // within [0,bits_in_use) if( bit_index( bits_in_use ) != 0 ) {
    // There are some bits that are not used in data/w-1:
    // "and" the unused ones away.
    data[w - 1] &= ((1U << bit_index( bits_in_use )) - 1);

    assert( class_invariant() );
    return( *this );
}

int BitVec::contains( const BitVec& r ) const {
    assert( class_invariant() && r.class_invariant() );
    assert( width() == r.width() );
    auto int i;
    for( i = 0; i < min( words, r.words ); i++ ) {
        if( r.data[i] != (r.data[i] & data[i]) ) {
            return( 0 );
        }
    }
    return( 1 );
}

int BitVec::something_common( const BitVec& r ) const {
    assert( class_invariant() && r.class_invariant() );
    assert( width() == r.width() );
    // Check if there's a bit in common.
    auto int i;
    auto unsigned int result( 0U );
```cpp
for( i = 0; i < min( words, r.words ); i++ ) {
    result |= (data[i] & r.data[i]);
} return( result != 0U );
}

int BitVec::something_set() const {
    assert( class_invariant() );
    // Check if all bits are unset.
    auto int i;
    auto unsigned int result( 0U );
    for( i = 0; i < words; i++ ) {
        result |= data[i];
    } return( result != 0U );
}

BitVec& BitVec::left_shift( const int r ) {
    // Don't do anything needless:
    if( r == 0 ) {
        words = words_required( width() + r );
        auto unsigned int *d( new unsigned int [words] );
        auto int i;
        for( i = 0; i < words; i++ ) {
            d[i] = 0U;
        } auto int wi = word_index( r );
        auto int bi = bit_index( r );
        // (wi,bi) index where the first bit of data[i] must go in d[i]
        if( bi == 0 ) {
            // Word aligned.
            for( i = 0; i < words_required( width() ); i++ ) {
                d[i + wi] = data[i];
            }
        } else {
            // Deal with the unaligned case.
            // Mask has the (bi) least-significant bits on.
            auto unsigned int rmask = (1U << bi) - 1;
            for( i = 0; i < words_required( width() ); i++ ) {
                // move data[i] into d[i+wi] and d[i+wi+1]
                // d[i + wi] = (d[i + wi] & rmask) | ((data[i] << bi) & ~rmask);
                // Assume that zero-filling occurs on the LSB.
                d[i + wi] = (d[i + wi] & rmask) | (data[i] << bi);
                d[i + wi + 1] = (data[i] >> (bits_per_word - bi)) & rmask;
            }
        }
        delete [] data;
        data = d;
        bits_in_use += r;
    }
    return( *this );
}

void BitVec::set_width( const int r ) {
    assert( class_invariant() );
    // Make sure that things are not shrinking.
    assert( r >= width() );
    // The data[] area may need some growing.
    if( r > words * bits_per_word ) {
        auto int w( words_required( r ) );
        auto unsigned int *d( new unsigned int [w] );
        auto int i;
        // Copy the useful stuff over to the new area.
        for( i = 0; i < words; i++ ) {
            d[i] = data[i];
        }
    }
```
// Make sure that now additional bits are set.
for ( ; i < w; i++ ) {
    d[i] = 0U;
}
delete[] data;
data = d;
words = w;

bits_in_use = r;
assert(class_invariant());
}

// The following could be made a lot more efficient by not constructing the local BitVec.
BitVec& BitVec::append( const BitVec& r ) {
    assert( class_invariant() && r.class_invariant() );
    auto BitVec t( r );
    // Make room for *this.
    t.left_shift( width() );
    assert( t.width() == width() + r.width() );
    set_width( width() + r.width() );
    assert( t.width() == width() );
    bitwise_or( t );
    assert( class_invariant() );
    return( *this );
}

int BitVec::iteLnext( int& r ) const {
    assert( class_invariant() );
    // Find the next bit that is set.
    for( r++ ; r < width(); r++ ) {
        if( contains( r ) ) {
            return( r );
        }
    }
    return( r = -1 );
}

int BitVec::smallest() const {
    assert( class_invariant() );
    // Find the first non-empty word.
    auto int r;
    auto int howfar( words_required( width() ) );
    for( r = 0; r < howfar && (data[r] == 0); r++ );

    // Could be that there isn't one:
    if( r == howfar ) {
        return( -1 );
    }

    // Find the first non-zero bit.
    auto int bitnum( r * bits_per_word );
    auto unsigned int d( data[r] );
    // Keep eating bits until the least significant bit is 1.
    // We're sure that there will be a bit.
    assert( d != 0U );
    while( d % 2 == 0 ) {
        bitnum++;
        d = d >> 1;
    }
    return( bitnum );
}

ostream& operator<<( ostream& os, const BitVec& r ) {
    assert( r.class_invariant() );
}
// Output the BitVec as a space-separated sequence of set bits.
auto int st;
    os << "{";
for( r.iter_start( st ); !r.iter_end( st ); r.iter_next( st ) ) {
    os << " " << st << " ";
}
return( os << "}" );

4 States and related classes

Implementation class: State

Files: state.h

Uses:

Description: In the FIRE engine, all finite automaton states are encoded as non-negative integers. The special value Invalid is used to flag an invalid state.

Implementation: Not making State a class has the effect that no extra information can be stored in a state, and a State can be silently converted to an int.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:54 $
#ifndef STATE_H
#define STATE_H

// Encode automata states as integers.
typedef signed int State;
// Invalid states mean something bad is about to happen.
const State Invalid = -1;
#endif
```

Implementation class: StatePool

Files: st-pool.h

Uses: State

Description: A StatePool is a dispenser of States (beginning with 0). A member function size() returns the number of States allocated so far. Two StatePools can be combined into one, with the result that the StatePool being combined into *this must be renamed to not clash with the States already allocated from *this.

Implementation: An integer counter is maintained, indicating the next State to be allocated. The class is really too simple to have a class invariant.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:55 $
#ifndef STATEPOOL_H
#define STATEPOOL_H

#include "state.h"
#include <iostream.h>

class StatePool {
public:
  // By default, start allocating states at 0:
  inline StatePool();

  // A copy-constructed StatePool starts at the same point.
  inline StatePool( const StatePool& r );
```
private:
  // The next one to be allocated.
  int next;

inline StatePool::StatePool() :
  next( 0 ) {}  

inline StatePool::StatePool( const StatePool& r ) :
  next( r.next ) {}  

inline int StatePool::size() const {
  return( next );
}

inline StatePool& StatePool::incorporate( const StatePool r ) {
  next += r.size();
  return( *this );
}

inline State StatePool::allocate() {
  return( next++ );
}

inline StatePool& StatePool::reincarnate() {
  next = 0;
  return( *this );
}

inline int StatePool::contains( const State r ) const {
  return( 0 <= r && r < next );
}

inline ostream& operator<<( ostream& os, const StatePool r ) {
  return( os << "[0," << r.next << "]" );
}

#endif

Implementation class: StateSet
Files: stateset.h, stateset.cpp

Uses: BitVec, State

Description: A StateSet is a set of States with a certain capacity. The capacity (called the domain) is one more than the greatest State that the set can contain. It can easily be enlarged, but it can only be shrunk (to zero) through the reincarnate member function. The maintenance of the domain is the responsibility of the client. Normal set operations are available, including iterators. Most member functions taking another StateSet expect it to have the same domain as *this (with catastrophic results if this is not true). The States in the set can also be renamed, so that they do not clash with the States of a certain StatePool. It is possible to take the union of two StateSets containing States from different StatePools. In this case, the States in the incoming StateSet are renamed during the union; this is done with the disjointing_union member function.
// complement *this.
inline StateSet& complement();

// inserts a State.
inline StateSet& add( const State r );

// remove a State from the set.
inline StateSet& remove( const State r );

// Set union.
inline StateSet& set_union( const StateSet& r );

// Set intersection.
inline StateSet& intersection( const StateSet& r );

// Set difference.
inline StateSet& remove( const StateSet& r );

// Set containment.
inline int contains( const StateSet& r ) const;

// Is a State in the set?
inline int contains( const State r ) const;

// Does this set have something in common with r?
inline int not_disjoint( const StateSet& r ) const;

// Make this set the emptyset.
inline void clear();

// What is the smallest element of *this?
inline State smallest() const;

// Some domain related members:

// How many States can this set contain?
// {0, domain()} can be contained in *this.
inline int domain() const;

inline void set_domain( const int r );

// Recycle this StateSet.
inline void reincarnate();

// Rename the elements of this StateSet so that they don't fall within
// StatePool r.
inline StateSet& st_rename( const int r );

// Include another StateSet into this one, renaming all the States.
inline StateSet& disjointing_union( const StateSet& r );

// Iterators:

// Place the first State in the iteration in reference r.
// r == Invalid if there is no first one.
inline State iter_start( State& r ) const;

// Is r the last State in an iteration sequence.
inline int iter_end( State r ) const;

// Place the next State, after r (in the iteration sequence), in reference r.
inline State iter_next( State& r ) const;

// Other special members:
friend ofstream& operator<<( ofstream& os, const StateSet& r );

    // Structural invariant on the StateSet, just the class invariant of the base.
    inline int class_invariant() const;
};

inline StateSet::StateSet() :
    BitVec() {}

inline StateSet::StateSet( const StateSet& r ) :
    BitVec( r ) {}

inline const StateSet& StateSet::operator=( const StateSet& r ) {
    BitVec::operator=( r );
    return( *this );
}

inline int StateSet::operator==( const StateSet& r ) const {
    return( BitVec::operator==( r ) );
}

inline int StateSet::operator!=( const StateSet& r ) const {
    return( !operator==( r ) );
}

inline int StateSet::empty() const {
    return( !BitVec::something_set() );
}

inline int StateSet::size() const {
    return( BitVec::bits_set() );
}

inline StateSet& StateSet::complement() {
    assert( class_invariant() );
    BitVec::bitwise_complement();
    assert( class_invariant() );
    return( *this );
}

inline StateSet& StateSet::add( const State r ) {
    BitVec::set_bit( r );
    return( *this );
}

inline StateSet& StateSet::remove( const State r ) {
    BitVec::unset_bit( r );
    return( *this );
}

inline StateSet& StateSet::set_union( const StateSet& r ) {
    BitVec::bitwise_or( r );
    return( *this );
}

inline StateSet& StateSet::intersection( const StateSet& r ) {
    BitVec::bitwise_and( r );
    return( *this );
}

inline StateSet& StateSet::remove( const StateSet& r ) {
    BitVec::bitwise_unset( r );
    return( *this );
}

inline int StateSet::contains( const StateSet& r ) const {

```cpp
inline int StateSet::contains( const State r ) const {
    return( BitVec::contains( r ) );
}
inline int StateSet::not_disjoint( const StateSet& r ) const {
    return( BitVec::something_common( r ) );
}
inline void StateSet::clear() {
    BitVec::clear();
}
inline int StateSet::smallest() const {
    return( BitVec::smallest() );
}
inline int StateSet::domain() const {
    return( BitVec::width() );
}
inline void StateSet::set_domain( const int r ) {
    assert( r >= BitVec::width() );
    BitVec::set_width( r );
}
inline void StateSet::rename( const int r ) {
    BitVec::left_shift( r );
    return( *this );
}
inline void StateSet::disjointing_union( const StateSet& r ) {
    BitVec::append( r );
    return( *this );
}
inline State StateSet::iter_start( State& r ) const {
    return( BitVec::iter_start( r ) );
}
inline int StateSet::iter_end( State r ) const {
    return( BitVec::iter_end( r ) );
}
inline State StateSet::iter_next( State& r ) const {
    return( BitVec::iter_next( r ) );
}
inline int StateSet::class_invariant() const {
    // The invalid stuff is a required definition.
    return( BitVec::class_invariant() && (Invalid == -1) );
}
#endif
```

**Implementation:** `StateSet` inherits from `BitVec` for implementation. Most of the member functions are inline dummies, calling the `BitVec` members.
Performance: StateSet would benefit from use-counting in BitVec.

Implementation class: StateTo

Files: stateto.h

Uses: State

Description: StateTo is a template class implementing mappings from States to some class T (the template type parameter). It is used extensively in transition relations and binary relations on states. Two methods of mapping a State are provided:

- Member function map takes a State and returns a non-const reference to the associated T. This is most often used to set up the map, by changing the associated T.
- Member function lookup takes a State and returns a const reference to the associated T. This is intended for use in clients that only lookup information, without changing the map.

StateTo includes a reincarnate member function, which does not reincarnate the T's. As with StateSets, the domain of the StateTo must be explicitly maintained by the client. A special member function disjointing_union is available which performs a normal union after the domain of the incoming StateTo has been renamed to avoid clashing with the domain of *this.

Implementation: Each StateTo contains a pointer to a dynamically allocated array of T, an integer indicating the size of the array, and an integer indicating how many of the array elements are in use. Whenever the array of T is enlarged, a bit extra is allocated to avoid repeated calls to new. Class T must have a default constructor, an assignment operator and an insertion (output) operator.

Performance: StateTo would benefit from use-counting in the class T. Use-counting in StateTo itself would likely add too much overhead if it were already done in T.
public:

/ * Constructors, destructors, operator= */

/ * Default is to not map anything. */
StateTo();

/ * Copying can be costly. Use-counts could make this cheaper. */
StateTo( const StateTo<T>& r );

/ * Assume delete 0 is okay. */
virtual ~StateTo();

/ * Use-counts could make this cheaper. */
const StateTo<T>& operator=( const StateTo<T>& r );

/ * First, a const lookup operator. */
inline const T& lookup( const State r ) const;

/ * Used to associate a State and a T in the mapping. Note: not const. */
inline T& map( const State r );

/ * Some domain members: */

/ * How many States can *this map? */
inline int domain() const;

/ * Set a new domain. */
void set_domain( const int r );

/ * Note the reincarnate() doesn't reincarnate the T's. */
inline void reincarnate();

/ * Allow two mappings to be combined; the domain of *this remains the same, while the */
/ * domain of r is renamed to not clash with the domain of *this. */
StateTo<T>& disjointing_union( const StateTo<T>& r );

/ * Some extras: */

friend ostream& operator<<( ostream& os, const StateTo<T>& r );

/ * Assert that everything's okay. */
inline int class_invariant() const;

private:

/ * Represent the map as a dynamically allocated array of T's. */
int howmany;
in_use;
T *data;

/ * When the array is grown by a certain amount, it also grows by an extra */
/ * buffer amount for efficiency. */
enum { expansion_extra = 5 };
);

template<class T>
StateTo<T>::StateTo() :
howmany( 0 ),
in_use( 0 ),
data( 0 ) {
assert( class_invariant() );
}

/ * Copying can be costly. Use-counts could make this cheaper. */
template<typename T>
StateTo<T>::StateTo(const StateTo<T>& r) :
  howmany( r.in_use + expansion_extra ),
  in_use( r.in_use ),
  data( new T[ in_use + expansion_extra ] ) {
    assert( r.class_invariant() );
    auto int i;
    for( i = 0; i < in_use; i++ ) {
      data[i] = r.data[i];
    }
    assert( class_invariant() );
  }

  // Assume there is nothing wrong with delete [] .
  template<typename T>
StateTo<T>::~StateTo() {
  delete [] data;
}

  // Use-counts could make this cheaper.
  template<typename T>
const StateTo<T>& StateTo<T>::operator=( const StateTo<T>& r ) {
    assert( r.class_invariant() );
    // Prevent assignment to self.
    if( this != &r ) {
      // Is there enough memory to contain the assignment?
      if( howmany < r.in_use ) {
        delete [] data;
        data = new T[ howmany = r.in_use + expansion_extra ];
      }
      in_use = r.in_use;
      assert( in_use <= howmany );
      auto int i;
      for( i = 0; i < in_use; i++ ) {
        data[i] = r.data[i];
      }
    }
    assert( class_invariant() );
    return( *this );
  }

  // The actual mapping functions:
  template<typename T>
inline const T& StateTo<T>::lookup( const State r ) const {
    assert( class_invariant() );
    // First check that it's in bounds.
    assert( 0 <= r && r < domain() );
    return( data[r] );
}

  // Used to associate a State and a T in the mapping. Note: not const.
  template<typename T>
inline T& StateTo<T>::map( const State r ) {
    assert( class_invariant() );
    // First check that it's in bounds.
    assert( 0 <= r && r < domain() );
    return( data[r] );
}

  // How many States can *this map?
  template<typename T>
inline int StateTo<T>::domain() const {
    return( in_use );
}

  // Set a new domain.
  template<typename T>
void StateTo<T>::set_domain( const int r ) {
    assert( class_invariant() );
    // Make sure that things aren't shrinking.
    assert( r >= in_use );
    if( r > howmany ) {
        auto int i;
        auto T *d( new T [howmany = r + expansion_extra] );
        for( i = 0; i < in_use; i++ ) {
            d[i] = data[i];
        }
        delete [] data;
        data = d;
        // Note: the newly created T's are only default constructed.
    }
    in_use = r;
    assert( class_invariant() );
}

// NB: the reincarnate() doesn't reincarnate the T's.
template<class T>
inline void StateTo<T>::reincarnate() {
in_use = 0;
}

// Allow two mappings to be combined; the domain of *this remains the same, while the
// domain of r is renamed to avoid this->domain().
template<class T>
StateTo<T>& StateTo<T>::disjointing_union( const StateTo<T>& r ) {
    assert( class_invariant() && r.class_invariant() );
    if( r.domain() != 0 ) {
        auto int olddom( domain() );
        set_domain( domain() + r.domain() );
        assert( domain() == olddom + r.domain() );

        // Copy r into the new location.
        auto int i;
        for( i = 0; i < r.domain(); i++ ) {
            data[i] = r.data[i];
        }
    }
    assert( class_invariant() );
    return( *this );
}

// T is assumed to have an operator<<
template<class T>
inline ostream& operator<<( ostream& os, const StateTo<T>& r ) {
    assert( r.class_invariant() );
    auto State i;
    for( i = 0; i < r.in_use; i++ ) {
        os << i << "->" << r.data[i] << endl;
    }
    return( os );
}

// Assert that everything's okay.
template<class T>
inline int StateTo<T>::class_invariant() const {
    return( 0 <= in_use
              && in_use <= howmany
              // So 0 <= howmany by transitivity.
              && (howmany != 0 ? data != 0 : data == 0) );
}

#endif
5 Transitions and related classes

Implementation class: TransPair

Files: tr-pair.h

Uses: CharRange, State

Description: A TransPair is a transition, a structure consisting of a label (a CharRange) and a destination State. The two are contained in the TransPair structure.

Implementation: A struct is defined, without member functions.

```
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 14:01:04 $ 
#ifndef TR_PAIRS_H 
#define TR_PAIRS_H 
#include "charrang.h" 
#include "state.h" 

struct TransPair { 
    CharRange transition_label; 
    State transition_destination; 
};
#endif
```

Implementation class: TransImpl

Files: tr-impl.h, tr-impl.cpp

Uses: CharRange, CRSet, State, StateSet, TransPair

Description: A TransImpl is a set of TransPairs. It is used as a base class for Trans and DTrans, which are used to implement transition relations. TransPairs can be added, but not removed from the set. When a new TransPair is added, if its CharRange is adjacent to the CharRange of a TransPair already in the set, and the destination State of the two TransPairs is the same, then the two TransPairs are merged into one.

```
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $ 
// $Date: 1994/08/15 14:01:03 $ 
#ifndef TRANSIMPL_H 
#define TRANSIMPL_H 
#include "charrang.h" 
#include "crset.h" 
#include "state.h" 
#include "stateset.h" 
#include "tr-pair.h" 
#include <assert.h> 
#include <iostream.h>

// Implement the basics of a char to StateSet map (a set of TransPair's). 
// It is used by DTrans and Trans. 

class TransImpl { 
```
protected:
  // Constructors, destructors, operator=:
  inline TransImpl();

  // Assume that delete [] 0 is okay.
  inline TransImpl();

  // Copy constructor allocates more memory. Should use (use-counting)
  // for efficiency.
  TransImpl( TransImpl& const r );

  // Destructor is virtual, simple.
  virtual ~TransImpl();

  // operator=() must copy the memory.
  const TransImpl& operator=( const TransImpl& r );

  // Some member functions for making transitions:

  // What are all of the labels on transitions in *this?
  CRSet out_labels() const;

  // What are all transition labels with destination in r?
  CRSet labels_into( const StateSet& r ) const;

  // Some special member functions:

  // Clear out all previous transitions, and zero the domain.
  inline void reincarnate();

  // Add a transition to the set.
  TransImpl& add_transition( const CharRange a, const State q );

  // Allow classes that inherit from TransImpl to have access to the real data:
  inline TransPair& transitions( const int i ) const;

  // Output the transitions.
  friend ostream& operator<<( ostream&, const TransImpl& r );

  // Maintain the class invariant.
  inline int class_invariant() const;

  // Helpers:
  void ensure_min_size( int w );

  // Implementation details:

  // How many transitions are there.
  int howmany;
  int in_use;

private:
  // A dynamically allocated array of (CharRange,State) pairs (transitions).
  TransPair *data;

  // For efficiency of the expansion helper function.
  enum { expansion_extra = 5 };
Assume that delete // 0 is okay.

```cpp
inline TransImpl::TransImpl() :
    howmany( 0 ),
    in_use( 0 ),
    data( 0 ) {
    assert( class_invariant() );
}
```

```cpp
inline void TransImpl::reincarnate() {
    assert( class_invariant() );
    in_use = 0;
    assert( class_invariant() );
}
```

```cpp
inline TransPair& TransImpl::transitions( const int i ) const {
    assert( class_invariant() );
    // i can be greater than in_use in some weird cases where the
    // transitions are still being set up.
    assert( 0 <= i );
    return( data[i] );
}
```

```cpp
// Maintain the class invariant.
inline int TransImpl::class_invariant() const {
    auto int ret( 1 );
    auto int i;
    for( i = 0; (i < in_use) && ret; i++ ) {
        ret = (data[i].transition_destination >= 0);
    }
    ret = ret && (in_use <= howmany);
    return( ret );
}
```

```cpp
#endif
```

### Implementation:
A `TransImpl` contains a pointer to a dynamically allocated array of `TransPair`, an integer indicating the size of the array, and an integer indicating how much of the array is in use.

### Performance:
Use-counting this class would bring a great benefit to `Trans`, `DTrans`, `TransRel`, and `DTransRel`.

```cpp
// Copy constructor allocates more memory. Should use copy-on-write (use-counting) for efficiency.
TransImpl::TransImpl( TransImpl& const r ) :
    howmany( r.in_use + expansion_extra ),
    in_use( r.in_use ),
    data( new TransPair [r.in_use + expansion_extra] ) {
    assert( r.class_invariant() );
    auto int ;
    for( i = 0; i < in_use; i++ ) {
        data[i] = r.data[i];
    }
    assert( class_invariant() );
}
```

```cpp
// Destructor is virtual, simple.
TransImpl::~TransImpl() {
    assert( class_invariant() );
    delete [] data;
}
```
5 TRANSITIONS AND RELATED CLASSES

// Standard dynamic memory copy:
const TransImpl& TransImpl::operator=( const TransImpl& r ) {
    assert( class_invariant() && r.class_invariant() );
    if( this != &r ) {
        // Don't use ensure_min_size() here due to excessive copying.
        if( howmany < r.in_use ) {
            auto TransPair *d( new TransPair[howmany = r.in_use + expansion_extra] );
            delete data;
            data = d;
        }
        assert( howmany >= r.in_use );
        auto int i;
        for( i = 0; i < r.in_use; i++ ) {
            data[i] = r.data[i];
        }
        in_use = r.in_use;
    }
    assert( class_invariant() );
    return( *this );
}

CRSet TransImpl::out_labels() const {
    auto int i;
    auto CRSet a;
    for( i = 0; i < in_use; i++ ) {
        a.add( data[i].transition_label );
    }
    return( a );
}

CRSet TransImpl::labels_into( const StateSet& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    auto int i;
    auto CRSet a;
    for( i = 0; i < in_use; i++ ) {
        assert( data[i].transition_destination <= r.domain() );
        if( r.contains( data[i].transition_destination ) ) {
            a.add( data[i].transition_label );
        }
    }
    assert( class_invariant() );
    return( a );
}

TransImpl& TransImpl::add_transition( const CharRange a, const State q ) {
    assert( 0 <= q );
    assert( a.class_invariant() );

    // Can the transition be merged with an already existing one.
    auto int i;
    for( i = 0; i < in_use; i++ ) {
        // They're mergeable if they go to the same place
        // and the labels are adjacent.
        if( (data[i].transition_destination == q) &&
            (data[i].transition_label.overlap_or_adjacent( a ) ) ) {
            data[i].transition_label.merge( a );
            return( *this );
        }
    }
    // The transition really must be added, since it wasn't merged.

    // Is there a need to grow the data[].
    ensure_min_size( in_use + 1 );
}
assert(in_use < howmany);
data[in_use].transition_label = a;
data[in_use+1].transition_destination = q;

return(*this);

void TransImpl::ensure_min_size(int w) {
    assert(class_invariant());
    assert(0 <= w);
    if(howmany < w) {
        auto TransPair *d(new TransPair[howmany = w + expansion_extra]);
        auto int i;
        for(i = 0; i < in_use; i++) {
            d[i] = data[i];
        }
        // Assume that delete [] is okay.
        delete[] data;
        data = d;
    }
    assert(howmany >= w);
    assert(class_invariant());
}

ostream& operator<<(ostream& os, const TransImpl& r) {
    assert(r.class_invariant());
    os << '{';
    auto int i;
    for(i = 0; i < r.in_use; i++) {
        os << ' ' << r.data[i].transition_label << '->' << r.data[i].transition_destination << ' ';
    }
    return(os << '}');
}

Implementation class: Trans

Files: trans.h, trans.cpp

Uses: CharRange, CRSet, State, StateSet, TransImpl, TransPair

Description: A Trans is a set of TransPairs (transitions) for use in transition relations. Transitions can be added to the set, but not removed. Member functions are provided to compute the destination of the transition set, on a particular character or on a CharRange (the destination is returned as a StateSet). Since a StateSet is returned, Trans has a range (which is one more than the maximum State that can occur as a transition destination) which is managed by the client and is used to determine the domain of the returned StateSet. Another member function computes the set of all transition labels, returning a CRSet.
#include <iostream.h>

// Map char to StateSet, using TransImpl.
// Implement the transitions for one state, or for the inverse of Qmap
// (in RFA's, LBFA's, and RBFA's).

class Trans : protected TransImpl {
    public:
        // Constructors, destructors, operator=:
        // Assume that delete [] 0 is okay.
        inline Trans();
        
        // Copy constructor allocates more memory. Should use (use-counting for
        // efficiency.
        inline Trans( const Trans& r );

        // operator=() must copy the memory.
        inline const Trans& operator=( const Trans& r );

        // Some member functions for making transitions:
        // Map a char to the corresponding StateSet.
        StateSet operator[]( const char a ) const;

        // Map a CharRange to the corresponding StateSet
        // assuming that the CharRange is entirely contained in the label
        // of a transition.
        StateSet range_transition( const CharRange a ) const;

        // What are all of the transitions in *this?
        inline CRSet out_labels() const;

        // What are all transition labels into StateSet r?
        inline CRSet labels_into( const StateSet& r ) const;

        // Some special member functions:
        // Clear out all prev. transitions, and zero the domain.
        inline void reincarnate();

        // The range of States that can be transitioned to.
        inline int range() const;

        // Change the range of States that can be transitioned to.
        // This is used in determining the domain() of the StateSet's (which
        // are destinations of transitions).
        inline void set_range( const int r );

        // Add one more transition to the set.
        inline Trans& add_transition( const CharRange a, const State q );

        // Do normal set union.
        Trans& set_union( const Trans& r );

        // Incorporate another Trans, while renaming all of the states.
        Trans& disjointing_union( const Trans& r );

        // Rename all of the States (that are destinations of some transition)
        // such that none of them fall in the range [0,r).
        Trans& st_rename( const int r );

        // Output the transitions.
private:

// Implementation details:
// The domain() of the associated StatePool.
int destination_range;

// Some inline members:
inline Trans::Trans() {
    TransImpl(),
    destination_range( 0 ) {
        assert( class_invariant() );
    }
}

inline Trans::Trans( const Trans& r ) :
    TransImpl( (TransImpl&)r ),
    destination_range( r.destination_range ) {
        assert( class_invariant() );
    }

inline const Trans& Trans::operator= ( const Trans& r ) {
    assert( class_invariant() );
    assert( r.class_invariant() );
    TransImpl::operator= ( (TransImpl&)r );
    destination_range = r.destination_range;
    assert( class_invariant() );
    return( *this );
}

inline CRSet Trans::out_labels() const {
    assert( class_invariant() );
    return( TransImpl::out_labels() );
}

inline CRSet Trans::labels_into( const StateSet& r ) const {
    assert( class_invariant() );
    return( TransImpl::labels_into( r ) );
}

inline void Trans::reincarnate() {
    assert( class_invariant() );
    TransImpl::reincarnate();
    assert( class_invariant() );
}

inline int Trans::range() const {
    assert( class_invariant() );
    return( destination_range );
}

inline void Trans::set_range( const int r ) {
    assert( class_invariant() );
    destination_range = r;
    assert( class_invariant() );
}

inline Trans& Trans::add_transition( const CharRange a, const State q ) {
    assert( class_invariant() );
    TransImpl::add_transition( a, q );
    assert( class_invariant() );
}
return( *this );

// Maintain the class invariant.
inline int Trans::class_invariant() const {
    auto int ret = 0;
    auto int i;
    for( i = 0; (i < in_use) && ret; i++ ) {
        ret = (0 <= transitions( i ).transition_destination)
            && (transitions( i ).transition_destination < destination_range);
    }
    return( ret );
}
#endif

Implementation: Trans inherits from TransImpl for implementation. It also maintains the range, as an integer. Most member functions are simply calls to the corresponding TransImpl member.

Performance: See the base class TransImpl.
transitions( i + in_use) = r.transitions( i );
}
in_use += r.in_use;
}
assert( class_invariant() );
return( *this );
}

Trans& Trans::disjointing_union( const Trans& r ) {
assert( class_invariant() );
// Don't do any useless work.
if( r.in_use != 0 ) {
ensure_min_size( in_use + r.in_use );
assert( howmany >= in_use + r.in_use );
auto int i;
for( i = 0; i < r.in_use; i++ ) {
transitions( i + in_use ).transition_label =
r.transitions( i ).transition_label;
transitions( i + in_use ).transition_destination =
r.transitions( i ).transition_destination + destination_range;
}
in_use += r.in_use;
destination_range += r.destination_range;
}
assert( class_invariant() );
return( *this );
}

// Rename all states in this Trans, so that they don't clash with
// those in the range [0,r).
Trans& Trans::sr_rename( const int r ) {
assert( class_invariant() );
// Don't do anything useless:
if( r != 0 ) {
auto int i;
for( i = 0; i < in_use; i++ ) {
transitions( i ).transition_destination += r;
}
destination_range += r;
}
assert( class_invariant() );
return( *this );
}

ostream& operator<<( ostream& os, const Trans& r ) {
assert( r.class_invariant() );
return( os << (TransImpl&)r );
}

Implementation class: DTrans

Files: dtrans.h, dtrans.cpp

Uses: CharRange, CRSet, State, StateSet, TransImpl, TransPair

Description: A DTrans is a set of TransPairs, with one restriction: the transition labels (CharRanges) are pairwise disjoint. (They are pairwise disjoint, since DTrans is used to implement deterministic transition functions.) The client must ensure that only transitions with disjoint labels are added. Member functions are provided to compute the destination of a transition, on a particular character or CharRange, returning a State (which is Invalid if there is no applicable transition). A State is returned (instead of a StateSet), since DTrans implement deterministic transition sets. A member function computes the set of all transition labels,
returning a \textit{CRSet}. Another member takes a \textit{StateSet} and returns the set of all transition labels on transitions with the destination in the \textit{StateSet}.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
// Revision: 1.2 $
// $Date: 1994/08/15 14:00:38 $
 ifndef DTRANS_H
 define DTRANS_H

#include "charrang.h"
#include "crset.h"
#include "state.h"
#include "stateset.h"
#include "tr-pair.h"
#include "tr-impl.h"
#include <assert.h>
#include <iostream.h>

// Implement a DFA's transition function for one State.
// Map a char to a unique next State, using TransImpl

class DTrans : protected TransImpl {
 public:

 // Constructors, destructors, operator=

 // By default, don't introduce any transitions.
 inline DTrans();

 // Copy constructor does a dynamic memory copy.
 inline DTrans( const DTrans& r );

 inline const DTrans& operator=( const DTrans& r );

 // Normal member functions:

 // Map a char to the unique next state.
 State operator[]( const char a ) const;

 // Map a CharRange to the corresponding State
 // assuming that the CharRange is entirely contained in the label
 // of a transition.
 State range_transition( const CharRange a ) const;

 // What are the labels of transitions out of *this.
 inline CRSet out_labels() const;

 // What are all transition labels into StateSet r?
 inline CRSet labels_into( const StateSet& r ) const;

 // Is there a valid out-transition on a?
 int valid_out_transition( const CharRange a ) const;

 // What is the range (States) of this map?
 // return a StateSet with domain dom.
 StateSet range( int dom ) const;

 // Special member functions:

 // Recycle this entire structure.
 inline void reincarnate();

 // Create a new out-transition.
 inline DTrans& add_transition( const CharRange a, const State q );

 friend ostream& operator<<( ostream& os, const DTrans& r );
```
inline int class_invariant() const;

// Inlines (mostly calling the base class):
inline DTrans::DTrans() :
    TransImpl() {
    assert( class_invariant() );
}

inline DTrans::DTrans( const DTrans& r ) :
    TransImpl( (TransImpl&)r ) {
    assert( class_invariant() );
}

inline const DTrans& DTrans::operator=( const DTrans& r ) {
    assert( class_invariant() );
    assert( r.class_invariant() );
    TransImpl::operator=( (TransImpl&)r );
    assert( class_invariant() );
    return( *this );
}

inline CRSet DTrans::out_labels() const {
    assert( class_invariant() );
    return( TransImpl::out_labels() );
}

inline CRSet DTrans::labels_into( const StateSet& r ) const {
    assert( class_invariant() );
    return( TransImpl::labels_into( r ) );
}

inline void DTrans::reincarnate() {
    assert( class_invariant() );
    TransImpl::reincarnate();
}

inline DTrans& DTrans::add_transition( const CharRange a, const State q ) {
    assert( class_invariant() );
    TransImpl::add_transition( a, q );
    return( *this );
}

inline int DTrans::class_invariant() const {
    // Should also check that all transitions are on different symbols.
    return( TransImpl::class_invariant() );
}

#endif

Implementation: DTrans inherits from TransImpl for implementation. Most member functions are simply calls to the corresponding TransImpl member.

Performance: See the base class TransImpl.
// Take first valid transition.
auto int i;
for( i = 0; i < in_use; i++ ) {
    if( transitions( i ).transition_label.contains( a ) ) {
        return( transitions( i ).transition_destination );
    }
}
assert( class_invariant() );
return( Invalid );

State DTrans::range_transition( const CharRange a ) const {
    assert( class_invariant() );
    // Take first valid transition.
    auto int i;
    for( i = 0; i < in_use; i++ ) {
        if( a <= transitions( i ).transition_label ) {
            return( transitions( i ).transition_destination );
        }
    }
    assert( class_invariant() );
    return( Invalid );
}

int DTrans::valid_out_transition( const CharRange a ) const {
    assert( class_invariant() );
    auto int i;
    for( i = 0; i < in_use; i++ ) {
        if( a <= transitions( i ).transition_label ) {
            return( 1 );
        }
    }
    assert( class_invariant() );
    return( 0 );
}

StateSet DTrans::range( int dom ) const {
    assert( class_invariant() );
    auto StateSet result;
    result.set_domain( dom );
    auto int i;
    for( i = 0; i < in_use; i++ ) {
        result.add( transitions( i ).transition_destination );
    }
    assert( class_invariant() );
    return( result );
}

ostream& operator<<( ostream& os, const DTrans& r ) {
    assert( r.class_invariant() );
    return( os << (TransImpl&)r );
}
6 Relations

Implementation class: StateRel

Files: staterel.h, staterel.cpp

Uses: State, StateSet, StateTo

Description: A StateRel is a binary relation on States. The class is used in the implementation of the ε-transition relation for class FA [Wat93a, Definition 2.1] and the follow relation [Wat93a, Definition 4.24] in classes RFA, LBFA and RBFA. Many relation operators are available, including taking the image of a State or a StateSet, and the star-closure of a StateSet. In order to easily construct StateRels, a member function union_cross is provided, which performs the following operation (where l, r are either States or StateSets):

\[ \ast \text{this} := \ast \text{this} \cup (l \times r) \]

Standard union is available, as is disjointing_union which operates analogously to the member function in StateSet and StateTo (incoming States are renamed to avoid a collision). As with StateSet, the domain must be explicitly maintained by the client. Those member functions which take a StateSet or StateRel as parameter expect the parameter to have the same domain as \( \ast \text{this} \).

```cpp
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:36 $
#ifndef STATEREL_H
#define STATEREL_H

#include "state.h"
#include "stateto.h"
#include "stateset.h"
#include "assert.h"
#include <iostream.h>

// Implement binary relations on States. This is most often used for epsilon transitions
// and follow relations.

class StateRel : protected StateTo<StateSet> { 
public:
    // Constructors, destructors, operator=:
    inline StateRel();
    inline StateRel( const StateRel& r );
    inline const StateRel& operator=( const StateRel& r );

    // Some relational operators:
    inline StateSet image( const StateSet& r ) const;
    inline StateSet closure( const StateSet& r ) const;
};
```
// Some functions updating *this:

// Member functions union_cross(A, B) makes *this the union (relation-wise) of *this with A times B (Cartesian cross product).
inline StateRel& union_cross( State p, State q );
inline StateRel& union_cross( State st, const StateSet& S );
StateRel& union_cross( const StateSet& S, State st );
StateRel& union_cross( const StateSet& A, const StateSet& B );

// Remove a pair of States from the relation.
inline StateRel& remove_pair( const State p, const State q );
StateRel& remove_pairs( const StateSet& P, const StateSet& Q );

// Clear out this relation, without changing the domain.
void clear();

// Perform normal union of two relations.
StateRel& set_union( const StateRel& r );

// Some domain members:

// What is the domain of this relation.
inline int domain() const;

// Change the domain of this relation.
void set_domain( const int r );

// Recycle this entire relation.
void reincarnate();

// Union relation r into *this, while adjusting r.
StateRel& disjointing_union( const StateRel& r );

// Some special members:

friend ostream& operator<<( ostream& os, const StateRel& r );

inline int class_invariant() const;
inline StateRel::StateRel( const StateRel& r ) {
    StateTo<StateSet>::operator=( (StateTo<StateSet>&)r );
    assert( class_invariant() );
    return( *this );
}

inline const StateSet& StateRel::image( const State r ) const {
    assert( class_invariant() );
    assert( 0 <= r && r < domain() );
    return( lookup( r ) );
}
inline int StateRel::domain() const {
    return( StateTo<StateSet>::domain() );
}

inline StateRel& StateRel::union_cross( State p, State q ) {
    assert( class_invariant() );
    assert( ( 0 <= p ) && ( p < domain() ) );
    assert( ( 0 <= q ) && ( q < domain() ) );
    map( p ).add( q );
    assert( class_invariant() );
    return( *this );
}

// Map a st also to StateSet S.
inline StateRel& StateRel::union_cross( State st, const StateSet& S ) {
    assert( class_invariant() );
    assert( S.class_invariant() );
    assert( ( 0 <= st ) && ( st < domain() ) && (S.domain() == domain()) );
    map( st ).set_union( S );
    assert( class_invariant() );
    return( *this );
}

inline StateRel& StateRel::remove_pair( const State p, const State q ) {
    assert( class_invariant() );
    assert( ( 0 <= p ) && ( p < domain() ) );
    assert( ( 0 <= q ) && ( q < domain() ) );
    map( p ).remove( q );
    map( q ).remove( p );
    assert( class_invariant() );
    return( *this );
}

inline int StateRel::class_invariant() const {
    // First, we must satisfy the base class_invariant().
    auto int ret( StateTo<StateSet>::class_invariant() );
    auto int i;
    for( i = 0; (i < domain()) && ret; i++ ) {
        ret = ret && lookup( i ).class_invariant()
        && (lookup( i ).domain() == domain());
    }
    return( ret );
}

#endif

Implementation: StateRel inherits for implementation from StateTo<StateSet>. Many member functions are simply calls to the corresponding member of StateTo. Member functions such as reincarnate first reincarnates all of the StateSets, followed by the StateTo.
for ( r.iter_start( st ); r.iter_end( st ); r.iter_next( st ) ) {
    result.set_union( lookup( st ) );
}
return( result );
}

StateSet StateRel::closure( const StateSet& r ) const {
assert( class_invariant() );
assert( r.class_invariant() );
assert( r.domain() == domain() );

// Use an iterative method to compute the Kleene closure.
auto StateSet result( r );

auto StateSet intermediate( image( r ) );
assert( intermediate.domain() == result.domain() );
while( !result.contains( intermediate ) ) {
    result.set_union( intermediate );
    intermediate = image( result );
}
return( result );
}

// Map all members of S to st as well.
StateRel& StateRel::union_cross( const StateSet& S, State st ) {
assert( class_invariant() );
assert( S.class_invariant() );
assert( (S.domain() == domain()) && (0 <= st) && (st < domain()) );
auto State i;
for( S.iter_start( i ); S.iter_end( i ); S.iter_next( i ) ) {
    map( i ).add( st );
}
assert( class_invariant() );
return( *this );
}

// This could probably have made use of union_cross(State,StateSet&).
StateRel& StateRel::union_cross( const StateSet& A, const StateSet& B ) {
assert( class_invariant() );
assert( A.class_invariant() );
assert( (A.domain() == domain()) && (B.domain() == domain()) );
auto State i;
for( A.iter_start( i ); A.iter_end( i ); A.iter_next( i ) ) {
    map( i ).set_union( B );
}
assert( class_invariant() );
return( *this );
}

StateRel& StateRel::remove_pairs( const StateSet& P, const StateSet& Q ) {
assert( class_invariant() );
assert( P.domain() == domain() );
assert( Q.domain() == domain() );
auto State i;
for( P.iter_start( i ); P.iter_end( i ); P.iter_next( i ) ) {
    map( i ).remove( Q );
}
assert( class_invariant() );
return( *this );
}

StateRel& StateRel::set_union( const StateRel& r ) {
assert( class_invariant() && r.class_invariant() );
assert( domain() == r.domain() );
auto State i;
for( i = 0; i < r.domain(); i++ ) {
map( i ).set_domain( r.lookup( i ) );
// Could also have been done with
// union_cross( i, r.lookup( i ) );
assert( class_invariant() );
return( *this );

void StateRel::set_domain( const int r ) {
    assert( class_invariant() );
    assert( r >= domain() );
    StateTo<StateSet>::set_domain( r );
    auto int i;
    for( i = 0; i < domain(); i++ ) {
        map( i ).set_domain( r );
    }
    assert( class_invariant() );
}

void StateRel::clear() {
    assert( class_invariant() );
    auto int i;
    for( i = 0; i < domain(); i++ ) {
        map( i ).clear();
    }
    assert( class_invariant() );
}

void StateRel::reincarnate() {
    assert( class_invariant() );
    auto int i;
    for( i = 0; i < domain(); i++ ) {
        map( i ).reincarnate();
    }
    StateTo<StateSet>::reincarnate();
    assert( class_invariant() );
}

StateRel& StateRel::disjointing_union( const StateRel& r ) {
    assert( class_invariant() & r.class_invariant() );
    auto int olddom( domain() );
    StateTo<StateSet>::disjointing_union( r );
    auto int i;
    // domain() is the new one, olddom is the old one:
    assert( domain() == olddom + r.domain() );
    // Just adjust the domains of those StateSet's that were already in *this.
    for( i = 0; i < olddom; i++ ) {
        map( i ).set_domain( domain() );
    }
    // Got to rename the incoming ones.
    for( i; i < domain(); i++ ) {
        map( i ).set_rename( olddom );
    }
    assert( class_invariant() );
    return( *this );
}

ostream& operator<<( ostream& os, const StateRel& r ) {
    assert( r.class_invariant() );
    return( os << (const StateTo<StateSet>& ) r );
}

Implementation class: SymRel
Files: symrel.h, symrel.cpp

Uses: State, StateSet, StateTo

Description: A SymRel is a binary symmetrical relation on States. They are used mainly in DFA minimization algorithms. Member functions are provided to add and remove pairs of States from the relation, as well as to test for membership in the relation.

```cpp
#include <assert.h>
#include <iostream.h>

class SymRel : protected StateRel {
public:
    // Constructors etc.
    inline SymRel();
    inline SymRel( const SymRel& r );
    inline const SymRel& operator=( const SymRel& r );

    // Some relation operators.
    // Make *this into the identity relation.
    SymRel& identity();

    // What is the image of a State under *this
    inline const StateSet& image( const State p ) const;

    // Add a pair of States.
    inline SymRel& add_pair( const State p, const State q );
    inline SymRel& add_pairs( const StateSet& P, const StateSet& Q );

    // Remove a pair of States.
    inline SymRel& remove_pair( const State p, const State q );
    inline SymRel& remove_pairs( const StateSet& P, const StateSet& Q );

    // Are a pair of States present?
    inline int contains_pair( const State p, const State q ) const;

    // Complement *this.
    SymRel& complement();

    // Some domain related members.
    inline int domain() const;
    void set_domain( const int r );

    // Special members.
    friend ostream& operator<<( ostream& os, const SymRel& r );
};
```
inline SymRel::SymRel() :
    StateRel() {
    assert( class_invariant() );
}

inline SymRel::SymRel( const SymRel& r ) :
    StateRel( (const StateRel &r) ) {
    assert( class_invariant() );
}

inline const SymRel& SymRel::operator=( const SymRel& r ) {
    assert( r.class_invariant() );
    StateRel::operator=( (const StateRel &r) );
    assert( class_invariant() );
    return( *this );
}

inline const StateSet& SymRel::image( const State p ) const {
    assert( class_invariant() );
    return( StateRel::image( p ) );
}

inline SymRel& SymRel::add_pair( const State p, const State q ) {
    assert( class_invariant() );
    StateRel::union_cross( p, q );
    StateRel::union_cross( q, p );
    assert( class_invariant() );
    return( *this );
}

inline SymRel& SymRel::add_pairs( const StateSet& P, const StateSet& Q ) {
    assert( class_invariant() );
    StateRel::union_cross( P, Q );
    StateRel::union_cross( Q, P );
    assert( class_invariant() );
    return( *this );
}

inline SymRel& SymRel::remove_pair( const State p, const State q ) {
    assert( class_invariant() );
    StateRel::remove_pair( p, q );
    StateRel::remove_pair( q, p );
    assert( class_invariant() );
    return( *this );
}

inline SymRel& SymRel::remove_pairs( const StateSet& P, const StateSet& Q ) {
    assert( class_invariant() );
    StateRel::remove_pairs( P, Q );
    StateRel::remove_pairs( Q, P );
    assert( class_invariant() );
    return( *this );
}

inline int SymRel::contains_pair( const State p, const State q ) const {
    assert( class_invariant() );
    return( StateRel::image( p ).contains( q ) );
}

inline int SymRel::domain() const {
    assert( class_invariant() );
    return( StateRel::domain() );
}

inline void SymRel::set_domain( const int r ) {
    StateRel::set_domain( r );
    assert( class_invariant() );
}
Implementation: SymRel inherits for implementation from StateRel. All of the member functions simply call through to StateRel.

Implementation class: StateEqRel

Files: st-eqrel.h, st-eqrel.cpp

Uses: State, StateSet, StateTo

Description: A StateEqRel is a binary equivalence relation on States. They are used mainly in DFA minimization algorithms. The argumentless constructor leaves the StateEqRel as the total relation. The identity member function makes the StateEqRel the identity relation. As with many other classes related to sets of States, the domain of the StateEqRel must be managed by the client. Member functions are available for determining if two States are equivalent, for splitting an equivalence class, and for determining the equivalence class (as a State) of a State. Each equivalence class has a unique representative; if an equivalence class is split, one of the (at most two) resulting classes is guaranteed to have, as its unique
representative, the representative of the original class. Iterator member functions can be used to iterate over the set of representatives, thereby iterating over the set of equivalence classes.

```cpp
#include "stateto.h"
#include <cassert.h>
#include <iostream.h>

class StateEqRel : protected StateTo<StateSet *> {
public:
    // Some constructors etc:
    // Construct the total eq. relation of domain r.
    StateEqRel( const int r );

    inline StateEqRel( const StateEqRel& r );
    inline const StateEqRel& operator=( const StateEqRel& r );

    // Some members for changing the relation:
    // Make two States equivalent:
    StateEqRel& equivalize( const State p, const State q );

    // Split an equivalence class into two (assuming that r is entirely contained
    // in a class):
    StateEqRel& split( const StateSet& r );

    // Make *this the identity relation:
    StateEqRel& identity();

    // Basic access members:
    // Are States p and q equivalent?
    inline int equivalent( const State p, const State q ) const;

    // What is the equivalence class [p]?
    inline const StateSet& equiv_class( const State p ) const;

    // What is the unique representative of eq. class [p]?
    inline State eq_class_representative( const State p ) const;

    // What is the set of representatives of equivalence classes of *this?
    StateSet representatives() const;

    // Special members:
    // Domain setting stuff:
    void set_domain( int r );
    inline int domain() const;

    friend ostream& operator<<( ostream& os, const StateEqRel& r );
};
```
inline int class_invariant() const;

inline StateEqRel::StateEqRel( const StateEqRel& r ) {
    StateTo<StateSet*>( r ) {
    assert( class_invariantO );
}

inline const StateEqRel& StateEqRel::operator=( const StateEqRel& r ) {
    StateTo<StateSet*>( r ) {
        assert( class_invariantO );
        assert( r.class_invariantO );
        StateTo<StateSet*>( operator=( r );
        assert( class_invariantO );
        return( *this );
}

inline int StateEqRel::equivalent( const State p, const State q ) const {
    assert( class_invariantO );
    assert( (0 <= p) & (p < domainO) );
    assert( (0 <= q) & (q < domainO) );
    return( lookup( p ) == lookup( q ) );
}

inline const StateSet& StateEqRel::equiv_class( const State p ) const {
    assert( class_invariantO );
    assert( (0 <= p) & (p < domainO) );
    return( *lookup( p ) );
}

inline State StateEqRel::eq_class_representative( const State p ) const {
    assert( class_invariantO );
    assert( (0 <= p) & (p < domainO) );
    return( lookup( p )->smallestO );
}

inline int StateEqRel::domainO const {
    return( StateTo<StateSet*>( domainO ) );
}

inline int StateEqRel::class_invariantO const {
    auto int result( 1 );
    auto State i;
    for( i = 0; i < domainO & result; i++ ) {
        result = (domainO == lookup( i ) ->domainO);
        result = result & lookup( i )->class_invariantO;
        // it's eq. class should contain i itself.
        result = result & lookup( i )->contains( i );
        // And that's all that lookup( i ) should contain.
        // Iterate over lookup( i ) and check that.
        auto State j;
        for( lookup( i )->iter_start( j );
            lookup( i )->iter_end( j ) & result;
            lookup( i )->iter_next( j ) ) {
            result = (lookup( i ) == lookup( j ));
        }
    return( result );
}

#endif

**Implementation:** StateEqRel inherits for implementation from StateTo<StateSet*>. Two equivalent States are mapped by the StateTo to pointers to the same StateSet.

/* (c) Copyright 1994 by Bruce W. Watson */
// Construct the total eq. relation of domain r.
StateEqRel::StateEqRel( const int r ) :
    StateTo<SetState *( ) ( ) { StateTo<SetState *( )::set_domain( r ) ;
    // Now construct a SetState representing the total relation.
    auto StateSet = const t( new StateSet );
t->set_domain( r );
t->complement();
auto State p;
for( p = 0; p < r; p++ ) {
    StateTo<SetState *( )::map( p ) = t;
}
    // Do not delete t!!
    assert( class_invariant() );
}
StateEqRel& StateEqRel::equivolize( const State p, const State q ) { assert( class_invariant() ); // Don't do anything needless:
if( !equivalent( p, q ) ) {
    // This is dangerous if they point to the same thing.
    assert( lookup( p ) != lookup( q ) );
    // Include q's eq. class in p's
    map( p )->set_union( *lookup( q ) );
    // Get q's eq. class relating to the p's.
    auto StateSet = oldq( lookup( q ) );
    auto StateSet = newp( lookup( p ) );
    assert( oldq != newp );
    auto State i;
    for( oldq->iter_start( i ); !oldq->iter_end( i ); oldq->iter_next( i ) ) {
        map( i ) = newp;
    }
    assert( equivalent( p, q ) );
delete oldq;
    assert( lookup( p ) == lookup( q ) );
    assert( class_invariant() );
    return( *this );
}
StateEqRel& StateEqRel::split( const StateSet& r ) { assert( class_invariant() );
assert( domain() == r.domain() );
    // Only split it if there's actually some splitting to do.
    // Choose first State in r for starters.
    auto State i;
r.iter_start( i );
    // Only do the splitting if r is wholly contained in the eq. class of it's
    // smallest element, and if the splitting will actually produce a new eq.
    // class.
    if( lookup( i )->contains( r ) && *lookup( i ) != r ) {
        // Split it.
        // Make all of not( r )'s States equivalent.
        map( i )->remove( r );
        // Make all of r's States equivalent.
// Build a new StateSet for the new class.
auto StateSet*n( new StateSet( r ) );
// i is already the first State in r.
for( ; r.iter_end( i ); r.iter_next( i ) ) {
    map( i ) = n;
}
assert( class_invariant() );
return( *this );

StateEqRel& StateEqRel::identity() {  
    assert( class_invariant() );
    // We'll need the representatives later.
    auto StateSet repr( representatives() );
    // Wipe out all previous stuff.
    auto State st;
    for( st = 0; st < domain(); st++ ) {
        // There may be something to wipe out here.
        // To avoid double delete [] of the same memory, only do the
        // deletion when st is the representative of it's eq. class.
        if( repr.contains( st ) ) {
            
        // Assign the new StateSet.
        map( st ) = new StateSet;
        // It's the emptyset, and set the domain.
        lookup( st )->set_domain( domain() );
        assert( lookup( st )->empty() );
        lookup( st )->add( st );
        }
        assert( class_invariant() );
        return( *this );
    }
}

StateSet StateEqRel::representatives() const {
    assert( class_invariant() );
    // Keep track of the States to consider.
    auto StateSet consider;
    consider.set_domain( domain() );
    consider.complement();
    auto StateSet ret;
    ret.set_domain( domain() );
    auto State st;
    // Iterate over all States that must be considered.
    // starting with all of the States.
    for( consider.iter_start( st ); !consider.iter_end( st ); consider.iter_next( st ) ) {
        ret.add( eq_class_representative( st ) );
        // No need to look at the rest of eq. class {st}.
        consider.remove( equiv_class( st ) );
        }
    assert( class_invariant() );
    return( ret );
}

void StateEqRel::set_domain( int r ) {  
    assert( class_invariant() );
    StateTo<StateSet *>::set_domain( r );
    assert( class_invariant() );
}
ostream& operator<<( ostream& os, const StateEqRel& r ) {
    assert( r.class_invariant() );
    os << "StateEqRel\n";
    // Print out all of the equivalence classes (each only once).
    auto State st;
    for( st = 0; st < r.domain(); st++ ) {
        // If i is the representative of its eq. class, then print the class.
        if( st == r.eq_class_representative( st ) ) {
            os << *r.lookup( st ) << \n;
        }
    }
    return( os );
}

**Implementation class: TransRel**

**Files:** transrel.h, transrel.cpp

**Uses:** CharRange, CRSet, State, StateSet, StateTo, Trans

**Description:** A TransRel maps a StateSet and a character (or a CharRange) to a StateSet. It is used to implement the transition relation in the class FA (see [Wat93a, Definition 2.1]). The responsibility of maintaining the domain of the relation lies with the client. Transitions can be added, but not removed.
// Transitioning on a CharRange? (Same idea as above.)
StateSet transition_on_range( const StateSet& r, const CharRange a ) const;

// On which labels can we transition?
CRSet out_labels( const StateSet& r ) const;

// Some functions updating *this:
inline TransRel& add_transition( const State p, const CharRange r, const State q );

// Some domain related members:

// What is the domain of this relation.
inline int domain() const;

// Change the domain of this relation.
void set_domain( const int r );

// Recycle this entire structure.
void reincarnate();

// Union relation r into *this, while adjusting r.
TransRel& disjointing_union( const TransRel& r );

// Some special members:
friend ostream& operator<<( ostream& os, const TransRel& r );
inline int class_invariant() const;

inline TransRel::TransRel() :
    StateTo<Trans>() {
    assert( class_invariant() );
}

inline TransRel::TransRel( const TransRel& r ) :
    StateTo<Trans>( StateTo<Trans>& r ) {
    assert( class_invariant() );
}

inline const TransRel& TransRel::operator=( const TransRel& r ) {
    assert( r.class_invariant() );
   // Call back to the base class.
    StateTo<Trans>::operator=( (const StateTo<Trans>&) r );
    assert( class_invariant() );
    return( *this );
}

inline int TransRel::domain() const {
    return( StateTo<Trans>::domain() );
}

inline TransRel& TransRel::add_transition( const State p, const CharRange r, const State q ) {
    assert( class_invariant() );
    assert( (0 <= p) && (p < domain()) );
    assert( (0 <= q) && (q < domain()) );
    map( p ).add_transition( r, q );
    assert( class_invariant() );
    return( *this );
}

inline int TransRel::class_invariant() const {
   // First, we must satisfy the base class_invariant().
auto int res( StateTo<Trans>::class.invariant() );
auto int i;
for( i = 0; (i < domain()) && res; i++ ) {
    res = lookup( i ).class.invariant() && (lookup( i ).range() == domain());
} return( res );
}
#endif

Implementation: TransRel inherits for implementation from StateTo<Trans>. Many of the member functions simply call the corresponding members functions of StateTo or Trans.
map( i ).set_range( r );
} assert( class_invariant() );
}

void TransRel::reincarnate() {
    assert( class_invariant() );
    auto int i;
    // First, reincarnate() all of the components before *this.
    for( i = 0; i < domain(); i++ ) {
        map( i ).reincarnate();
    }
    StateTo<Trans>::reincarnate();
    assert( class_invariant() );
}

TransRel& TransRel::disjointing_union( const TransRel& r ) {
    assert( class_invariant() && r.class_invariant() );
    auto int olddom( domain() );
    StateTo<Trans>::disjointing_union( r );
    assert( StateTo<Trans>::domain() == r.domain() + olddom );
    auto int i;
    for( i = 0; i < olddom; i++ ) {
        map( i ).set_range( domain() );
    }
    for( ; i < domain(); i++ ) {
        map( i ).at.rename( olddom );
    }
    assert( class_invariant() );
    return( *this );
}

ostream& operator<<( ostream& os, const TransRel& r ) {
    assert( r.class_invariant() );
    return( os << (const StateTo<Trans>&)r );
}

Implementation class: DTransRel

Files: dtransre.h, dtransre.cpp

Uses: CharRange, CRSet, DTrans, State, StateSet, StateTo

Description: A DTransRel maps a State and a character (or a CharRange) to a State. It is used to implement the deterministic transition relation in the class DFA (see [Wat93a, Property 2.25]). The domain of the relation must be maintained explicitly by the client. Transitions can be added to the relation, but not removed. The client must ensure that the relation remains deterministic.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:39 $
#ifndef DTRANSREL_H
#define DTRANSREL_H
#include "state.h"
#include "stateset.h"
#include "stateto.h"
#include "dtrans.h"
#include "crset.h"
#include <assert.h>
#include <iostream.h>
// Implement a deterministic transition relation, as a function from States time
// char to State. This is used for transition relations in DFA's.

class DTransRel : protected StateTo<DTrans> { public:  // Constructors, destructors, operator=:
    // Argument-less constructor:
inline DTransRel();

    inline DTransRel( const DTransRel& r );
    // Default destructor is okay:
inline const DTransRel& operator=( const DTransRel& r );

    // Some relational operators:
    // Compute the image of r, and a under *this,
inline State image( const State r, const char a ) const;
    // Compute the image of r, and CharRange a under *this.
inline State transition_on_range( const State r, const CharRange a ) const;
    // Compute the reverse transition on a range under *this:
    StateSet reverse_transition( const State r, const CharRange a ) const;
    // What are the transition labels between some State r and StateSet s?
inline CRSet labels_between( const State r, const StateSet& s ) const;
    // Given State r, what are the labels on transitions out of r?
inline CRSet out_labels( const State r ) const;
    // What are all States reverse reachable from r?
    StateSet reverse_closure( const StateSet& r ) const;

    // Some functions updating *this:
inline DTransRel& add_transition( const State p, const CharRange a, const State q );

    // Some domain members:
    // What is the domain of this relation.
inline int domain() const;
    // Change the domain of this relation.
inline void set_domain( const int r );
    // Recycle this entire structure.
    void reincarnate();

    // Some special members:
    friend ostream& operator<<( ostream& os, const DTransRel& r );
inline int class_invariant() const;
};

inline DTransRel::DTransRel() :
    StateTo<DTrans>()
{
    assert( class_invariant() );
}
inline DTransRel::DTransRel( const DTransRel& r ) {
    StateTo<DTrans>( (StateTo<DTrans>&)r ) { assert( class_invariant() ); }
}

inline const DTransRel& DTransRel::operator=( const DTransRel& r ) {
    assert( r.class_invariant() ); // Call back to the base class.
    StateTo<DTrans>::operator=( (const StateTo<DTrans>&) r );
    assert( class_invariant() );
    return( *this );
}

inline State DTransRel::image( const State r, const char a ) const {
    assert( class_invariant() );
    assert( 0 <= r && r < domain() );
    return( lookup( r )[a] );
}

inline State DTransRel::transition_on_range( const State r, const CharRange a ) const {
    assert( class_invariant() );
    assert( 0 <= r && r < domain() );
    return( lookup( r ).range_transition( a ) );
}

inline CRSet DTransRel::labels_between( const State r, const StateSet& s ) const {
    assert( class_invariant() );
    assert( s.class_invariant() );
    assert( domain() == s.domain() );
    assert( 0 <= r && r <= domain() );
    return( lookup( r ).labels_into( s ) );
}

inline CRSet DTransRel::out_labels( const State r ) const {
    assert( class_invariant() );
    return( lookup( r ).out_labels() );
}

inline DTransRel& DTransRel::add_transition( const State p, const CharRange a, const State q ) {
    assert( class_invariant() );
    map( p ).add_transition( a, q );
    assert( class_invariant() );
    return( *this );
}

inline int DTransRel::domain() const {
    return( StateTo<DTrans>::domain() );
}

inline void DTransRel::set_domain( const int r ) {
    assert( class_invariant() );
    StateTo<DTrans>::set_domain( r );
    assert( class_invariant() );
}

inline int DTransRel::class_invariant() const {
    // First, we must satisfy the base class_invariant().
    auto int i( StateTo<DTrans>::class_invariant() );
    auto int k;
    for( k = 0; (k < domain()) && i; k++ ) {
        i = i && lookup( k ).class_invariant();
    }
    return( i );
}
inline ostream& operator<<( ostream& os, const DTransRel& r ) {
    assert( r.class_invariant() );
    return( operator<<( os, (const StateTo<DTrans>&)r ) );
}

#endif

Implementation: DTransRel inherits for implementation from StateTo<DTrans>. Many of the member functions are simply calls to the members of StateTo or DTrans.

*/ (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 13:59:58 $
#include "dtransre.h"

StateSet DTransRel::reverse_transition( const State r, const CharRange a ) const {
    assert( class_invariant() );
    auto StateSet ret;
    ret.set_domain( domain() );
    auto State p;
    // Iterate over all of the States, and see which have transitions to r.
    for( p = 0; p < domain(); p++ ) {
        if( transition_on_range( p, a ) == r ) {
            ret.add( p );
        }
    }
    return( ret );
}

StateSet DTransRel::reverse_closure( const StateSet& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    assert( domain() == r.domain() );
    auto StateSet result( r );
    auto StateSet intermediate;
    intermediate.set_domain( domain() );
    assert( intermediate.empty() );
    do {
        result.set_union( intermediate );
        intermediate.clear();
        // Go through the State's to see which can reach set result on
        // some transition.
        auto State st;
        for( st = 0; st < domain(); st++ ) {
            if( result.not_disjoint( lookup( st ), range( domain() ) ) ) {  
                intermediate.add( st );
            }
        }
    } while( !result.contains( intermediate ) );
    return( result );
}

void DTransRel::reincarnate() {
    assert( class_invariant() );
    // Don't reset the domain()
    auto int i;
for( i = 0; i < domain(); i++ ) {
    map( i ).reincarnate();
}
StateTo<DTrans>::reincarnate();
assert( class_invariant() );
Part II
Regular expressions and \(\Sigma\)-algebras

7 Regular expressions

Implementation class: \(REops\)

Files: reops.h

Uses:

Description: The regular operators (of the \(\Sigma\)-algebra — see class \(Reg\) or [Wat93a, Definition 3.12]) are encoded as elements of an enumeration. These are usually stored in a type-field in regular expressions. They play an important role in computing the homomorphic (\(\Sigma\)-algebra) image of a regular expression.

Implementation: \(REops\) is defined as an \texttt{enum}.

```
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:47 $
#ifndef REOPS_H
#define REOPS_H

enum REops {
    EPSILON,
    EMPTY,
    SYMBOL,
    OR,
    CONCAT,
    STAR,
    PLUS,
    QUESTION
};
#endif
```

Implementation class: \(RE\)

Files: re.h, re.cpp

Uses: CharRange, CRSet, REops

Description: An \(RE\) is a regular expression (see [Wat93a, Section 3] for the definition of regular expressions). The argumentless constructor constructs the regular expression \(\emptyset\) (the regular expression denoting the empty language). It is not possible to construct more complex regular expressions with the member functions (see the template class \(Reg<RE>\) for information on constructing regular expressions). Class \(RE\) is the implementation of the carrier set of the \(\Sigma\)-term algebra (an \(RE\) is a term in the \(\Sigma\)-term algebra).

A member function returns the operator type of the main (or root) operator of the regular expression. (The operator types are enumerated in \(REops\).) Other member functions can be used to determine additional information about the main (root) operator of the regular
expression: the associated CharRange (for a SYMBOL basis operator), and the subexpressions (for non-basis, binary and unary, operators). A very basic istream extraction (input) operator is provided, expecting the input to be a regular expression in prefix notation; the operator does little error checking.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:46 $
#include "re.h"
#define RE_H
#include "charrang.h"
#include "crset.h"
#include "reaps.h"
#include <cassert.h>
#include <iostream.h>

class RE {
public:
  // Some constructors, destructors, and operator=:
  // By default, create the RE denoting the empty language.
  RE();
  RE( const RE& r );
  virtual ~RE();
  const RE& operator=( const RE& r );

  // Some basic access member functions:
  // How many SYMBOL nodes in this regular expression?
  //   Mainly for use in constructing RFA's.
  int num_symbols() const;

  // How many operators in this RE?
  //   Used in ISImpl (the item set stuff).
  int num_operators() const;

  // What is the main operator of this regular expression?
  inline REops root_operator() const;

  // What is the CharRange of this RE, if it is a SYMBOL regular expression.
  inline CharRange symbol() const;

  // What is the left RE of this RE operator (if it is a higher operator).
  inline const RE& left_subexpr() const;

  // What is the right RE of this RE operator (if it a binary operator).
  inline const RE& right_subexpr() const;

  // Some derivatives (Brzozowski's) related member functions:
  // Does this accept epsilon?
  //   This is from Definition 3.20 and Property 3.21
  int Null() const;

  // What is the First of this?
  //   This is from Definition 4.60
```
CRSet First() const;

// Is this in similarity normal form (SNF)?
int in_snf() const;

// Put this into similarity normal form.
RE& snf();

// Reduce (optimize) this by removing useless information.
RE& reduce();

// What is the derivative of this (w.r.t. r)?
RE derivative( const CharRange& r ) const;

// Some ordering members (largely used in similarity and comparisons)
int ordering( const RE& r ) const;

// Some comparisons:
inline int operator==( const RE& r ) const;
inline int operator!=( const RE& r ) const;
inline int operator<( const RE& r ) const;
inline int operator<=( const RE& r ) const;
inline int operator>( const RE& r ) const;
inline int operator>=( const RE& r ) const;

// Some extras:
friend ostream& operator<<( ostream& os, const RE& r );
friend istream& operator>>( istream& is, RE& r );

inline int class_invariant() const;

protected:
// Some protected helpers, mainly for Reg<RE>:
inline void set_root_operator( REops r );
inline void set_symbol( const CharRange r );

// Make a copy of this in r
void shallow_copy( RE *const r ) const;

void reincarnate();

// Put this into OR normal form (ONF) (used in the snf functions)
RE& onf();

// Destroy node r, moving its data into this.
void assimilate_node( RE *const r );

// Some implementation details.
REops op;
RE *left, *right;
CharRange sym;
};

inline RE::RE() : op( EMPTY ),
  left( 0 ),
  right( 0 ) {
  assert( class_invariant() );
}

// Some inline operators:

inline REops RE::root_operator() const {
  return( op );
}
inline CharRange RE::symbol() const {
    assert( op == SYMBOL );
    return( sym );
}

// Assume that *this is a higher (non-basis) regular operator.
inline const RE& RE::left_subexpr() const {
    assert( (op != EMPTY) && (op != EPSILON) && (op != SYMBOL) );
    return( *left );
}

// Assume that *this is a binary regular operator.
inline const RE& RE::right_subexpr() const {
    assert( (op == OR) || (op == CONCAT) );
    return( *right );
}

inline void RE::set_root_operator( REops r ) {
    // No class assertion here, since *this is still being constructed.
    op = r;
}

inline void RE::set_symbol( const CharRange r ) {
    assert( op == SYMBOL );
    sym = r;
}

inline int RE::operator==( const RE& r ) const {
    return( ordering( r ) == 0 );
}

inline int RE::operator!=( const RE& r ) const {
    return( ordering( r ) != 0 );
}

inline int RE::operator<( const RE& r ) const {
    return( ordering( r ) < 0 );
}

inline int RE::operator<=( const RE& r ) const {
    return( ordering( r ) <= 0 );
}

inline int RE::operator>( const RE& r ) const {
    return( ordering( r ) > 0 );
}

inline int RE::operator>=( const RE& r ) const {
    return( ordering( r ) >= 0 );
}

inline int RE::class_invariant() const {
    switch( op ) {
    case EPSILON:
    case EMPTY:
        return( left == 0 && right == 0 );
    case SYMBOL:
        return( left == 0 && right == 0 );
    case OR:
    case CONCAT:
        return( left != 0 && right != 0
            && left_subexpr().class_invariant()
            && right_subexpr().class_invariant() );
    case STAR:
    case PLUS:
Implementation: Regular expressions are implemented as expression trees. The comparison of regular expressions is defined recursively and uses a depth-first traversal.

Performance: Use-counting could avoid the deep-tree copies that are performed. An RE could be stored as a prefix-form string, as in [RW93]; this could give some problems with the heavy use of members such as left_subexpr and right_subexpr.

```cpp
RE::RE( const RE& e ) :
    op( e.op ),
    right( 0 ) { // Only the right on purpose.
        assert( e.class_invariant() );

        switch( e.root_operator() ) {
            case EPSILON:  
                left = 0;
                break;
            case EMPTY:    
                left = 0;
                break;
            case SYMBOL:   
                left = 0;
                sym = e.sym;
                break;
            case OR:       
                right = new RE( e.right_subexpr() );
            case CONCAT:   
                right = new RE( e.right_subexpr() );
            case STAR:     
                case PLUS:   
                    default:   
                        // Should throw() something!
                        break;
                    break;
                case QUESTION: 
                    default:   
                        // Should throw() something!
                        break;
                    break;
            }  
        assert( class_invariant() );
    }

RE::RE() {
    delete left;
    delete right;
}

const RE& RE::operator=( const RE& e ) {
    op( e.op ),
    right( 0 ) { // Only the right on purpose.
        assert( e.class_invariant() );

        switch( e.root_operator() ) {
            case EPSILON:  
                left = 0;
                break;
            case EMPTY:    
                left = 0;
                break;
            case SYMBOL:   
                left = 0;
                sym = e.sym;
                break;
            case OR:       
                right = new RE( e.right_subexpr() );
            case CONCAT:   
                right = new RE( e.right_subexpr() );
            case STAR:     
                case PLUS:   
                    default:   
                        // Should throw() something!
                        break;
                    break;
                case QUESTION: 
                    default:   
                        // Should throw() something!
                        break;
                    break;
            }  
        assert( class_invariant() );
    }
```
assert( e.class invariant() );

right = 0;

switch( e.root_operator() ) {
    case EPSILON:
        left = 0;
        break;
    case EMPTY:
        left = 0;
    // In no other case is it safe to copy the sym.
        sym = e.sym;
        break;
    case SYMBOL:
        left = 0;
        break;
    case OR:
    case CONCAT:
        delete right;
        right = new RE( e.right_subexpr() );
    case STAR:
    case PLUS:
    case QUESTION:
        delete left;
        left = new RE( e.left_subexpr() );
        break;
}

assert( class_invariant() );
return( *this );

// How many symbols are there in *this RE?
int RE::num_symbols() const {
    auto int ret;
    switch( op ) {
        case EPSILON:
        case EMPTY:
        case SYMBOL:
            ret = 1;
            break;
        case OR:
        case CONCAT:
            ret = left->num_symbols() + right->num_symbols();
            break;
        case STAR:
        case PLUS:
        case QUESTION:
            ret = left->num_symbols();
            break;
    }
    return( ret );
}

// How many operators are there in *this RE?
int RE::num_operators() const {
    auto int ret;
    switch( op ) {
        case EPSILON:
        case EMPTY:
        case SYMBOL:
            ret = 1;
            break;
    }
}
break;
case OR:
case CONCAT:
    ret = left->num_operators() + right->num_operators() + 1;
    break;
case STAR:
case PLUS:
case QUESTION:
    ret = left->num_operators() + 1;
    break;
}
return( ret );

// Copy *this into *r
void RE::shallow_copy( RE *const r ) const {
    r->op = op;
    r->left = left;
    r->right = right;
    r->sym = sym;
}

void RE::reincarnate() {
    if( left != 0 ) {
        // This is a non-basic operator for reincarnation.
        // Delete what used to be there.
        delete left;
        left = 0;
        if( right != 0 ) {
            // This is a binary operator for reincarnation.
            delete right;
            right = 0;
        }
    }
    op = EMPTY;
    assert( class_invariant() );
}

// Output in prefix notation.
// Part of this could be REops, if enums could be used for overload resolution.
ostream& operator<<( ostream& as, const RE& r ) {
    switch( r.root_operator() ) {
    case EMPTY:
        as << '0';
        break;
    case EPSILON:
        as << '1';
        break;
    case SYMBOL:
        as << r.symbol();
        break;
    case OR:
        as << " | " << r.left_subexpr() << " " << r.right_subexpr();
        break;
    case CONCAT:
        as << " . " << r.left_subexpr() << " " << r.right_subexpr();
        break;
    case STAR:
        as << " * " << r.left_subexpr();
        break;
    case PLUS:
        as << " + " << r.left_subexpr();
        break;
    case QUESTION:
        as << " ? = " << r.left_subexpr();
        break;
    }
return( os );
}

// Input, in prefix notation. Not much error checking is done!
istream& operator>>( istream& is, RE& r ) {
    // Wipe out anything that used to be in r.
    delete r.left;
    delete r.right;
    // If something goes wrong try to leave r as the EMPTY regular expression.
    r.left = r.right = 0;
    r.op = EMPTY;

    auto char c;
    // It could be that there is nothing in the input.
    if( !(is >> c) ) {
        is.clear( ios::badbit | is.rdstate() );
    } else {
        switch( c ) {
            case '"':
                r.op = EPSILON;
                break;
            case '0':
                r.op = EMPTY;
                break;
            case '[':
                // This stuff should really be as the extraction operator
                // in class CharRange.
                is >> c;
                if( c != '"' ) {
                    cerr << "First CharRange incorrect\n";
                    is.clear( ios::badbit | is.rdstate() );
                } else {
                    // Input first character of the range.
                    is >> c;
                    auto char c2;
                    is >> c2;
                    if( c2 != '"' ) {
                        cerr << "Second CharRange not terminated properly\n";
                        is.clear( ios::badbit | is.rdstate() );
                    } else {
                        // Input first char. of second range.
                        is >> c2;
                        r.sym = CharRange( c, c2 );
                        r.op = SYMBOL;
                        is >> c;
                        if( c != '"' ) {
                            cerr << "Second CharRange not terminated properly\n";
                            is.clear( ios::badbit | is.rdstate() );
                        } else {
                            cerr << "Close block not found\n";
                            is.clear( ios::badbit | is.rdstate() );
                        }
                    }
                }
            case '\':
                is >> c;
                r.sym = CharRange( c );
            break;
        }
    }
}
7.2 Derivatives

Two functions on regular expressions, Null and First (see [Wat93a, Example 3.20, Definition 4.60]) — both used in computing derivatives of regular expressions), are defined as recursive member functions in file deriv.cpp. Function Null returns 1 if the empty word (ε) is in the language denoted by the regular expression, and 0 otherwise. Function First returns a CRSet denoting the characters which can occur as the first character of a word in the language denoted by the regular expression.

Member function derivative takes a CharRange and returns the derivative of the regular expression with respect to the CharRange. The derivative is computed recursively according to the definition given in [Wat93a, Definition 5.23]. It is used in the implementation of Brzozowski's construction.
• All of its OR operators are left-associative; for example \((E_0 \cup E_1) \cup E_2\) is left-associative, while \(E_0 \cup (E_1 \cup E_2)\) is not.

• The OR regular expression is in one of two forms (where \(\leq\) is the total ordering on regular expressions): either \((E_0 \cup E_1) \cup E_2\) where \(E_1 \leq E_2\) and \((E_0 \cup E_1)\) is in ONF, or \(E_0 \cup E_1\) where \(E_0 \leq E_1\). (The use of \(<\) instead of \(\leq\) implies that if the subexpressions of an OR expression are equal (under the total ordering), then they are collapsed into one expression, implementing the idempotence of OR.)

The ONF is used to provide the equivalent of a multi-ary OR operator, implementing the associativity, commutativity and idempotence of the OR operator, as detailed in [Wat93a, Definition 5.26].

The member function \texttt{in_snf} returns 1 if the \texttt{RE} is in SNF, and 0 otherwise. The member \texttt{snf} puts the \texttt{RE} in SNF, using function \texttt{onf} as a helper. Member function \texttt{reduce} optimizes an \texttt{RE}, removing any redundant subexpressions. It implements rules 1 to 5 of [Wat93a, Remark 5.32]. The function performs a bottom-up traversal of the regular expression, making such transformations as \(\emptyset \cdot E \rightarrow \emptyset\) and \(\emptyset^* \rightarrow \epsilon\).

All of these members (including the total ordering) are defined in file \texttt{deriv.cpp}.

```
/* (c) Copyright 1994 by Bruce W. Watson */
/* $Revision: 1.2 $ */
/* $Date: 1994/08/15 13:59:46 $ */
#include "re.h"
#include "sigma.h"

// Does *this accept epsilon?
// Implement Definition 3.20 and Property 3.21
int RE::Null() const {
    assert( class_invariant() );

    auto int ret;
    switch( op ) {
    case EPSILON: ret = 1; break;
    case EMPTY: case SYMBOL: ret = 0; break;
    case OR: ret = left->Null() || right->Null(); break;
    case CONCAT: ret = left->Null() && right->Null(); break;
    case STAR: ret = 1; break;
    case PLUS: ret = left->Null(); break;
    case QUESTION: ret = 1; break;
    }
    return( ret );
}

// What is the First of *this?*
// Implement Definition 4.60
CRSet RE::First() const {
    assert( class_invariant() );
```
7.1 Similarity of REs

```c
auto CRSet a;
switch( op ) {
    case EPSILON:
    case EMPTY:
        break;
    case SYMBOL:
        a.append( sym );
        break;
    case OR:
        a = left->First().combine( right->First() );
        break;
    case CONCAT:
        a = left->First();
        if( left->Null() ) {
            a.combine( right->First() );
        }
        break;
    case STAR:
    case PLUS:
    case QUESTION:
        a = left->First();
        break;
}
return( a );
```

// Is this in similarity normal form (SNF)?
int RE::in_snf() const {
    assert( class_invariant() );

    auto int ret;
    // SNF means that all OR nodes are left-associative, and
    // in the two cases:
    //   A OR B that A < B, or
    //   (A OR B) OR C that B < C and (A OR B) is in SNF.
    switch( op ) {
        case EPSILON:
        case EMPTY:
        case SYMBOL:
            ret = 1;
            break;
        case OR:
            if( (right->op == OR) || !right->in_snf() ) {
                // This can't be in SNF.
                ret = 0;
            } else {
                if( left->op == OR ) {
                    // Second case.
                    ret = (*left->right) < *right && left->in_snf();
                } else {
                    // First case.
                    ret = (*left < *right) && left->in_snf();
                }
            }
            break;
        case CONCAT:
            // A CONCAT is in SNF if the subexpressions are in SNF.
            ret = left->in_snf() && right->in_snf();
            break;
        case STAR:
        case PLUS:
        case QUESTION:
            // A unary subexpr. is in SNF if it's subexpressions are too.
            ret = left->in_snf();
            break;
    }
```
return( ret );
}

// Put *this into similarity normal form.
RE& RE::snf() {
    assert( class_invariant() );

    switch( op ) {
    case EPSILON:
    case EMPTY:
        break;
    case SYMBOL:
        // Already in SNF.
        break;
    case OR:
        // While the right is an OR, rotate them.
        // Note: this is not a true rotation, since we get
        // E | (F | G) => (F | E) | G instead of (E | F) | G
        // but, by commutativity it's okay.
        while( right->op == OR ) {
            auto RE*temp{ left );
            left = right;
            right = left->right;
            left->right = temp;
            assert( class_invariant() );
        }
        assert( right->op != OR );
        left->snf();
        assert( class_invariant() );
        assert( left->in_snf() );
        right->snf();
        assert( class_invariant() );
        assert( right->in_snf() );
        snf();
        assert( class_invariant() );
        break;
    case CONCAT:
        left->snf();
        assert( class_invariant() );
        assert( left->in_snf() );
        right->snf();
        assert( class_invariant() );
        assert( right->in_snf() );
        break;
    case STAR:
    case PLUS:
    case QUESTION:
        left->snf();
        assert( class_invariant() );
        assert( left->in_snf() );
        break;
    }
    assert( in_snf() );
    assert( class_invariant() );
    return( *this );
}

// What is the derivative of *this?
// Implement Definition 5.83
RE RE::derivative( const CharRange& r ) const {
    assert( class_invariant() );

    // Duplicate some of the knowledge appearing in sig-re.cpp
    auto RE e;
    switch( op ) {
    case EPSILON:
    case EMPTY:
        assert( e.op == EMPTY );
7.1 Similarity of REs

break;
case SYMBOL:
    if( r <= sym ) {
        e.op = EPSILON;
        assert( e.class_invariant() );
    } else {
        // else, it should be EMPTY.
        assert( e.op == EMPTY );
    }
    break;
case OR:
    e.op = OR;
    e.left = new RE( left->derivative( r ) );
    e.right = new RE( right->derivative( r ) );
    assert( e.class_invariant() );
    break;
case CONCAT:
    if( left->Null() ) {
        e.op = OR;
        e.right = new RE( right->derivative( r ) );
        e.left = new RE;
        e.left->op = CONCAT;
        e.left->left = new RE( left->derivative( r ) );
        e.left->right = new RE( *right );
        assert( e.class_invariant() );
    } else {
        e.op = CONCAT;
        e.left = new RE( left->derivative( r ) );
        e.right = new RE( *right );
        assert( e.class_invariant() );
    }
    break;
case STAR:
    e.op = CONCAT;
    e.left = new RE( left->derivative( r ) );
    e.right = new RE( this );
    assert( e.class_invariant() );
    break;
case PLUS:
    e.op = CONCAT;
    e.left = new RE( left->derivative( r ) );
    e.right = new RE;
    e.right->op = STAR;
    e.right->right = 0;
    e.right->left = new RE( *left );
    assert( e.class_invariant() );
    break;
case QUESTION:
    e = left->derivative( r );
    break;
    // By the class_invariant(), the default: cannot occur.
}
assert( e.class_invariant() );
return( (RE)e );

// Implement rules 1-4 of Remark 5.32 of the Taxonomy.
RE& RE::reduce() {
    assert( class_invariant() );
    switch( op ) {
    case EPSILON:
        case EMPTY:
        case SYMBOL:
            // These basis operators cannot be reduced further.
break;

case OR:
    left->reduce();
    assert( class_invariant() );
    right->reduce();
    assert( class_invariant() );
    if( left->op == EMPTY ) {
        // EMPTY OR E == E
        delete left;
        assimilate_node( right );
        assert( class_invariant() );
    } else if( right->op == EMPTY ) {
        delete right;
        assimilate_node( left );
        assert( class_invariant() );
    }

    // The case where left and right are both EMPTY is handled correctly.
    break;

case CONCAT:
    left->reduce();
    assert( class_invariant() );
    right->reduce();
    assert( class_invariant() );
    if( left->op == EMPTY ) {
        // EMPTY CONCAT E == EMPTY
        delete right;
        assimilate_node( left );
        assert( class_invariant() );
    } else if( right->op == EMPTY ) {
        delete left;
        assimilate_node( right );
        assert( class_invariant() );
    } else if( left->op == EPSILON ) {
        // EPSILON CONCAT E == E
        delete left;
        assimilate_node( right );
        assert( class_invariant() );
    } else if( right->op == EPSILON ) {
        delete right;
        assimilate_node( left );
        assert( class_invariant() );
    }

    break;

case STAR:
    left->reduce();
    assert( class_invariant() );
    if( left->op == EPSILON ) {
        // EPSILON * == EPSILON
        assimilate_node( left );
        assert( class_invariant() );
    } else if( left->op == EMPTY ) {
        // EMPTY * == EPSILON
        delete left;
        op = EPSILON;
        left = right = 0;
        assert( class_invariant() );
    }

    break;

case PLUS:
    left->reduce();
    assert( class_invariant() );
    if( left->op == EPSILON ) {
        // EPSILON + == EPSILON
        assimilate_node( left );
        assert( class_invariant() );
    } else if( left->op == EMPTY ) {
        // EMPTY + == EMPTY

7.1 Similarity of REs

```cpp
assimilate_node( left );
assert( class_invariant() );

break;
case QUESTION:
  left->reduce();
  assert( class_invariant() );
  if( left->op == EPSILON ) {
    // EPSILON == EPSILON
    assimilate_node( left );
    assert( class_invariant() );
  } else if( left->op == EMPTY ) {
    // EMPTY == EPSILON
    delete left;
    op = EPSILON;
    left = right = 0;
    assert( class_invariant() );
  }
  break;
}
assert( class_invariant() );
return( *this );

// Put *this into OR normal form (ONF) (used in the snf functions)
RE& RE::onf() {
  assert( class_invariant() );
  assert( op == OR );
  assert( right->op != OR );

  // Two possibilities: (A OR B) OR C, A OR B.
  if( left->op == OR ) {
    // First one.
    // Figure out which order B,C should be in:
    auto int ord( left->right->ordering( *right ) );
    if( ord == 0 ) {
      // B == C
      // destroy C.
      delete right;
      assimilate_node( left );
    } else if( ord > 0 ) {
      // B > C
      // Need to swap B,C
      // Just do it with pointers:
      auto RE *const temp( right );
      right = left->right;
      left->right = temp;

      // Also make sure that (what's now) (A OR C)
      // is also in ONF.
      left->onf();
    } else, it's already in OR NF.
  } else {
    // Second case.
    // Figure out the order of A,B:
    auto int ord( left->ordering( *right ) );
    if( ord == 0 ) {
      // A == B
      // Wipe out one of the two nodes, and make *this
      // equal to the remaining one.
      delete right;
      assimilate_node( left );
    } else if( ord > 0 ) {
      // A > B
      // Need to swap A,B (left and right):
      auto RE *const temp( right );
```
right = left;
left = temp;
}

// else, it's already in OR NF

assert( class_invariant() );
assert( in_snf() );
return( *this );
}

// Some ordering members (largely used in similarity)
// (This is a kind of lexicographic ordering.)
int RE::ordering( const RE& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    if( op != r.op ) {
        return( op - r.op );
    } else {
        assert( op == r.op );
        auto int ret;
        switch( op ) {
            case EPSILON:
                // These two are unordered (equal).
                ret = 0;
                break;
            case SYMBOL:
                // Both are symbols, so order on the sym.
                ret = sym.ordering( r.sym );
                break;
            case OR:
            case CONCAT:
                ret = left->ordering( r.left_subexpr() );
                if( ret != 0 ) {
                    // Do nothing.
                    // Compare the right subexprs, since the left
                    // ones are equal.
                    ret = right->ordering( r.right_subexpr() );
                }
                break;
            case STAR:
            case PLUS:
            case QUESTION:
                ret = left->ordering( r.left_subexpr() );
                break;
        }
        return( ret );
    }
}

// Assimilate *r into *this, and wipe out *r.
void RE::assimilate_node( RE *const r ) {
    // We can't assert( class_invariant() );
    // since we can't be sure that *this is still good.
    // This just delays catching any potential invariant violations.
    assert( r->class_invariant() );
    op = r->op;
    left = r->left;
    right = r->right;
    sym = r->sym;
    assert( class_invariant() );
    r->op = EMPTY;
    r->left = r->right = 0;
    delete r;
}
7.2 Derivatives

Two functions on regular expressions, \textit{Null} and \textit{First} (see [Wat93a, Example 3.20, Definition 4.60]) — both used in computing derivatives of regular expressions), are defined as recursive member functions in file \texttt{deriv.cpp}. Function \textit{Null} returns 1 if the empty word (\(\varepsilon\)) is in the language denoted by the regular expression, and 0 otherwise. Function \textit{First} returns a \textit{CRSet} denoting the characters which can occur as the first character of a word in the language denoted by the regular expression.

Member function \textit{derivative} takes a \textit{CharRange} and returns the derivative of the regular expression with respect to the \textit{CharRange}. The derivative is computed recursively according to the definition given in [Wat93a, Definition 5.23]. It is used in the implementation of Brzozowski's construction.
8 The $\Sigma$-algebra

The $\Sigma$-algebra (as defined in [Wat93a, Section 3]) is defined as a template class.

Implementation class: $\text{Reg}$

Files: $\text{sigma.h}$

Uses: $\text{CharRange, RE, REops}$

Description: $\text{Reg}$ implements the $\Sigma$-algebra as defined in [Wat93a, Section 3]. The single type (or generic) parameter $T$ is used to specify the carrier set of the $\Sigma$-algebra. The template $\text{Reg}$ is an abstract template, in the sense that it is only used to force a common interface between the $\Sigma$-algebras. Most of the member functions are left undefined, with versions specific to the carrier set being defined separately (see files $\text{sig-re.cpp, sig-fa.cpp, and sig-rfa.cpp}$). Regular expressions (class $\text{RE}$) are taken as the $\Sigma$-term algebra. A special member function is defined, taking a regular expression, and constructing the homomorphic image of the $\text{RE}$, in the $\Sigma$-algebra of $T$. The $\Sigma$-algebra is the only way to construct regular expressions, and it is particularly useful for constructing parts of a finite automaton separately. $\text{Reg}<T>$ inherits publicly from a $T$, and since a $\text{Reg}<T>$ contains nothing extra, it can be cast to a $T$ safely (no slicing occurs, and no information is lost). Presently, only $\text{Reg}<\text{RE}>, \text{Reg}<\text{FA}>, \text{Reg}<\text{RFA}>$ are available. (Each of $\text{RE}, \text{FA}$, and $\text{RFA}$ also have constructors taking a $\text{const}$ reference to $\text{RE}$; for practical purposes, these constructors are much faster than constructing the homomorphic image using $\text{Reg}$.)

Implementation: The template is used to force a common interface for $\Sigma$-algebras with different carrier sets. Forcing an interface is commonly done using abstract base classes, although this is not possible in this case, as the return types of many of the member functions would not be correct.

Performance: The homomorphism of the image member function is recursive, and keeps partially constructed results in local variables. Use-counting in the carrier class can improve performance.
Just pass back to the base class.

```cpp
T( const T& ) {} // Construct the homomorphic image of regular expression r, using the Sigma-
```

// algebra operators (corresponding to the operators of the regular expression).

```cpp
Reg( const RE& r ) {
    assert( r.class_invariant() );
    homomorphic_image( r );
    assert( T::class_invariant() );
}
```

// Default destructor falls through to the "T()"

```cpp
inline const Reg<T>& operator=( const Reg<T>& r ) {
    // Call through to the base-class's operator=
    T::operator=( r );
    return( *this );
}
```

// Now the Sigma-algebra signature:

```cpp
// Sigma-algebra basis
Reg<T>& epsilon();
Reg<T>& empty();
Reg<T>& symbol( const CharRange r );
```

// Sigma-algebra binary ops

```cpp
Reg<T>& or( const Reg<T>& r );
Reg<T>& concat( const Reg<T>& r );
```

// Sigma-algebra unary ops

```cpp
Reg<T>& star();
Reg<T>& plus();
Reg<T>& question();
```

protected:

```cpp
// Helper for constructing the homomorphic image of a regular expression.
// (Can also be used as a type of copy constructor for RE's.)
inline void homomorphic_image( const RE& r );
```
8.1 The $\Sigma$-term algebra $Reg\langle RE \rangle$

Implementation class: $Reg\langle RE \rangle$

Files: sig-re.cpp

Uses: CharRange, Reg, RE, REops

Description: The template instantiation $Reg\langle RE \rangle$ can be used to construct regular expressions (see the documentation on template class Reg).

Implementation: The implementation consists of straight-forward expression tree manipulations. The implementation of $RE$ is declared protected to give $Reg\langle RE \rangle$ access to it.

Performance: These member functions would benefit from use-counting of class $RE$.

```c
Reg<RE>& Reg<RE>::epsilon() {
    // This may have been something in a previous life.
    reincarnate();
}```
8.1 The $\Sigma$-term algebra Reg<RE>

```cpp
set_root_operator( EPSILON );
assert( class_invariant() );
return( *this );
}

Reg<RE>& Reg<RE>::empty() {
    // See epsilon() case.
    reincarnate();
    set_root_operator( EMPTY );
    assert( class_invariant() );
    return( *this );
}

Reg<RE>& Reg<RE>::symbol( const CharRange r ) {
    // See epsilon case.
    reincarnate();
    set_root_operator( SYMBOL );
    set_symbol( r );
    assert( class_invariant() );
    return( *this );
}

Reg<RE>& Reg<RE>::or( const Reg<RE>& r ) {
    assert( class_invariant() );
    assert( r.class_invariant() );
    auto RE *const lft( new RE );
    // Make a copy of *this.
    shallow_copy( lft );
    auto RE *const rt( new RE( r ) );
    op = OR;
    left = lft;
    right = rt;
    assert( class_invariant() );
    return( *this );
}

Reg<RE>& Reg<RE>::concat( const Reg<RE>& r ) {
    assert( class_invariant() );
    assert( r.class_invariant() );
    auto RE *const lft( new RE );
    shallow_copy( lft );
    auto RE *const rt( new RE( r ) );
    op = CONCAT;
    left = lft;
    right = rt;
    assert( class_invariant() );
    return( *this );
}

Reg<RE>& Reg<RE>::star() {
    assert( class_invariant() );
    auto RE *const d( new RE );
    shallow_copy( d );
    op = STAR;
    left = d;
    right = 0;
    assert( class_invariant() );
    return( *this );
}
```
Reg<RE>::plusO {
  auto RE *const d( new RE);
  shallow_copy( d);
  op = PLUS;
  left = d;
  right = 0;
  assert( class_invariantO);
  return( *this );
}

Reg<RE>::questionO {
  auto RE *const d( new RE);
  shallow_copy( d);
  op = QUESTION;
  left = d;
  right = 0;
  assert( class_invariantO);
  return( *this );
}
Part III
Automata and their components

9 Abstract finite automata

Implementation class: FAabs

Files: faabs.h

Uses: DFA (mentioned)

Description: FAabs is an abstract class, used to provide a common interface to the different types of finite automata (which are FA, DFA, RFA, LBFA, and RBFA). The following operations are provided via member functions:

1. determine how many states there are in the concrete finite automaton;
2. restart the finite automaton in its start states;
3. advance to a new set of states (make a transition) on a character;
4. determine if the automaton is in accepting states;
5. determine if the automaton is stuck (unable to make further transitions);
6. determine if a string is in the language of the automaton, and
7. return a deterministic finite automaton (a DFA) which accepts the same language.

By convention, the argumentless constructor of a class inheriting from FAabs must construct an object of that class that accepts the empty language (i.e. the object does not accept anything).

Implementation: Since it is an abstract base class (pure virtual), all except one of the member functions are pure virtual; the acceptable member function is defined.
virtual int stuck() = 0;

// Is the string w acceptable?
virtual int acceptable(const char *w) {
    for( restart(); stuck() && *w; advance(*w++) ) {} // It's acceptable if *this is final, and the whole of w was consumed.
    return( in_final() && !*w );
}

// Return a DFA accepting the same language as *this.
virtual DFA determinism() const = 0;

#endif
10 Deterministic FAs

Implementation class: DFA

Files: dfa.h, dfa.cpp

Uses: DFA_components, DSDFARev, DTransRel, FAabs, State, StateSet, StateEqRel, SymRel

Description: A DFA is a deterministic finite automaton (see [Wat93a, Property 2.25] for the definition of DFA). It implements the interface required by the abstract class FAabs. Additionally, it also provides member functions to reverse the automaton, and to minimize it (the minimization functions are described later). A special constructor is provided, which takes a structure containing the essential components of a DFA, and uses those components to construct the automaton; this constructor is used in several DFA constructions involving the subset construction (see [Wat93a, p. 12–13] for the subset construction).

```c++
/* (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:27 $
#endif DFA_H
#define DFA_H

#include "faabs.h"
#include "state.h"
#include "stateset.h"
#include "dtransrel.h"
#include "dfacomp.h"
#include "stateeqrel.h"
#include "symrel.h"
#include "dsdfarev.h"
#include <assert.h>
#include <iostream.h>

class DFA : virtual public FAabs {
  public:
    // Constructors, destructors, operator=:
    // Default copy constr, destr, operator= are okay.
    DFA();

    // A special constructor used for subset construction etc.
    DFA( const DFA_components& r );

    // Some member functions:

    // A special one, to reconstruct a DFA, given new components, etc.
    inline DFA& reconstruct( const DFA_components& r );

    // Member functions required by class FAabs:

    virtual int num_states() const;
    virtual void restart();
    virtual void advance( char a );
    virtual int in_final() const;
    virtual int stuck();
    virtual DFA determinism() const;

    // A function to reverse *this.
    DFA& reverse();
};
```
// Some minimization algorithms:

inline DFA& min_Brzezowski();
DFA& min_HopcroftUllman();
DFA& min_dragon();
DFA& min_Hopcroft();
DFA& min_Watson();

// Some member functions relating to useful State's.

// Can all States reach a final State?
int Useful() const;

// Remove any States that cannot reach a final State.
DFA& useless();

// Special member functions:
friend ostream& operator<<( ostream& os, const DFA& r );
inline int class_invariant() const;

protected:

// Given a minimizing equivalence relation, shrink the DFA.
DFA& compress( const StateEqRel& r );
DFA& compress( const SymRel& r );

// Attempt to split the eq. class [p].P w.r.t. [q].P
// (Return 1 if it was split, 0 otherwise.)
State split( const State p, const State q, const CharRange a, StateEqRel& P ) const;

// A helper for min_Watson.
int arc_eq( State p, State q, SymRel& S, const StateEqRel& H, const SymRel& Z ) const;

// Implementation details:
StatePool Q;
// S must be a singleton set, or empty.
StateSet S;
StateSet F;
DTransRel T;

// Some simulation details:
State current;

// Create a DFA with no State's, accepting nothing.
inline DFA::DFA() :
Q(),
S(),
F(),
T(),
current( Invalid ) {
assert( class_invariant() );
}

// A special constructor used for subset construction etc.
// A DFA constructed this way will always have a start State.
inline DFA::DFA( const DFA_components& r ) :
Q( r.Q ),
S( r.S ),
T( r.T ),
F( r.F ) {
current = Invalid;
assert( class_invariant() );
}

inline DFA& DFA::reconstruct( const DFA_components& r ) {
    Q = r.Q;
    S = r.S;
    T = r.T;
    F = r.F;
    current = Invalid;
    assert( class_invariant() );
    return( *this );
}

// See Section 2 (p. 5) of the minimization Taxonomy.
inline DFA& DFA::min_Brzozowski() {
    assert( class_invariant() );
    return( reverse().reverse() );
}

inline int DFA::class_invariant() const {
    return( Q.size() == S.size() && Q.size() == F.size() && Q.size() == T.size() && current < Q.size() && S.size() <= 1 );
}

#endif

Implementation: All of the member functions are straight-forward implementations, with the exception of the minimization and reversal member functions. Those are further described later (the minimization member functions are discussed in Part IV). The constructor which takes a DFA_components object is only provided because most C++ compilers do not support template member functions yet. When these are fully supported, template function construct_components will be inlined in the constructor.

Performance: Use-counting the classes used in the automata (such as DTransRel and StateSet) would improve performance on copy construction and assignment.

int DFA::num_states() const {
    assert( class_invariant() );
    return( Q.size() );
}

void DFA::restart() {
    assert( class_invariant() );
    // There really should be only one state in S.
    // this is ensured by the class invariant.
    current = S.smallest();
}

void DFA::advance( char a ) {
DFA::in_final() const {
    assert( class_invariant() );
    return( F.contains( current ) );
}

int DFA::stuck() {
    assert( class_invariant() );
    return( current == Invalid );
}

DFA DFA::determinism() const {
    assert( class_invariant() );
    // Keep it really simple!
    return( *this );
}

DFA& DFA::reverse() {
    // Make sure that *this is structurally sound.
    assert( class_invariant() );
    // Now construct the DFA components from an abstract DFA state.
    reconstruct( construct_components( DSDFARev( F, &T, &S ) ) );
    return( *this );
}

DFA& DFA::compress( const StateEqRel& r ) {
    assert( class_invariant() );
    // All of the components will be constructed into this structure:
    auto DFA_components ret;
    // Give each eq. class of r a State name:
    // newnames maps States to their new names after compression.
    auto StateTo<State> newnames;
    newnames.set_domain( Q.size() );
    auto State st;
    for( st = 0; st < Q.size(); st++ ) {
        // If st is the representative of its class allocate a new name.
        auto State strep( r.eq_class_representative( st ) );
        if( st == strep ) {
            newnames.map( st ) = ret.Q.allocate();
        } else {
            newnames.map( st ) = newnames.lookup( strep );
        }
    }
    // Construct the new transition relation.
    ret.T.set_domain( ret.Q.size() );
    ret.F.set_domain( ret.Q.size() );
    auto CRSet a;
    for( st = 0; st < Q.size(); st++ ) {
        // If st is the representative, construct the transition.
        if( st == r.eq_class_representative( st ) ) {
            auto State stprime( newnames.lookup( st ) );
            // What are st's out-transitions?
            auto CharRange b;
            a = T.out_labels( st );
            // The out-labels of any other element of [st]-r could have
        }
    }

// been used instead. Some other choice may, indeed, lead
// to a smaller DFA. This approach is used for simplicity.
auto int it;
// iterate over the labels, constructing the transitions.
for( it = 0; labels.end( it ); it++) {
    b = a.iterator( it );
    ret.T.add_transition( stprime, b,
        newnames.lookup( T.transition_on_range( st, b ) ) );
}

// st's eq. class may be final.
if( F.contains( st ) ) {
    ret.F.add( stprime );
}

// Set up the new start state.
ret.S.set_domain( ret.Q.size() );
ret.S.add( newnames.lookup( S.smallest() ) );
reconstruct( ret );
assert( class_invariant() );
return( *this );

DFA& DFA::compress( const SymRel& r ) {
    assert( class_invariant() );

    // All of the components will be constructed into this structure:
    auto DFA.components ret;

    // Give each eq. class of r a State name:
    // newnames maps States to their new names after compression.
    auto StateTo<State> newnames;
    newnames.set_domain( Q.size() );

    auto StateSet consider;
    consider.set_domain( Q.size() );
    consider.complement();

    // Build the set of representatives.
    auto StateSet repr;
    repr.set_domain( Q.size() );

    auto State st;
    for( consider.iter_start( st ); !consider.iter_end( st ); consider.iter_next( st ) ) {
        // st will always be the representative of its class.
        assert( st == r.image( st ).smallest() );
        repr.add( st );

        // give st the new name
        auto State n ( ret.Q.allocate() );
        newnames.map( st ) = n;

        // Go over [st], and give them all the new name.
        auto State z;
        for( r.image( st ).iter_start( z ); !r.image( st ).iter_end( z );
            r.image( st ).iter_next( z ) ) {
            newnames.map( z ) = n;
        }

        // Now mark [st] as having been done already.
        consider.remove( r.image( st ) );
        // The outer iterator should still work okay.
    }
}
Construct the new transition relation.
ret.T.set_domain( ret.Q.size() );
ret.F.set_domain( ret.Q.size() );

auto CRSet a;
// Go over all of the representatives (eq. classes), constructing the
// transitions.
for( repr.iter_start( st ); !repr.iter_end( st ); repr.iter_next( st ) ) {
  auto State stprime( newnames.lookup( st ) );
  // What are st's out-transitions?
  auto CharRange b;

  a = T.out_labels( st );
  // The out-labels of any other element of [st]r could have
  // been used instead. Some other choice may, indeed, lead
  // to a smaller DFA. This approach is used for simplicity.
  auto int it;
  // Iterate over the labels, constructing the transitions.
  for( it = 0; !a.iter_end( it ); it++ ) {
    b = a.iterator( it );
    ret.T.add_transition( stprime, b,
      newnames.lookup( T.transition_on_range( st, b ) ) );
  }

  // st's eq. class may be final.
  if( F.contains( st ) ) {
    ret.F.add( stprime );

    // Set up the new start state.
    ret.S.set_domain( ret.Q.size() );
    ret.S.add( newnames.lookup( S.smallest() ) );
    reconstruct( ret );
    assert( class_invariant() );
    return( *this );
  }

  // Can all of the State's in *this reach a final State?
  // Implement Definition 2.23
  int DFA::Useful() const {
    assert( class_invariant() );
    auto StateSet r( T.reverse_closure( F ) );
    return( r.complement().empty() );
  }

  // Remove any State's from *this that cannot reach a final State. (This is a last
  // step in minimization, since some of the min. algorithms may yield a DFA with a
  // sink state.)
  // Implement Remark 2.39
  DFA& DFA::useful() {
    assert( class_invariant() );
    auto StateSet freachable( T.reverse_closure( F ) );
    auto StateTo<State> newnames;
    newnames.set_domain( Q.size() );

    // All components will be constructed into a special structure:
    auto DFA_components ret;

    auto State st;
    for( st = 0; st < Q.size(); st++ ) {
      // If this is a Useful State, carry it over by giving it a name
      // in the new DFA.
      if( freachable.contains( st ) ) {

  // Implement Definition 2.23
      int DFA::Useful() const {
        assert( class_invariant() );
        auto StateSet r( T.reverse_closure( F ) );
        return( r.complement().empty() );
      }
newnames.map( st ) = ret.Q.allocate();
}

// It is possible that nothing needs to be done (i.e., the all States were already F useful).
if( Q.size() != ret.Q.size() ) {
    ret.T.set_domain( ret.Q.size() );
    ret.F.set_domain( ret.Q.size() );
    auto CRSet a;
    for( st = 0; st < Q.size(); st++ ) {
        // Only construct the transitions if st is final reachable.
        if( reachable.contains( st ) ) {
            a = T.out_labels( st );
            auto State stprime( newnames.lookup( st ) );
            auto CharRange b;
            auto int it;
            // Construct the transitions.
            for( it = 0; it != a.end( it ); it++ ) {
                b = a.iterator( it );
                ret.T.add_transition( stprime, b,
                    newnames.lookup( T.transition_on_range( st, b ) ) );
            }
        // This may be a final State.
        if( F.contains( st ) ) {
            ret.F.add( stprime );
        }
    }
    ret.S.set_domain( ret.Q.size() );
    // Add a start State only if the original one was final reachable.
    if( S.not_disjoint( reachable ) ) {
        ret.S.add( newnames.lookup( S.smallest() ) );
    }
    reconstruct( ret );
    assert( class_invariant() );
    return( *this );
}

ostream& operator<<( ostream& os, const DFA& r ) {
    os << "\nDFA\n";
    os << "Q = " << r.Q << "\n";
    os << "S = " << r.S << "\n";
    os << "F = " << r.F << "\n";
    os << "Transitions = \n" << r.T << "\n";
    os << "current = " << r.current << "\n";
    return( os );
}
11 Constructing a DFA

Implementation class: $DFA_{\text{components}}$

Files: dfacomp.h

Uses: $DTransRel$, $StatePool$, $StateSet$

Description: A $DFA_{\text{components}}$ is a structure containing the essential parts of a DFA. Class $DFA$ has a constructor taking a $DFA_{\text{components}}$. It is used in the subset construction, as the return type of template function $construct_{\text{components}}$.

Implementation: The class is implemented as a struct.

Performance: The template function $construct_{\text{components}}$ should really be a constructor template of $DFA$. This would avoid needing $DFA_{\text{components}}$, and the overhead of passing the structure by value.

```c
/* (c) Copyright 1994 by Bruce W. Watson */
/* $Revision: 1.2 $ */
/* $Date: 1994/08/15 14:00:28 $ */
#ifndef DFACOMP_H
#define DFACOMP_H
#include "st-pool.h"
#include "stateset.h"
#include "dtransrel.h"

struct DFA_components {
    StatePool Q;
    StateSet S;
    DTransRel T;
    StateSet F;
};
#endif
```

11.1 Abstract states and the subset construction

An abstract state is a certain type of object used in the construction of a DFA. They are essentially states in the subset construction (see [Wat93a, p. 12-13]) with some extra information. The template function $construct_{\text{components}}$ uses the extra information to construct a DFA. All abstract states in FIRE engine are implemented using classes with names beginning with $DS$, such as $DSDFARev$. An abstract state must have the following member functions:

- an argumentless constructor, a copy constructor, an assignment operator, and equality and inequality operators;
- $final$ — returns 1 if the abstract state is an accepting (final) state, 0 otherwise;
- $out.labels$ — returns a $CRSet$ representing the set of labels of out-transitions from the abstract state; and
- $out.transition$ — takes a $CharRange$ (which is an element of the $CRSet$ returned by $out.labels$), and returns the abstract state resulting from a transition on the $CharRange$.

Implementation function: $construct_{\text{components}}$

Files: dfaseed.h
11.1 Abstract states and the subset construction

Uses: CharRange, CRSet, DFA_components, State, StateTo

Description: Template function construct_components implements the subset construction, with useless state removal [Wat93a, p. 12–13]. It takes an “abstract state” and constructs the components of a DFA (using the abstract state argument as the start state), returning them in a DFA_components structure. It does this by encoding the abstract states as States, using a breadth-first traversal of the start-reachable abstract states. During the traversal, the deterministic transition relation (a DTransRel) is also constructed. As a result of using a traversal starting at the start state, only reachable States and the reachable part of the deterministic transition relation are constructed.

Implementation: This template function should really appear as a template constructor of class DFA. It is implemented separately, as template member functions have only recently been incorporated into the draft of the C++ language standard. The function implements the subset construction (see [Wat93a, pp. 12, 13]). Each abstract state is assigned a State, using a StateTo to keep track of the names assigned. The out-transitions from each State are constructed, using the StateTo to lookup the encoding of an abstract state. The abstract state classes are to be written in such a way that there are only finitely many of them, thereby ensuring termination of the function. The useless state removal is hidden in the fact that, by starting with the start state, only reachable States are constructed.

Performance: The performance could be greatly increased by making this template function a template constructor of class DFA, avoiding by-value structure passing.

```c++
/** (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:29 $
#ifndef DFA_SEED_H
#define DFA_SEED_H
#include "state.h"
#include "stateto.h"
#include "charrang.h"
#include "crset.h"
#include "dfacomps.h"
#include <assert.h>

// A template function, representing an abstract DFA, used in the construction
// of real DFA's.
// It is assumed that class T is a DS??? class (constrained genericity). See
// dsfa.h or dsfarev.h for examples of a DS??? class.

// Takes a T (an abstract start State), and constructs a DFA.
template<class T>
DFA_components construct_components( const T& abs_start ) {

    auto DFA_components ret;

    // Map each of the State's to a unique T, and vice-versa.
    auto StateTo<T> names;

    // Allocate a name for the new start State, and insert it into the namer.
    auto State s( ret.Q.allocate() );

    names.set.domain( ret.Q.size() );
    names.map( s ) = abs_start;

    ret.T.set.domain( ret.Q.size() );
    ret.F.set.domain( ret.Q.size() );

    // As invariant:
    // ret.T.domain() == ret.Q.size() & & ret.F.domain() == ret.Q.size()
    // and all States < current are already done.
```
auto State current;
   // Now construct the transitions, and finalness of each of the States.
   // ret.Q grows as we go.
   for( current = 0; current < ret.Q.size(); current++ ) {
      // If the abstract state associated with current says it's final, then
      // current is too.
      if( names.lookup( current ).final() ) {
         ret.F.add( current );
      }
   }
   // Now go through all of the out-transitions of the abstract
   // state associated with current (ie. names.lookup( current )).
   auto CRSet a( names.lookup( current ).out_labels() );

   auto CharRange b;
   auto int it;
   for( it = 0; it.iter.end( it ); it++ ) {
      b = a.iterator( it );

      // Do something with the destination of the transition.
      auto T dest( names.lookup( current ).out_transition( b ) );

      // See if dest already has a name (by linear search).
      auto State i;
      for( i = 0; i < ret.Q.size() && (names.lookup( i ) != dest); i++ ) {
      }

      // The abstract state may not have a name yet, so we may need
      // to allocate one.
      if( i == ret.Q.size() ) {
         // Associate i with dest.
         // And maintain the invariant.
         auto State j( ret.Q.allocate() );

         assert( i == j );
         names.set_domain( ret.Q.size() );
         ret.T.set_domain( ret.Q.size() );
         ret.F.set_domain( ret.Q.size() );

         names.map( i ) = dest;
      }

      // Now i is the name of dest.
      assert( dest == names.lookup( i ) );
      // Create the actual transition.
      ret.T.add_transition( current, b, i );
   }
   // That's all for current.

   // Time to resynchronize the domain() of ret.S with ret.Q.size():
   ret.S.set_domain( ret.Q.size() );
   // Add the start State now.
   ret.S.add( s );

   // Return, constructing the DFA on the way out.
   return( ret );
}


As an example of an abstract state, consider class DSDFARev.

Implementation class: DSDFARev
11.1 Abstract states and the subset construction

Files: dsdfarev.h, dsdfarev.cpp

Uses: CharRange, CRSet, DTransRel, StateSet

Description: Class DSDFARev is used in the reversal of a DFA. It is an abstract state representing a set of states, in the reversal of the deterministic automaton (the reversal of a deterministic finite automaton is not necessarily deterministic). A DSDFARev is constructed in the DFA member function reverse. Member functions support all of the required interface of an abstract state.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/06/15 14:00:30 $
#ifndef DSDFAREV_H
#define DSDFAREV_H

#include "charrang.h"
#include "crset.h"
#include "stateset.h"
#include "dtransre.h"
#include <cassert.h>
#include <iostream.h>

// This class is used to represent abstract States in a DFA that is still under
// construction. It is used in the reversal of a DFA.
// Objects of this class represent States in the subset construction of the
// reverse of a DFA.

class DSDFARev {
public:
  // Must always have an argument-less constructor.
  inline DSDFARev();
  inline DSDFARev( const DSDFARev& r );
  
  // A special constructor:
  inline DSDFARev( const StateSet& rq, const DTransRel* T, const StateSet* S );
  inline const DSDFARev& operator==( const DSDFARev& r );
  inline int final() const;
  CRSet out_labels() const;
  DSDFARev out_transition( const CharRange a ) const;
  inline int operator==( const DSDFARev& r ) const;
  inline int operator!=( const DSDFARev& r ) const;

  friend ostream& operator<<( ostream& os, const DSDFARev& r );
};

private:
  StateSet whom;
  const DTransRel* T;
  const StateSet* S;
};

// Must always have an argument-less constructor.
inline DSDFARev::DSDFARev() :
  which(),
  T( 0 ),
  S( 0 ) {}
Implementation: The set of States in the reversed DFA is represented as a StateSet. A DSDFARev maintains pointers to the components of the DFA from which it was created. Two DSDFARevs are equal if their StateSets are equal.
11.2 Derivatives of regular expressions

auto State i;
for( i = 0; i < which.domain(); i++ ) {
a.combine( T->labels_between( i, which ) );
}
return( a );
}

DSDFARrev DSDFARrev::out_transition( const CharRange a ) const {
  assert( class invariant() );
  auto StateSet result;
  // Set the correct domain.
  result.set_domain( which.domain() );

  // Find the reverse transitions by going through all State's.
  auto State i;
  for( i = 0; i < which.domain(); i++ ) {
    auto State j( T->transition_on_range( i, a ) );
    // We know that there's a transition from i to j on a.
    if( which.contains( j ) ) {
      // Then we want to add the reverse transition.
      result.add( i );
    }
  }

  assert( class invariant() );
  // Construct the abstract State on the way out of here:
  return( DSDFARrev( result, T, S ) );
}

ostream& operator<<( ostream& os, const DSDFARrev& r ) {
  os << "\nDSDFARrev\n" << r.which << r.T << r.S << \"\n\";
  return( os );
}

\[
\]

11.2 Derivatives of regular expressions

Implementation class: DSRE

Files: dsre.h, dsre.cpp

Uses: CharRange, CRSet, RE

Description: A DSRE represents a derivative of a regular expression. A derivative of a regular expression is again a regular expression; a DSRE simply provides an abstract state interface to the derivatives.
class DSRE : protected RE {
public:
    // Must always have an argument-less constructor.
    inline DSRE();

    // A special constructor:
    inline const DSRE& operator=( const DSRE& r );

    // The required member functions:
    inline int final() const;
    inline CRSet out_labels() const;
    inline DSRE out_transition( const CharRange a ) const;
    inline int operator==( const DSRE& r ) const;
    inline int operator!=( const DSRE& r ) const;

    friend ostream& operator<<( ostream& os, const DSRE& r );

    inline int class_invariant() const;
};

// Must always have an invariant.
inline DSRE::DSRE() : RE() {
    assert( class_invariant() );
}

inline DSRE::DSRE( const RE& r ) :
    RE( r ) {
    assert( r.class_invariant() );
    // They must always be in similarity normal form SNF (see deriv.cpp)
    RE::snf();
    assert( class_invariant() );
}

inline const DSRE& DSRE::operator=( const DSRE& r ) {
    assert( r.class_invariant() );
    RE::operator=( (const RE&)r );
    assert( class_invariant() );
    return( *this );
}

inline int DSRE::final() const {
    assert( class_invariant() );
    return( RE::Null() );
}

inline CRSet DSRE::out_labels() const {
    assert( class_invariant() );
    return( RE::First() );
}

inline DSRE DSRE::out_transition( const CharRange a ) const {
    assert( class_invariant() );
    return( RE::derivative( a ) );
}

inline int DSRE::operator==( const DSRE& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( RE::operator==( r ) );
}
11.2 Derivatives of regular expressions

```cpp
inline int DSRE::operator!=( const DSRE& r ) const {
    return( operator==( r ) );
}

inline int DSRE::class_invariant() const {
    return( RE::class_invariant() && RE::in_snf() );
}
```

### Implementation:
A DSRE inherits from RE. The interface required of abstract states (such as member functions `final`, `out_labels`, and `out_transition`) is provided through the use of the RE member functions such as `Null`, `First`, and `derivative` (respectively). When a new DSRE is constructed, it is put into similarity normal form, to ensure that there will only be finitely many DSREs (see [Wat93a, Theorem 5.31]).

### Performance:
RE member function `derivative` returns an RE by value, which is then passed to the DSRE constructor. Use-counting RE could eliminate the overhead of copy constructor and destructor calls.

```cpp
ostream& operator<<( ostream& os, const DSRE& r ) {
    assert( r.class_invariant() );
    return( os << "\nDSRE\n" << (const RE&)r );
}
```

---

### Implementation class: DSREopt

**Files:** dsre-opt.h, dsre-opt.cpp

**Uses:** CharRange, CRSet, RE

**Description:** This class is identical to DSRE, with one addition: the underlying regular expression (the derivative) is reduced — redundant subexpressions are eliminated. This makes it more likely that two derivatives (denoting the same language) will be found to be equal (using the DSREopt equality operator) in template function `construct_components`, thus giving a DFA with fewer States.
// Most member functions are calls through to the corresponding RE members.
// DSREopt inherits from RE for implementation.

class DSREopt : protected RE {
    public:
        // Must always have an argument-less constructor.
        inline DSREopt();

        // A special constructor:
        inline DSREopt( const RE& r );

        inline const DSREopt& operator=( const DSREopt& r );

    // The required member functions:
    inline int final() const;
    inline CSet out_labels() const;
    inline DSREopt out_transition( const CharRange a ) const;
    inline int operator==( const DSREopt& r ) const;
    inline int operator!=( const DSREopt& r ) const;

    friend ostream& operator<<( ostream& os, const DSREopt& r );

    inline int class_invariant() const;

};

// Must always have an argument-less constructor.
inline DSREopt::DSREopt() :
    RE() {
    assert( class_invariant() );
}

inline DSREopt::DSREopt( const RE& r ) :
    RE( r ) {
    assert( r.class_invariant() );
    // They must always be in similarity normal form SNP (see deriv.cpp)
    RE::snf();
    // They must also be reduced.
    RE::reduce();
    assert( class_invariant() );
}

inline const DSREopt& DSREopt::operator=( const DSREopt& r ) {
    assert( r.class_invariant() );
    RE::operator=( (const RE&)r );
    assert( class_invariant() );
    return( *this );
}

inline int DSREopt::final() const {
    assert( class_invariant() );
    return( RE::Null() );
}

inline CSet DSREopt::out_labels() const {
    assert( class_invariant() );
    return( RE::First() );
}

inline DSREopt::DSREopt::out_transition( const CharRange a ) const {
    assert( class_invariant() );
    return( RE::derivative( a ) );
}

inline int DSREopt::operator==( const DSREopt& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
}
11.3 Item sets

Implementation: Redundant information is eliminated by calling RE member function reduce in the constructor from an RE.

Performance: See DSRE.

---

11.3 Item sets

Implementation class: ISImpl

Files: is-impl.h, is-impl.cpp

Uses: BitVec, CharRange, CRSet, RE

Description: ISImpl is a base class implementing an item set [Wat93a, Definition 5.58]. It is used as a base class in abstract state classes DSIS, DSDeRemer, and DSIS_opt. It includes a constructor from a pointer to RE (the regular expression associated with the item set). The pointed-to RE is assumed to remain in existence while the DFA components are constructed by template function construct_components. Additionally, the abstract state members final and out_labels are defined. The member function move_dots takes a CharRange and provides the functionality of "derivatives of item sets" (as defined in [Wat93a, Definition 5.61]), while member function D implements the dot closure relation D defined in [Wat93a, Definition 5.63].
This class is used to represent abstract States in a DFA that is still under construction. It is used as the base class in representing item sets, for the item set construction, DeRemer’s construction, and the optimized item set construction. This implements Section 5.5 of the Taxonomy.

class ISImpl {
protected:
    // Must always have an argument-less constructor.
    inline ISImpl();

    // A special constructor:
    ISImpl(const RE *r);

    const ISImpl& operator=(const ISImpl& r);

    // The required member functions:
    inline int final() const;
    CRSet out_labels() const;

    inline int operator==(const ISImpl& r) const;
    inline int operator!=(const ISImpl& r) const;

    // Move the dots across sym nodes.
    inline void move_dots(const CharRange& r);

friend ostream& operator<<(ostream& os, const ISImpl& r);

    inline int class_invariant() const;

    // Some implementation details:
    // Which RE is this with-respect-to:
    const RE *e;

    // Where are the dots:
    // The indices in the BitVec’s are the pre-order traversal orders of
    // the nodes in *e.
    // before indicates the nodes with a dot before them;
    // after indicates the nodes with a dot after them.
    BitVec before;
    BitVec after;

private:
    // Some helpers:

    // Move the dots as far as possible.
    // This is named according to Definition 5.63 of the Taxonomy.
    void D(const RE& r, int& node_num);

    // Fetch the labels throughout the tree.
    // Helper to out_labels().
    CRSet traverse_labels(const RE& r, int& node_num) const;

    // Move the dots throughout the RE tree:
    // Helper to move_dots().
    void ISImpl::traverse_move_dots(const RE& r, const CharRange& a, int& node_num);
};

// Must always have an argument-less constructor.
// The resulting ISImpl won't satisfy the class_invariant().
inline ISImpl::ISImpl() :
    e(0) {}

inline int ISImpl::final() const {
11.3 Item sets

assert( class_invariant() );
// It will be final if there is a dot after the root (which is node 0
// in the traversal order).
// See construction 5.69 of the Taxonomy.
return( after.contains( 0 ) );

inline CRS::out_labels() const {
    assert( class_invariant() );
    // Start at the root, node 0.
    auto int node( 0 );
    return( traverse_labels( *e, node ) );
}

inline int ISImpl::operator==( const ISImpl& r ) const {
    assert( r.class_invariant() );
    // This and r must be relative to the same RE.
    assert( e == r.e );
    // All dots must be in the same places.
    return( (before == r.before) && (after == r.after) );
}

inline int ISImpl::operator!=( const ISImpl& r ) const {
    return( !operator==( r ) );
}

// Move the dots across sym nodes
inline void ISImpl::move_dots( const CharRange& r ) {
    assert( class_invariant() );
    // Traverse the RE tree.
    // i maintains the node number.
    auto int i( 0 );
    // Start without dots after the nodes.
    after.clear();
    traverse_move_dots( *e, r, i );
    assert( i == e->num_operators() );
    // Now go back to the root, and do the closure.
    i = 0;
    D( *e, i );
    assert( i == e->num_operators() );
}

inline int ISImpl::class_invariant() const {
    return( e->class_invariant()
        && before.width() == e->num_operators()
        && after.width() == before.width() );
}

#endif

Implementation: As explained in [Wat93a, Section 5.5], a dot (an item in an item set) can occur either before or after a regular expression, or any of its subexpressions. The subexpressions of the associated regular expression (including the expression itself) are encoded by their node number (starting at 0) in a prefix traversal of the RE expression tree. The dots before subexpressions are stored as bits in a BitVec called before, while the dots after subexpressions are stored as bits in a BitVec, called after (in both cases, the bits indicate if the corresponding dot is present). Two ISImples are equal if these two BitVecs are equal, i.e. their dots before and after are equal. The member functions move_dots and D both make prefix traversals of the RE expression tree, keeping track of the prefix number of each subexpression.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
#include "is-impl.h"

ISImpl::ISImpl( const RE &r ) :
e( r ) {
    assert( r->class_invariant() );
    auto int i{ r->num_operators() };
    before.set_width( i );
    after.set_width( i );
    assert( !(before.something_set() || after.something_set()) );
    // Now put a dot before the root of *e.
    before.set_bit( 0 );
    // Now propagate the dots.
    auto int nodes( 0 );
    D( *r, nodes );
    assert( nodes == r->num_operators() );
    assert( class_invariant() );
}

const ISImpl& ISImpl::operator=( const ISImpl& r ) {
    e = r.e;
    before = r.before;
    after = r.after;
    assert( class_invariant() );
    return( *this );
}

void ISImpl::traverse_move_dots( const RE& r, const CharRange& a, int& node_num ) {
    assert( r.class_invariant() );
    switch( r.root_operator() ) {  // node_num is the preorder number of the associated regular expression.
    case EPSILON:
        // Remove any dot that may be before.
        before.unset_bit( node_num );
        node_num++;
        break;
    case EMPTY:
        // Only dots in front a SYMBOL node, matching CharRange a, can advance.
        before.unset_bit( node_num );
        node_num++;
        break;
    case SYMBOL:
        // if there's a match, advance the bit.
        if( (a <= r.symbol()) && before.contains( node_num ) ) {
            after.set_bit( node_num );
        }
        before.unset_bit( node_num );
        node_num++;
        break;
    case OR:
    case CONCAT:
        before.unset_bit( node_num );
        node_num++;
        traverse_move_dots( r.left_subexpr(), a, node_num );
        traverse_move_dots( r.right_subexpr(), a, node_num );
        break;
    case STAR:
    case PLUS:
    case QUESTION:
        before.unset_bit( node_num );
        node_num++;
        traverse_move_dots( r.left_subexpr(), a, node_num );
        break;
    }
}
11.3 Item sets

Move the dots as far as possible.
This is named according to Definition 5.63 of the Taxonomy.

void ISImpl::D( const RE & r, int & node_num ) {
    // Need to remember if there was a dot in front of this node, and what the preorder number of this node is.
    auto int b;
    auto int nn;
    auto int node_right;
    auto int sub_parirty;

    switch( r.root_operator() ) {  
    case EPSILON:
        // The dot always moves through an EPSILON.
        if( before.contains( node_num ) ) {
            after.set_bit( node_num );
        }
        node_num++;
        break;
    case EMPTY:
    case SYMBOL:
        // The dot never moves through EMPTY or SYMBOL.
        // Just advance to the next preorder number.
        node_num++;
        break;
    case OR:
        // Is there one before this node?
        b = before.contains( node_num );
        nn = node_num++;
        // If b, the propagate the dot inside the (left of the) OR too.
        if( b ) {
            // node_num is now the node num of the left subexp.
            before.set_bit( node_num );
        }
        // Propagate through the left subexpression.
        D( r.left_subexpr(), node_num );
        // If the dot is after the left subexpr, then propagate out of the OR.
        if( after.contains( nn + 1 ) ) {
            after.set_bit( nn );
        }
    // If b, propagate the dot to the right of the OR.
    if( b ) {
        before.set_bit( node_num );
    }
    // Save the node number of the right subexpr.
    node_right = node_num;
    // Propagate through the right subexpr.
    D( r.right_subexpr(), node_num );
    // If the dot is after the right, then propagate it out of the OR.
    if( after.contains( node_right ) ) {
        after.set_bit( nn );
    }
    break;
    case CONCAT:
        nn = node_num++;
        // If there's a dot before the CONCAT, propagate it into the left subexpr.
        if( before.contains( nn ) ) {
            before.set_bit( node_num );
        }
        // Propagate through the left subexpr.
        D( r.left_subexpr(), node_num );
        // If the dot is after the left subexpr, move it before the right one.
        if( after.contains( nn + 1 ) ) {
            before.set_bit( node_num );
        }
    }
}
CONSTRUCTING A DFA

Save the node number of the right subexpr.
node_right = node_num;

// Propagate through the right.
D( r.right_subexpr(), node_num );

// If the dot is after the right subexpr, move it behind the CONCAT.
if( after.contains( node_right ) ) {
  after.set_bit( nn );
}
break;

// A dot before the expression means that it moves after too.
if( before.contains( node_num ) ) {
  after.set_bit( node_num );
}

// Fall through here.

// The fall through from the STAR is correct!
n = node_num++;

// If there's a dot before the STAR/PLUS and into the subexpr.
if( before.contains( nn ) ) {
  before.set_bit( node_num );
}

// Remember if there's already a dot before the subexpr.
sub_parity = before.contains( node_num );

// Propagate through the subexpr.
D( r.left_subexpr(), node_num );

// Check if a dot is after the subexpr.
if( after.contains( nn + 1 ) ) {
  // Move the dot out.
  after.set_bit( nn );
  // and move the bit around before the subexpr.
  // if it wasn't already there before.
  if( !sub_parity ) {
    // Re-propagate the dots.
    // nn + 1 is the node num of the subexpr.
    before.set_bit( ++nn );
    D( r.left_subexpr(), nn );
  }
}
break;

// If there's a dot before the QUESTION, move it after, and into the subexpr.
if( before.contains( nn ) ) {
  after.set_bit( nn );
  before.set_bit( node_num );
}

// Propagate through the subexpr.
D( r.left_subexpr(), node_num );

// If there's a dot after the subexpr, propagate it out.
if( after.contains( nn + 1 ) ) {
  after.set_bit( nn );
}
break;

// Fetch the labels throughout the tree.
CRSet ISimpl::traverse_labels( const RE& r, int& node_num ) const {
  // assume that the root of r is node number node_num.
  assert( class_invariant() );
}
11.3 Item sets

assert( r.class_invariant() );

auto CRSet b;
switch( r.root_operator() ) {
    case EPSILON:
        node_num++;  // Check if this node has a dot before it.
        if( before.contains( node_num ) ) {
            b.append( r.symbol() );
        }
        node_num++;  // Check if this node has a dot before it.
        break;
    case SYMBOL:
        if( before.contains( node_num ) ) {  // Check if this node has a dot before it.
            b.append( r.symbol() );
        }
        node_num++;  // Check if this node has a dot before it.
        break;
    case OR:
    case CONCAT:
        node_num++;  // Check if this node has a dot before it.
        b = traverse_labels( r.left_subexpr(), node_num );  // Check if this node has a dot before it.
        b.combine( traverse_labels( r.right_subexpr(), node_num ) );
        break;
    case STAR:
    case PLUS:
    case QUESTION:
        node_num++;  // Check if this node has a dot before it.
        b = traverse_labels( r.left_subexpr(), node_num );  // Check if this node has a dot before it.
        break;
    }
    return( b );
}

ostream& operator<<( ostream& os, const ISImpl& r ) {
    assert( r.class_invariant() );
    return( os << "\nISImpl\n" << *(r.e) << "\nbefore: " << r.before
        << "\nafter: " << r.after << '\n' );
}

Implementation class: DSIS

Files: dsis.h, dsis.cpp

Uses: CharRange, CRSet, ISImpl, RE

Description: Class DSIS provides the full abstract state interface of an item set (see class ISImpl). DSIS inherits from ISImpl for implementation. It only adds the out_transition member function. It is used in the item set construction [Wat93a, Construction 5.69].

// This class is used to represent abstract States in a DFA that is still under
// construction. It represents the item sets in the Iconstr construction.
// See Construction 5.69
// DSIS inherits from ISImpl for implementation.
class DSIS : protected ISImpl {
    // Must always have an argument-less constructor.
    inline DSIS();

    // A special constructor:
    inline DSIS( const RE & r );

    inline const DSIS & operator=( const DSIS & r );

    // The required member functions:
    inline int final() const;
    inline CRSet out_labels() const;
    DSIS out_transition( const CharRange a ) const;
    inline int operator==( const DSIS & r ) const;
    inline int operator!=( const DSIS & r ) const;

friend ostream& operator<<( ostream& os, const DSIS & r );

    inline int class_invariant() const;
};

// The default constructor won’t leave *this in a condition satisfying the
// class invariant.
inline DSIS::DSIS() : ISImpl() {
}

inline DSIS::DSIS( const RE & r ) : ISImpl( r ) {
    assert( r.class_invariant() );
    assert( class_invariant() );
}

inline const DSIS & DSIS::operator=( const DSIS & r ) {
    assert( r.class_invariant() );
    ISImpl::operator=( ( const ISImpl& ) r );
    // *this may not satisfy the invariant until after the assignment.
    assert( class_invariant() );
    return( *this );
}

inline int DSIS::final() const {
    assert( class_invariant() );
    return( ISImpl::final() );
}

inline CRSet DSIS::out_labels() const {
    assert( class_invariant() );
    return( ISImpl::out_labels() );
}

inline int DSIS::operator==( const DSIS & r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( ISImpl::operator==( r ) );
}

inline int DSIS::operator!=( const DSIS & r ) const {
    return( !operator==( r ) );
}

inline int DSIS::class_invariant() const {
    // Should really check that before and after are fully closed.
    return( ISImpl::class_invariant() );
}
11.3 Item sets

Implementation: Most of the implementation is provided by class ISImpl.

```
#include "dsis.h"

DSIS::out_transition( const CharRange a ) const {
    assert( class_invariantO );
    auto DSIS ret( *this );
    ret.move_dots( a );
    return( ret );
}

ostream& operator<<( ostream& as, const DSIS& r ) {
    assert( r.class_invariantO );
    return( as << "\nDSIS\n" << (const ISImpl&)r );
}
```

Implementation class: DSDeRemer

Files: dsderem.h, dsderem.cpp

Uses: CharRange, CRSet, ISImpl, RE

Description: Class DSDeRemer provides the abstract state interface of an item set (see class ISImpl). DSDeRemer inherits from ISImpl for implementation. It is used in DeRemer's construction [Wat93a, Construction 5.75]. DeRemer's construction can yield smaller DFAs than the item set construction.
inline const DSDeRemer& operator=( const DSDeRemer& r);

// The required member functions:
inline int final() const;
inline CRSet out_labels() const;
DSDeRemer out_transition(const CharRange a) const;
inline int operator==( const DSDeRemer& r) const;
inline int operator!=( const DSDeRemer& r) const;

friend ostream& operator<<( ostream& os, const DSDeRemer& r);

inline int class_invariant() const;

private:
// Helpers: the optimization function of the DeRemer construction.
inline void opt();
void traverse_opt( const RE& r, int& i);

inline DSDeRemer::DSDeRemer() :
   ISImpl() {
}

inline DSDeRemer::DSDeRemer( const RE* r ) :
   ISImpl( r ) {
   assert( r->class_invariant() );
   // The ISImpl constructor will have closed before/after, but not optimized yet.
   opt();
   assert( class_invariant() );
}

inline const DSDeRemer& DSDeRemer::operator=( const DSDeRemer& r ) {
   assert( r.class_invariant() );
   ISImpl::operator=( (const ISImpl*)r );
   assert( class_invariant() );
   return( *this );
}

inline int DSDeRemer::final() const {
   assert( class_invariant() );
   return( ISImpl::final() );
}

inline CRSet DSDeRemer::out_labels() const {
   assert( class_invariant() );
   return( ISImpl::out_labels() );
}

inline int DSDeRemer::operator==( const DSDeRemer& r ) const {
   assert( class_invariant() );
   assert( r.class_invariant() );
   return( ISImpl::operator==( r ) );
}

inline int DSDeRemer::operator!=( const DSDeRemer& r ) const {
   return( !operator==( r ) );
}

inline void DSDeRemer::opt() {
   auto int i( 0 );
   traverse_opt( *e, i );
   assert( i == (e->num_operators()) );
}

inline int DSDeRemer::class_invariant() const {
   // Should really check that before and after are fully closed,
11.3 Item sets

Implementation: The implementation is largely provided by the base class ISImpl. The member function \texttt{opt} (with helper \texttt{traverse_opt}) implements DeRemer's dot filter function \(X\) as defined in [Wat93a, Definition 5.72]. The filter function makes a single prefix traversal of the \(RE\) expression tree. By applying the filter, it becomes more likely that template function \texttt{construct\_components} will find two item sets (denoting the same language) to be equal (this will result in fewer states in the constructed \(DFA\)).

```c
#include "dsderem.h"

DSDeRemer::out_transition( const CharRange a ) const {
    assert( class_invariant() );
    auto DSDeRemer ret( *this );
    ret.move_dots( a );
    ret.opt();
    return( ret );
}

void DSDeRemer::traverse_opt( const RE& r, int& node_num ) {
    assert( r.class_invariant() );
    assert( r.class_invariant() );
    // Recursively traverse \(r\) and apply the optimizations of Defn. 5.72
    // (function \(X\)) of the Taxonomy.
    switch( r.root_operator() ) {
        case EPSILON:
        case EMPTY:
        case SYMBOL:
            node_num++;
            break;
        case OR:
            before.unset_bit( node_num );
            // Fall through is good.
        case CONCAT:
            node_num++;
            traverse_opt( r.left_subexpr(), node_num );
            traverse_opt( r.right_subexpr(), node_num );
            break;
        case STAR:
            before.unset_bit( node_num );
            node_num++;
            after.unset_bit( node_num );
            traverse_opt( r.left_subexpr(), node_num );
            break;
        case PLUS:
        case QUESTION:
            node_num++;
            traverse_opt( r.left_subexpr(), node_num );
            break;
    }
}

ostream& operator<<( ostream& os, const DSDeRemer& r ) {
    assert( r.class_invariant() );
    return( os << "\nDSDeRemer\n" << (const ISImpl&); );
}
```
Implementation class: DSISopt

Files: dsis-opt.h, dsis-opt.cpp

Uses: CharRange, CRSet, ISImpl, RE

Description: Class DSISopt provides the abstract state interface of an item set (see class ISImpl). DSISopt inherits from ISImpl for implementation. It is used in the optimized item set construction [Wat93a, Construction 5.82]. The optimized item set construction (called Oconstr in [Wat93a]) can yield much smaller DFAs than either the normal item set construction or DeRemer's construction.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:32 $
#ifndef DSIS_OPT_H
#define DSIS_OPT_H
#include "charrang.h"
#include "crset.h"
#include "re.h"
#include "is-impl.h"
#include <assert.h>
#include <iostream.h>

class DSIS_opt : protected ISImpl {
public:
   // Must always have an argument-less constructor.
   inline DSIS_opt();

   // A special constructor:
   inline const DSIS_opt& operator=( const DSIS_opt& r );

   // The required member functions:
   inline int final() const;
   inline CRSet out_labels() const;
   DSIS_opt out_transition( const CharRange a ) const;
   inline int operator==( const DSIS_opt& r ) const;
   inline int operator!=( const DSIS_opt& r ) const;

   friend ostream& operator<<( ostream& os, const DSIS_opt& r );

   inline int class_invariant() const;

private:
   // Helpers: the optimization function of the DeRemer construction.
   inline void opt();
   void traverse_opt( const RE& r, int& i );
};

inline DSIS_opt::DSIS_opt() :
   ISImpl() {
}

inline DSIS_opt::DSIS_opt( const RE& r ) :
11.3 Item sets

```cpp
ISImpl( r )
assert( r->class_invariant() );
// The ISImpl constructor will close before/after, but not optimize.
opt();
assert( class_invariant() );
}

inline const DSIS_opt& DSIS_opt::operator=( const DSIS_opt& r )
assert( r.class_invariant() );
ISImpl::operator=( (const ISImpl&)r );
assert( class_invariant() );
return( *this );

inline int DSIS_opt::final() const
assert( class_invariant() );
return( ISImpl::final() );

inline CRSet DSIS_opt::out_labels() const
assert( class_invariant() );
return( ISImpl::out_labels() );

inline int DSIS_opt::operator==( const DSIS_opt& r ) const
assert( class_invariant() );
assert( r.class_invariant() );
return( ISImpl::operator==( r ) );

inline int DSIS_opt::operator!=( const DSIS_opt& r ) const
return( !operator==( r ) );

inline void DSIS_opt::opt()
// Remember if there's a dot after the root.
auto int par( after.contains( 0 ) );
after.clear();
auto int i( 0 );
traverse_opt( *e, i );
assert( i == (e->num_operators() ) );
// The dot after the root may have been removed, so it can be put back.
if( par ) {
  after.set_bit( 0 );
}

inline int DSIS_opt::class_invariant() const
// Should really check that before and after are fully closed,
// and that they are optimized.
return( ISImpl::class_invariant() );
```

**Implementation:** The implementation is largely provided by the base class ISImpl. The member function `opt` (with helper `traverse_opt`) implements the optimized dot filter function $Y$ as defined in [Wat93a, Definition 5.79]. The filter function makes a single prefix traversal of the RE expression tree. By applying the filter, it becomes more likely that template function `construct_components` will find two item sets (denoting the same language) to be equal. The reason why the optimized item set construction yields smaller DFAs than DeRemer's construction is that the $Y$ filter is more effective at removing redundant information than the $X$ filter used in DeRemer's construction (see [Wat93a, Remark 5.81]).
DSIS_opt DSIS_opt::out_transition( const CharRange a ) const {
    assert( class_invariantO );
    auto DSIS_opt ret{ *this };
    ret.move_dots( a );
    ret.optO;
    return( ret );
}

// Implement Definition 5.79
void DSIS_opt::traverse_opt( const RE& r, int& node_num ) {
    assert( class_invariant() );
    assert( r.class_invariant() );
    // Recursively traverse r and apply the optimizations of Defn. 5.79
    // (function Y) of the Taxonomy.
    // After will already have been cleared by DSIS_opt::opt()
    switch( r.root_operator() ) {
        case EPSILON:
            before.unset_bit( node_num );
            node_num++;
            break;
        case SYMBOL:
            // Don't remove a bit before — see Definition 5.79
            node_num++;
            break;
        case OR:
        case CONCAT:
            before.unset_bit( node_num );
            node_num++;
            traverse_opt( r.left_subexpr(), node_num );
            traverse_opt( r.right_subexpr(), node_num );
            break;
        case STAR:
        case PLUS:
        case QUESTION:
            before.unset_bit( node_num );
            node_num++;
            traverse_opt( r.left_subexpr(), node_num );
            break;
    }
}

ostream& operator<<( ostream& os, const DSIS_opt& r ) {
    assert( r.class_invariant() );
    return( os << "DSIS_opt\n" << (const ISImpl&)r );
}
12 Finite automata

Implementation class: FA

Files: fa.h, fa.cpp

Uses: FAabs, RE, State, StatePool, StateRel, StateSet, TransRel

Description: Class FA implements finite automata as defined in [Wat93a, Definition 2.1]. It inherits from FAabs, and implements the interface defined there. A constructor taking an RE is provided, implementing Thompson's top-down construction [Wat93a, Construction 4.5]. This constructor can be more efficient than using the \( \Sigma \)-algebra \( \text{Reg}<FA> \).

```c
/* (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:41 $
#endif FA_H
#define FA_H

#include "faabs.h"
#include "st-pool.h"
#include "stateset.h"
#include "staterel.h"
#include "transrel.h"
#include "re.h"
#include <assert.h>
#include <iostream.h>

// Implement general finite automata (Definition 2.1 of the Taxonomy).
// These can be constructed by the Sigma-algebra (see sig-fa.cpp) or using
// the special constructor from RE's.

class FA : virtual public FAabs {  
public:

  // Constructors, destructors, operator=:
  FA();

  // Provide a copy constructor:
  FA( const FA& r );

  // A special constructor, implementing the Thompson's top-down construction
  // (see Construction 4.5).
  FA( const RE& e );

  // Default operator= is okay.

  // Basic FAabs member functions (without overriding acceptable()):

  virtual int num_states() const;
  virtual void restart();
  virtual void advance( char a );
  virtual int in_final() const;
  virtual int stuck();
  virtual DFA determinism() const;

  // Special member functions:

  friend ostream& operator<<( ostream& os, const FA& r );

  inline int class_invariant() const;

protected:

  // Functions states_reqd, td (see Construction 4.5) for use in the constructor from RE.
  int states_reqd( const RE& e );
  void td( const State s, const RE& e, const State f );
```
// recycle this FA:
void reincarnate();

// Implementation details:
StatePool Q;
StateSet S, F;

// Transitions maps each State to its out-transitions.
TransRel Transitions;
// E is the epsilon transition relation.
StateRel E;

// Simulation stuff:
StateSet current;

inline int FA::class_invariant() const {
    // Should also check that current is E-closed.
    return (Q.size() == S.domain() && Q.size() == F.domain() && Q.size() == Transitions.domain() &&
            Q.size() == E.domain() && Q.size() == current.domain() &&
            S.class_invariant() && F.class_invariant() &&
            Transitions.class_invariant() &&
            E.class_invariant() &&
            current.class_invariant() );
}

#endif

Implementation: Most of the member functions are implemented in a straight-forward manner. The constructor from an RE makes a traversal of the RE to determine the number of States to allocate beforehand.

Performance: Since Thompson’s construction yields finite automata with certain structural properties (see [Wat93a, end of Definition 4.1]), a special “Thompson’s construction” automata class could be efficiently implemented, instead of the general finite automaton structure defined in FA.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 13:59:58 $
#include "fa.h"
#include "dfaseed.h"
#include "dsfa.h"
#include "dfa.h"

// Construct an FA accepting nothing.
FA::FA() : Q() {
    auto State s( Q.allocate() );
    auto State f( Q.allocate() );
    S.set_domain( Q.size() );
    S.add( s );

    F.set_domain( Q.size() );
    F.add( f );

    Transitions.set_domain( Q.size() );
    E.set_domain( Q.size() );
}
current.set_domain( Q.size() );
assert( class_invariant() );
}

FA::FA( const FA& r ) :
Q( r.Q ),
S( r.S ),
F( r.F ),
Transitions( r.Transitions ),
E( r.E ),
current( r.current ) {
assert( class_invariant() );
}

FA::FA( const RE& e ) {
// First, allocate enough states by setting up the domains.
// See Section 4.1.1 of the Taxonomy.
auto int states_required( states_reqd( e ) );
S.set_domain( states_required );
F.set_domain( states_required );
Transitions.set_domain( states_required );
E.set_domain( states_required );
current.set_domain( states_required );

auto State s( Q.allocate() );
auto State f( Q.allocate() );
S.add( s );
F.add( f );
td( s, e, f );
assert( class_invariant() );
}

// The following follows directly from inspecting Thompson's construction
// (Definition 4.1).
int FA::states_reqd( const RE& e ) {
assert( e.class_invariant() );

auto int ret;
switch( e.root_operator() ) {
case EPSILON:
case EMPTY:
case SYMBOL:
ret = 2;
break;
case OR:
ret = 2 + states_reqd( e.left_subexpr() ) + states_reqd( e.right_subexpr() );
break;
case CONCAT:
ret = states_reqd( e.left_subexpr() ) + states_reqd( e.right_subexpr() );
break;
case STAR:
case PLUS:
case QUESTION:
ret = 2 + states_reqd( e.left_subexpr() );
break;
}
return( ret );
}

int FA::num_states() const {
return( Q.size() );
}

// The simulation details follow directly from Section 2 of the Taxonomy.
void FA::restart() {
assert( class_invariant() );
current = E.closure( S );
assert(class_invariantO);
}

void FA::advance( char a ) {
    assert( class_invariantO );
    // Compute the epsilon-closure.
    current = E.closure( Transitions.image( current, a ) );
    assert( current == E.closure( current ) );
    assert( class_invariantO );
}

int FA::in_final() const {
    assert( class_invariantO );
    return( current.not_disjoint( F ) );
}

int FA::stuck() {
    assert( class_invariantO );
    return( current.empty() );
}

DFA FA::determinism() const {
    // Make sure that *this is structurally sound.
    assert( class_invariantO );
    // Now construct the DFA components.
    return( DFA( construct_components( DSFA( S, &Transitions, &E, &F ) ) ) );
}

ostream& operator<<( ostream& os, const FA& r ) {
    assert( r.class_invariantO );
    os << "\nFA\n";
    os << "Q = " << r.Q << "\n";
    os << "S = " << r.S << "\n";
    os << "F = " << r.F << "\n";
    os << "Transitions = \n" << r.Transitions << "\n";
    os << "current = " << r.current << "\n";
    return( os );
}

void FA::td( const State s, const RE& e, const State f ) {
    assert( e.class_invariantO );
    // Implement function td (of Construction 4.5).
    switch( e.root_operatorO ) {
        case EPSILON:
            E.union_cross( s, f );
            break;
        case EMPTY:
            break;
        case SYMBOL:
            Transitions.add_transition( s, e.symbolO(), f );
            break;
        case OR:
            auto State p( Q.allocateO() );
            auto State q( Q.allocateO() );
            td( p, e.left_subexprO(), q );
            auto State r( Q.allocateO() );
            auto State t( Q.allocateO() );
            td( r, e.right_subexprO(), t );
            E.union_cross( s, p );
            E.union_cross( s, r );
            E.union_cross( q, f );
            break;
    }
}
case CONCAT:
{
    auto State p( Q.allocate() );
    auto State q( Q.allocate() );
    td( s, e.left_subexpr(), p );
    td( q, e.right_subexpr(), f );
    E.union_cross( p, q );
}
break;

E.union_cross( t, f );
break;

case STAR:
{
    auto State p( Q.allocate() );
    auto State q( Q.allocate() );
    td( p, e.left_subexpr(), q );
    E.union_cross( s, p );
    E.union_cross( q, p );
    E.union_cross( q, f );
    E.union_cross( s, f );
}
break;

E.union_cross( g, p );
E.union_cross( g, f );
E.union_cross( s, f );

E.union_cross( p, q );
E.union_cross( p, q, q );
E.union_cross( q, p );
E.union_cross( q, q, q );
E.union_cross( s, q );
E.union_cross( s, q, q );
E.union_cross( q, f );
E.union_cross( s, f );

auto State p( Q.allocate() );
auto State q( Q.allocate() );
E.union_cross( s, p );
E.union_cross( q, p );
E.union_cross( q, f );
E.union_cross( s, f );

} break;

case QUESTION:
{
    auto State p( Q.allocate() );
    auto State q( Q.allocate() );
    td( p, e.left_subexpr(), q );
    E.union_cross( s, p );
    E.union_cross( q, p );
    E.union_cross( q, f );
    E.union_cross( s, f );
}
break;

void FA::reincarnate()
{
    Q.reincarnate();
    S.reincarnate();
    F.reincarnate();
    Transitions.reincarnate();
    E.reincarnate();
    current.reincarnate();
}
}

Implementation class: DSFA

Files: dsfa.h, dsfa.cpp

Uses: CharRange, CRSet, StateRel, StateSet, TransRel
Description: Class DSFA implements the abstract class interface required to construct a DFA from an FA. A DSFA is constructed in the FA member function `determinism`, and then passed to template function `construct_components`, which constructs the DFA components.

*/
// (c) Copyright 1994 by Bruce W. Watson */
//@ Revision: 1.2
//@ $Date: 1994/08/15 14:00:31$
ifndef DSFA_H
#define DSFA_H
#include "charrang.h"
#include "crset.h"
#include "stateset.h"
#include "staterel.h"
#include "transrel.h"
#include <assert.h>
#include <iostream.h>

/* This class is used to represent abstract States in a DFA that is still under construction. It is used in the construction of a DFA from an FA. The behaviour of a DSFA follows the simulation behaviour of an FA as in the subset construction. */

class DSFA {
public:
    // Must always have an argument-less constructor.
    inline DSFA();

    inline DSFA( const DSFA& r );

    // A special constructor:
    DSFA( const StateSet& rq,
          const TransRel* T,
          const StateRel* E,
          const StateSet* F );

    inline const DSFA& operator=( const DSFA& r );

    // The required member functions:
    inline int final() const;
    CRSet out_labels() const;
    DSFA out_transition( const CharRange a ) const;
    inline int operator==( const DSFA& r ) const;
    inline int operator!=( const DSFA& r ) const;

    friend ostream& operator<<( ostream& os, const DSFA& r );

    inline int class_invariant() const;

private:
    StateSet which;
    const TransRel* T;
    const StateRel* E;
    const StateSet* F;

};

// Must always have an argument-less constructor.
inline DSFA::DSFA() :
    which(),
    T( 0 ),
    E( 0 ),
    F( 0 )
{ // No assertion of the class invariant, since it won't qualify.
}

inline DSFA::DSFA( const DSFA& r ) :


which( r.whkh ),
T( r.T ),
E( r.E ),
F( r.F ) {
    assert( class_invariant() );
}

inline const DSFA& DSFA::operator=( const DSFA& r ) {
    assert( r.class_invariant() );
    // *this may not satisfy its invariant yet.
    which = r.whkh;
    T = r.T;
    E = r.E;
    F = r.F;
    assert( class_invariant() );
    return( *this );
}

inline int DSFA::final() const {
    return( which.not_disjoint( *F ) );
}

inline int DSFA::operator==( const DSFA& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    return( T == r.T && E == r.E && F == r.F );
}

inline int DSFA::operator!=( const DSFA& r ) const {
    return( !operator==( r ) );
}

inline int DSFA::class_invariant() const {
    return( T != 0 && E != 0 && F != 0 &&
            which.domain() == T->domain() &&
            which.domain() == E->domain() &&
            which.domain() == F->domain() &&
            which == E->closure( which ) );
}

} #endif

Implementation: A DSFA contains a StateSet, representing the set of FA States that make up a DFA state in the subset construction (see [Wat93a, p. 12–13] for an explanation of the subset construction). The implementation follows directly from the way in which an FA processes an input string.

// (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 13:59:50 $
#include "dsfa.h"

// A special constructor:
DSFA::DSFA( const StateSet& rq,
    const TransRel *rT,
    const StateRel *rE,
    const StateSet *rF ) :
    which( rE->closure( rq ) ),
    T( rT ),
    E( rE ),
    F( rF ) {


assert( class_invariant() );
}

DSFA::out_labels() const {
    assert( class_invariant() );
    return( T->out_labels( which ) );
}

DSFA::out_transition( const CharRange a ) const {
    assert( class_invariant() );
    // Construct the abstract State on the way out of here:
    // Assume that which is already E closed, then transition on CharRange
    // a; the StateSet gets E closed again in the constructor.
    return( DSFA( T->transition_on_range( which, a ), T, E, F ) );
}

ostream& operator<<( ostream& os, const DSFA& r ) {
    os << "\DSFA\n" << r.which << "\r.T" << "\r.E" << "\r.F" << '\n';
    return( os );
}

12.1 The $\Sigma$-algebra $\text{Reg}<\text{FA}>$

Implementation class: $\text{Reg}<\text{FA}>$

Files: sig-fa.cpp

Uses: CharRange, FA, Reg, State

Description: The template instantiation $\text{Reg}<\text{FA}>$ implements Thompson’s $\Sigma$-algebra of finite automata, as defined in [Wat93a, Definition 4.1]. The operators can be used directly to construct complex finite automata, or the $\text{Reg}<\text{FA}>$ constructor from $\text{RE}$ (the constructor defined in class $\text{Reg}$) can be used to construct the homomorphic image of the regular expression (the constructor uses these operators indirectly).

Implementation: The implementation follows directly from [Wat93a, Definition 4.1]. In some places it is complicated by the management of domains of StateSets, StateRels, and TransRels.

/* (c) Copyright 1994 by Bruce W. Watson */
#include "charrang.h"
#include "sigma.h"
#include "fa.h"

// Implement the Sigma-algebra operators (Definition 4.29 of the Taxonomy).
Reg<FA>& Reg<FA>::epsilon() {
    // *this may have been something in a previous life.
    // *this may have been something in a previous life.
    // *this may have been something in a previous life.
    // *this may have been something in a previous life.
    repeatmate();
    auto State s( Q.allocate() );
    auto State f( Q.allocate() );
    S.set_domain( Q.size() );
    S.add( s );
    F.set_domain( Q.size() );
    F.add( f );
    Transitions.set_domain( Q.size() );
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```cpp
  E.set_domain( Q.size() );
  E.union_cross( s, f );
  current.set_domain( Q.size() );
  assert( class_invariant() );
  return( *this );
}

Reg<FA>& Reg<FA>::empty() {
  // See epsilon case.
  reincarnate();
  auto State s( Q.allocate() );
  auto State f( Q.allocate() );
  S.set_domain( Q.size() );
  S.add( s );
  F.set_domain( Q.size() );
  F.add( f );
  Transitions.set_domain( Q.size() );
  E.set_domain( Q.size() );
  current.set_domain( Q.size() );
  assert( class_invariant() );
  return( *this );
}

Reg<FA>& Reg<FA>::symbol( const CharRange r ) {
  // See epsilon case.
  reincarnate();
  auto State s( Q.allocate() );
  auto State f( Q.allocate() );
  S.set_domain( Q.size() );
  S.add( s );
  F.set_domain( Q.size() );
  F.add( f );
  Transitions.set_domain( Q.size() );
  Transitions.add_transition( s, r, f );
  E.set_domain( Q.size() );
  current.set_domain( Q.size() );
  assert( class_invariant() );
  return( *this );
}

Reg<FA>& Reg<FA>::or( const Reg<FA>& r ) {
  assert( class_invariant() );
  assert( r.class_invariant() );
  // All state-related stuff in r must be adjusted.
  Q.incorporate( r.Q );
  auto State s( Q.allocate() );
  auto State f( Q.allocate() );
  S.disjointing_union( r.S );
```
S.set_domain( Q.size() );
F.disjointing_union( r.F );
F.set_domain( Q.size() );

Transitions.disjointing_union( r.Transitions );
Transitions.set_domain( Q.size() );
E.disjointing_union( r.E );
E.set_domain( Q.size() );

E.union_cross( s, S );
E.union_cross( F, f );
S.clear();
S.add( s );
F.clear();
F.add( f );
current.set_domain( Q.size() );
assert( class_invariant() );
return( *this );

Reg<FA>& Reg<FA>::concat( const Reg<FA>& r ) {
assert( class_invariant() );
assert( r.class_invariant() );
// See the or operator.
// All state-related stuff in r must be adjusted.

// Save the old domain().
auto int olddom( Q.size() );

// Incorporate the other StatePool.
Q.incorporate( r.Q );

// Adjust the domain of the Start states.
S.set_domain( Q.size() );

// Transitions are just unioned.
Transitions.disjointing_union( r.Transitions );

// The epsilon trans. are unioned and F times r.S are added.
E.disjointing_union( r.E );
F.set_domain( Q.size() );

// r.S will be needed for epsilon transitions.
auto StateSet S1( r.S );
// rename it to the new StatePool size.
S1.rename( olddom );
E.union_cross( F, S1 );

// F remains the Final states.
F = r.F;
F.set_rename( olddom );
current.set_domain( Q.size() );
assert( class_invariant() );
return( *this );
}

Reg<FA>& Reg<FA>::star() {
assert( class_invariant() );

12.1 The $\Sigma$-algebra $\text{Reg}<\text{FA}>$

// Create some new States, and adjust the domains.
auto State s( Q.allocate() );
auto State f( Q.allocate() );

S.set_domain( Q.size() );
F.set_domain( Q.size() );
Transitions.set_domain( Q.size() );
E.set_domain( Q.size() );
current.set_domain( Q.size() );
E.union_cross( s, S );
E.union_cross( s, f );
E.union_cross( F, S );
E.union_cross( F, f );
S.clear();
S.add( s );
F.clear();
F.add( f );
assert( class_invariant() );
return( *this );
}

Reg<FA>& Reg<FA>::plus() {
    assert( class_invariant() );

    // Create some new States, and adjust the domains.
    auto State s( Q.allocate() );
    auto State f( Q.allocate() );

    S.set_domain( Q.size() );
    F.set_domain( Q.size() );
    Transitions.set_domain( Q.size() );
    E.set_domain( Q.size() );
    current.set_domain( Q.size() );

    E.union_cross( s, S );
    E.union_cross( s, f );
    E.union_cross( F, S );
    E.union_cross( F, f );
    S.clear();
    S.add( s );
    F.clear();
    F.add( f );
    assert( class_invariant() );
    return( *this );
}

Reg<FA>& Reg<FA>::question() {
    assert( class_invariant() );

    // Create some new States, and adjust the domains.
    auto State s( Q.allocate() );
    auto State f( Q.allocate() );

    S.set_domain( Q.size() );
    F.set_domain( Q.size() );
    Transitions.set_domain( Q.size() );
    E.set_domain( Q.size() );
    current.set_domain( Q.size() );

    E.union_cross( s, S );
    E.union_cross( s, f );
    E.union_cross( F, f );
S.clear();
S.add(s);
F.clear();
F.add(f);

assert(class_invariant());
return(*this);
13 Reduced finite automata

Implementation class: RFA

Files: rfa.h, rfa.cpp

Uses: DFA, FAabs, LBFA, RBFA, RE, StatePool, StateRel, StateSet, Trans

Description: Class RFA implements reduced finite automata, as defined in [Wat93a, Definition 4.24]. It inherits from FAabs, and implements the interface defined by abstract base FAabs. A constructor taking an RE provides a very efficient top-down implementation of homomorphism rfa defined in [Wat93a, Definition 4.30].

/* (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:48 $
#ifndef RFA_H
#define RFA_H

#include "faabs.h"
#include "st-pool.h"
#include "stateset.h"
#include "staterel.h"
#include "trans.h"
#include "re.h"
#include "dfa.h"
#include <assert.h>
#include <iostream.h>

//*[ c ] The existence of LBFA and RBFA are needed, for friendship.
// Can't include lbfa.h or rbfa.h due to circularity.
class LBFA;
class RBFA;

//*[ Implement RFA's (reduced finite automata - Definition 4.24 of the Taxonomy) 
//*[ as a type of FAabs.

class RFA : virtual public FAabs {
public:
  // Some constructors:
  RFA();
  // Need a copy constructor:
  RFA( const RFA& r );
  // The Sigma-homomorphism constructor (see Definition 4.30):
  RFA( const RE& e );
  // Default destr, operator= are okay.
  // Normal FAabs member functions (don't override acceptable()):
  virtual int num_states() const;
  virtual void restart();
  virtual void advance( char a );
  virtual int in_final() const;
  virtual int stuck();
  virtual DFA determinism() const;

  // An alternate implementation of determinism() using the LBFA interpretation.
  virtual DFA determinism2() const;

  // Special members:
*/
friend ostream& operator<<( ostream& os, const RFA& r );

// These two must be friends so that they can construct themselves properly.
friend class LBFA;
fund class RBFA;

inline int class_invariant() const;

protected:

// A helper: compute all of the components into place.
// for use in the constructor.
void rfa_into( const RE& e,
                 StatePool& Qp,
                 StateSet& f,
                 StateSet& i,
                 Trans& Qm,
                 StateRel& foll,
                 int& N );

// Recycle this:
void reincarnate();

// Implementation details, protected for Reg<RFA> use.
StatePool Q;
StateSet first, last;
Trans Qmap_inverse;
StateRel follow;
int Nullable;

// Some simulation stuff.
int final;
StateSet current;

inline int RFA::class_invariant() const {
    return ( Q.size() == first.domain()
            && Q.size() == last.domain()
            && Q.size() == Qmap_inverse.range()
            && Q.size() == follow.domain()
            && Q.size() == current.domain()
            && first.class_invariant()
            && last.class_invariant()
            && Qmap_inverse.class_invariant()
            && follow.class_invariant()
            && current.class_invariant() );
}

#endif

Implementation: Most of the member functions are implemented in a straight-forward manner.
In implementing RFA, a choice must be made between the two interpretations of States:
the left-biased or the right-biased interpretation (see the bottom of p. 73 in [Wat93a] for
a brief explanation of the different interpretations). The interpretation chosen here is the
right-biased one, since it appears to be the most efficient one in practice.

*/ (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:11 $
#include "rfa.h"
#include "drefa.h"
#include "drefas2.h"
#include "dfaseed.h"
RFA::RFA() : Nullable{ 0 } {
    assert( class_invariant() );
}

RFA::RFA( const RFA& r ) :
    Q( r.Q ),
    first( r.first ),
    last( r.last ),
    Qmap_inverse( r.Qmap_inverse ),
    follow( r.follow ),
    Nullable( r Nullable ),
    final( r.final ),
    current( r.current ) {
    assert( class_invariant() );
}

// The Sigma-homomorphism constructor (see Definition 4.30):
RFA::RFA( const RE& e ) {
    assert( e.class_invariant() );
    auto int size( e.num_symbols() );
    first.set_domain( size );
    last.set_domain( size );
    Qmap_inverse.set_range( size );
    follow.set_domain( size );

    // Now compute all of the components into place in *this
    rfa_into( e, Q, first, last, Qmap_inverse, follow, Nullable );
    current.set_domain( size );
    assert( class_invariant() );
}

// Provide implementation for all of the FAabs required members.
int RFA::num_states() const {
    return( Q.size() );
}

// The following functions make use of the RBFA interpretation of states
// (Section 4.3 of the Taxonomy).
void RFA::restart() {
    assert( class_invariant() );
    // Ready to see any char corresponding to a first.
    current = first;
    // Only acceptable if *this accepts epsilon (ie. Nullable is true).
    final = Nullable;
    assert( class_invariant() );
}

void RFA::advance( char a ) {
    assert( class_invariant() );

    // Figure out which are valid out-transitions.
    current.intersection( Qmap_inverse[a] );

    // current is the set of States we can really be in to see a.
    // We're accepting if at least one of the current States is also a last.
    final = current.not_disjoint( last );
    current = follow.image( current );
    assert( class_invariant() );
}

int RFA::in_final() const {
    assert( class_invariant() );
    return( final );
int RFA::stuck() {
    assert(class_invariant());
    return(current.empty());
}

DFA RFA::determinism() const {
    assert(class_invariant());

    // Now construct the DFA components.
    return(construct_components(DSRFA(first,&Qmap_inverse,&follow,&first,&last,Nullable)));
}

DFA RFA::determinism2() const {
    assert(class_invariant());

    // Now construct, using the right-biased interpretation.
    return(construct_components(DSRFA2(&Qmap_inverse,&follow,&first,&last,Nullable)));
}

// Implement a top down version of Sigma homomorphism rfa (Definition 4.36)
void RFA::rfa_into(const RE& e, StatePool& Qp, StateSet& f, StateSet& l, Trans& Qm, StateRel& foll, int& N) {
    assert(e.class_invariant());

    switch(e.root_operator()) {
    case EPSILON:
        // Nothing to do, but make it nullable.
        N = 1;
        return;
    case EMPTY:
        N = 0;
        return;
    case SYMBOL:
        // There is a symbol here, so give it a State.
        {
            auto State q(Qp.allocate());
            f.add(q);
            l.add(q);
            Qm.add_transition(e.symbol(), q);  // Nothing to do to follow.
            N = 0;
        }
        return;
    case OR:
    case CONCAT:
        // Lots of common code, so do the two together.
        {
            // Compute the rfa of e.left_subexpr() into *this.
            rfa_into(e.left_subexpr(), Qp, f, l, Qm, foll, N);
            // Use some locals to store the pieces of the RFA of
// the right subexpression.
auto StateSet fr;
fr.set_domain( f.domain() );
auto StateSet lr;
lr.set_domain( l.domain() );
auto Trans Qmr;
Qmr.set_range( Qm.range() );
auto StateRel follr;
follr.set_domain( foll.domain() );
auto int Nr;

// Now compute the RFA components corresponding to the right subexpr.
// Note: states are still taken from Qp.
rfa_into( e.right_subexpr(), Qp, fr, lr, Qmr, follr, Nr );

Qm.set_union( Qmr );
if( e.root_operator() == OR ) {
    f.set_union( fr );
    l.set_union( lr );
    foll.set_union( follr );
    N = N | | Nr;
} else {
    // This is a CONCAT.
    assert( e.root_operator() == CONCAT );
    foll.set_union( follr );
    foll.union_cross( f, fr );
    if( N ) {
        f.set_union( fr );
    }
    if( Nr ) {
        l.set_union( lr );
    } else {
        l = lr;
    }
    N = N && Nr;
}

return;
case STAR:
    rfa_into( e.left_subexpr(), Qp, f, l, Qm, foll, N );
    N = 1;
    return;
case PLUS:
    // First, do the subexpression.
    rfa_into( e.left_subexpr(), Qp, f, l, Qm, foll, N );
    foll.union_cross( f, l );
    if( e.root_operator() == STAR ) {
      N = 1;
    } else {
      assert( e.root_operator() == PLUS );
    }
    return;
case QUESTION:
    rfa_into( e.left_subexpr(), Qp, f, l, Qm, foll, N );
    N = 1;
    return;
}

void RFA::reincarnate() {
    Q.reincarnate();
    first.reincarnate();
    last.reincarnate();
    Qmap_inverse.reincarnate();
    follow.reincarnate();
    Nullable = final = 0;
    current.reincarnate();
}
inline const DSRFA& operator=( const DSRFA& r );

// The required member functions:
inline int final() const;
CRSet out_labels() const;

};

// This class is used to represent abstract States in a DFA that is still under
// construction. It is used in the construction of a DFA from an RFA. The behaviour
// of a DSRFA follows the simulation behaviour of an RFA.

// Must always have an argument-less constructor.
inline DSRFA();

// A special constructor:
inline DSRFA( const StateSet& r, const StateRel* rfollow, const Trans* rfollow,
const StateSet* rlast, const int rfinalness );
DSRFA out_transition( const CharRange a ) const;
inline int operator==( const DSRFA& r ) const;
inline int operator!=( const DSRFA& r ) const;

friend ostream& operator<<( ostream& os, const DSRFA& r );
inline int operator<<=( const DSRFA& r ) const;

private:
  // This stuff may vary from object to object.
  StateSet which;
  int finalness;

  // This stuff should be the same for all objects corresponding
  // to a particular RFA.
  const Trans *Qmap_inverse;
  const StateRel *follow;
  const StateSet *first;
  const StateSet *last;
};

// Must always have an argument-less constructor.
inline DSRFA::DSRFA() :
  which(0),
  Qmap_inverse(0),
  follow(0),
  first(0),
  last(0),
  finalness(0) {
  // No assert since it won't satisfy the class invariant.
}

inline DSRFA::DSRFA( const DSRFA& r ) :
  which( r.which ),
  Qmap_inverse( r.Qmap_inverse ),
  follow( r.follow ),
  first( r.first ),
  last( r.last ),
  finalness( r.finalness ) {
  assert( class_invariant() );
}

inline const DSRFA& DSRFA::operator=( const DSRFA& r ) {  
  assert( r.class_invariant() );
  // *this may not satisfy the class invariant yet.
  which = r.which;
  Qmap_inverse = r.Qmap_inverse;
  follow = r.follow;
  first = r.first;
  last = r.last;
  finalness = r.finalness;
  assert( class_invariant() );
  return( *this );
}

inline int DSRFA::final() const {
  assert( class_invariant() );
  return( finalness );
}

inline int DSRFA::operator==( const DSRFA& r ) const {
  assert( class_invariant() );
  assert( r.class_invariant() );
  assert( Qmap_inverse == r.Qmap_inverse && follow == r.follow && first == r.first );
}
Implementation: A DSRFA contains a StateSet, representing the set of RFA States that make up a DFA state in the subset construction (under the right-biased interpretation of states). It also contains an integer indicating if the abstract state is a final one.
Implementation class: **DSRFA2**

Files: dsrfa2.h, dsrfa2.cpp

Uses: CharRange, CRSet, StateRel, StateSet, Trans

**Description:** Class **DSRFA2** implements the abstract class interface required to construct a DFA from an RFA. **DSRFA2** is an alternative to **DSRFA**, using the left-biased interpretation of RFA States, instead of the right-biased interpretation used in **DSRFA**. A **DSRFA2** is constructed in the RFA member function **determinism2**, and then passed to template function **construct_components**, which constructs the components of the DFA.

```cpp
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  // $Date: 1994/08/15 14:00:38 $
#ifndef DSRFA2_H
#define DSRFA2_H

#include "charrang.h"
#include "crset.h"
#include "stateset.h"
#include "staterel.h"
#include "transrel.h"
#include <cassert.h>
#include <iostream.h>

class DSRFA2 {
    public:

    // Must always have an argument-less constructor.
    inline DSRFA2();

    inline DSRFA2( const DSRFA2& r );

    // A special constructor (for use in constructing the start state):
    DSRFA2( const Trans* Qmap_inverse,
        const StateRel* follow,
        const StateSet* first,
        const StateSet* last,
        const int finalness );

    inline const DSRFA2& operator=( const DSRFA2& r );

    // The required member functions:
    inline int final() const;
    CRSet out_labels() const;
    DSRFA2 out_transition( const CharRange a ) const;
    inline int operator==( const DSRFA2& r ) const;
    inline int operator!=( const DSRFA2& r ) const;

    friend ostream& operator<< ( ostream& os, const DSRFA2& r );
};
```
inline int class_invariant() const:

private:
   // Another special constructor, for use in out.transitions():
   DSRFA2( const StateSet& rq,
         const Trans *Qmap_inverse,
         const StateRel *follow,
         const StateSet *first,
         const StateSet *last );

   // This stuff may vary from object to object.
   StateSet which;
   int finalness;

   // This stuff should be the same for all objects corresponding
   // to a particular RFA.
   const Trans *Qmap_inverse;
   const StateRel *follow;
   const StateSet *first;
   const StateSet *last;

   // Must always have an argument-less constructor.
   inline DSRFA2():DSRFA2() :
      which(0),
      Qmap_inverse( 0 ),
      follow( 0 ),
      first( 0 ),
      last( 0 ),
      finalness( 0 ) {
      // No assert since it won't satisfy the class invariant.
   }

   inline DSRFA2::DSRFA2( const DSRFA2& r ) :
      which( r.which ),
      Qmap_inverse( r.Qmap_inverse ),
      follow( r.follow ),
      first( r.first ),
      last( r.last ),
      finalness( r.finalness ) {
      assert( class_invariant() );
   }

   inline const DSRFA2& DSRFA2::operator=( const DSRFA2& r ) {
      assert( r.class_invariant() );
      // *this may not satisfy the class invariant yet.
      which = r.which;
      Qmap_inverse = r.Qmap_inverse;
      follow = r.follow;
      first = r.first;
      last = r.last;
      finalness = r.finalness;
      assert( class_invariant() );
      return( *this );
   }

   inline int DSRFA2::final() const {
      assert( class_invariant() );
      return( finalness );
   }

   inline int DSRFA2::operator==( const DSRFA2& r ) const {
      assert( class_invariant() );
      assert( r.class_invariant() );
      assert( Qmap_inverse == r.Qmap_inverse
         && follow == r.follow
```
Implementation: A DSRFA2 contains a StateSet, representing the set of RFA States that make up a DFA state in the subset construction (under the left-biased interpretation of states). It also contains an integer indicating if the abstract state is a final one.

Performance: For higher performance in constructing a DFA, use class DSRFA instead.
finalness = rq.not_disjoint(*last);
assert(class_invariant());
}

CRSet DSRFA2::out_labels() const {
    assert(class_invariant());
    // There are two cases to deal with, it's either the start state, or not.
    // emptiness of which is indicator of start state.
    if (which.empty()) {
        return(Qmap_inverse->labels_into(*first);
    } else {
        return(Qmap_inverse->labels_into(follow->image(which)));
    }
}

// Pretty much follow the stuff in rfa.cpp
DSRFA2 DSRFA2::out_transition(const CharRange a) const {
    assert(class_invariant());
    // Again, two cases:
    auto StateSet t ( which.empty() ? *first : follow->image( which ) );
    assert(t.empty());
    return(DSRFA2(Qmap_inverse->range_transition(a).intersection(t),
                    Qmap_inverse,
                    follow,
                    first,
                    last) );
}

ostream& operator<<(ostream& os, const DSRFA2& r) {
    os << "\nDSRFA2
" << r.which << r.Qmap_inverse << r.follow
<< r.first << r.last << r.finalness << '\n';
    return(os);
}

13.1 The Σ-algebra Reg<RFA>

Implementation class: Reg<RFA>

Files: sig-rfa.cpp

Uses: CharRange, Reg, RFA

Description: The template instantiation Reg<RFA> implements the Σ-algebra of reduced finite automata, as defined in [Wat93a, Definition 4.29]. The operators can be used directly to construct complex RFAs, or the Reg<RFA> constructor from RE (which is defined in template class Reg) can be used to construct the homomorphic image of the regular expression.

Implementation: The implementation follows directly from [Wat93a, Definition 4.29].
13.1 The $\Sigma$-algebra $\text{Reg<RFA>}$

Null = 1;

assert( class.invariant() );
return( *this );

Reg<RFA>& Reg<RFA>::empty() {
    // See epsilon case.
    reincarnate();
    assert( Nullable == 0 );
    return( *this );
}

Reg<RFA>& Reg<RFA>::symbol( const CharRange r ) {
    // See epsilon case.
    reincarnate();
    auto State q( Q.allocate() );
    first.set_domain( Q.size() );
    first.add( q );
    last.set_domain( Q.size() );
    last.add( q );
    Qmap_inverse.set_range( Q.size() );
    Qmap_inverse.add_transition( r, q );
    follow.set_domain( Q.size() );
    // Nothing to add to follow.
    Nullable = 0;
    current.set_domain( Q.size() );
    assert( class.invariant() );
    return( *this );
}

Reg<RFA>& Reg<RFA>::or( const Reg<RFA>& r ) {
    assert( class.invariant() );
    assert( r.class.invariant() );
    // All state-related stuff in $r$ must be adjusted.
    Q.incorporate( r.Q );
    first.disjointing_union( r.first );
    last.disjointing_union( r.last );
    Qmap_inverse.disjointing_union( r.Qmap_inverse );
    follow.disjointing_union( r.follow );
    Nullable = Nullable || r.Nullable;
    current.set_domain( Q.size() );
    assert( class.invariant() );
    return( *this );
}

Reg<RFA>& Reg<RFA>::concat( const Reg<RFA>& r ) {
    assert( class.invariant() );
    assert( r.class.invariant() );
}
// See the or operator.
// All state-related stuff in r must be adjusted.
// First, incorporate the follow sets.

follow.disjointing_union( r.follow );
// Rename the incoming StateSet's first and last StateSets.
auto StateSet fil( r.first );
fil.st.rename( Q.size() );
auto StateSet la1( r.last );
la1.st.rename( Q.size() );

Q.incorporate( r.Q );
// Adjust last as well.
last.set_domain( Q.size() );
follow.union_cross( last, fil );

first.set_domain( Q.size() );
if( Nullable ) {
    first.set_union( fil );
}

if( r Nullable ) {
    last.set_union( la1 );
} else {
    last = la1;
}

Qmap_inverse.disjointing_union( r.Qmap_inverse );

Nullable = Nullable && r.Nullable;

current.set_domain( Q.size() );
assert( class_invariant() );
return( *this );

Reg<RFA>& Reg<RFA>::star() {
    assert( class_invariant() );

    // Nothing to do to Q, first, last, Qmap_inverse.
    follow.union_cross( last, first );
    Nullable = 1;
    assert( class_invariant() );
    return( *this );
}

Reg<RFA>& Reg<RFA>::plus() {
    assert( class_invariant() );

    // Don't change Q, first, last, Qmap_inverse, Nullable.
    follow.union_cross( last, first );
    assert( class_invariant() );
    return( *this );
}

Reg<RFA>& Reg<RFA>::question() {
    assert( class_invariant() );

    // Don't change Q, first, last, Qmap_inverse, follow.
    Nullable = 1;
    assert( class_invariant() );
    return( *this );
}
14 Left-biased finite automata

Implementation class: LBFA

Files: lba.h, lba.cpp

Uses: DFA, FAabs, RFA, State, StatePool, StateRel, StateSet, Trans

Description: Class LBFA implements left-biased finite automata, as defined in [Wat93a, Definition 4.20]. It inherits from FAabs, and implements the interface defined by abstract base FAabs. A constructor taking an RFA provides a method of (indirectly) constructing an LBFA from regular expressions. The constructor implements isomorphism decode as defined in [Wat93a, Definition 4.28]. A special member function takes an an RFA and implements the non-isomorphic mapping convert defined in [Wat93a, Definition 4.35]. This mapping provides an alternative way of constructing an LBFA from an RFA (see [Wat93a, p. 36–37]).
friend ostream& operator<<( ostream& os, const LBFA& r );

inline int class_invariant() const;

protected:

// Implementation stuff, protected for Reg<LBFA>:

StatePool Q;
// Single start state.
State s;
StateSet F;
// Qmap (see Definition 4.24) stored as its inverse.
Trans Qmap_inverse;
StateRel follow;

// Simulation stuff:
StateSet current;

};

inline int LBFA::class_invariant() const {
    return( Q.contains( s )
        && Q.size() == F.domain()
        && Q.size() == Qmap_inverse.range()
        && Q.size() == follow.domain()
        && Q.size() == current.domain()
        && F.class_invariant()
        && Qmap_inverse.class_invariant()
        && follow.class_invariant()
        && current.class_invariant() );
}

#endif

Implementation: Class LBFA is a friend of class RFA. Most of the member functions are implemented in a straight-forward manner.

LBFA::LBFA() {
    // Ensure that this has the LBFA properties.
    // a single start State, with no in-transitions,
    s = Q.allocate();
    F.set_domain( Q.size() );
    Qmap_inverse.set_range( Q.size() );
    follow.set_domain( Q.size() );
    current.set_domain( Q.size() );
    assert( class_invariant() );
}

// Implement homomorphism decode (Definition 4.28).
LBFA::LBFA( const RFA& r ) :
    Q( r.Q ),
    F( r.last ),
    Qmap_inverse( r.Qmap_inverse ),
    follow( r.follow ) {
    assert( r.class_invariant() );
}

// The new start state:
    s = Q.allocate();
    F.set_domain( Q.size() );
Qmap_inverse.set_range(Q.size());
follow.set_domain(Q.size());
current.set_domain(Q.size());

// ...which is final if the RFA is nullable.
if( r Nullable ) {
    F.add(s);
}
auto StateSet fst(r.first);
fst.set_domain(Q.size());
follow.union_cross(s, fst);
assert(r.class_invariant());
}

int LBFA::num_states() const {
    assert(class_invariant());
    return(Q.size());
}

void LBFA::restart() {
    assert(class_invariant());
current.clear();
current.add(s);
assert(class_invariant());
}

void LBFA::advance(char a) {
    assert(class_invariant());
    current = Qmap_inverse(a).intersection(follow.imagery(current));
}

int LBFA::in_final() const {
    return(current.no_disjoint(F));
}

int LBFA::stuck() {
    return(current.empty());
}

DFA LBFA::determinism() const {
    assert(class_invariant());
    // Need s as a singleton StateSet.
    auto StateSet S;
    S.set_domain(Q.size());
    S.add(s);
    // Now construct the DFA components.
    return(construct_components(DSLBFA(S, &Qmap_inverse, &follow, &F)));
}

// Implement homomorphism decode (Definition 4.28).
LBFA& LBFA::decode(const RFA& r) {
    assert(r.class_invariant());
    Q = r.Q;
    F = r.last;
    Qmap_inverse = r.Qmap_inverse;
    follow = r.follow;

    // The new start state:
s = Q.allocate();
F.set_domain( Q.size() );
Qmap_inverse.set_range( Q.size() );
follow.set_domain( Q.size() );
current.set_domain( Q.size() );

// ...which is final if the RFA is nullable.
if( r_Nullable ) {
  F.add( s );
}
auto StateSet fst( r.first );
fst.set_domain( Q.size() );
follow.union_cross( s, fst );
assert( class_invariant() );
return( *this );
}

// Implement non-homomorphic RFA->LBFA mapping convert (Defn. 4.35).
LBFA& LBFA::convert( const RFA& r ) {
  // Implement Definition 4.35 of the Taxonomy.
  assert( r.class_invariant() );
  Q = r.Q;
  // r.first must be a singleton set for this to work properly!
  // (See Property 4.37):
  assert( r.first.size() == 1 );
  s = r.first.smallest();
  F = r.last;
  Qmap_inverse = r.Qmap_inverse;
  follow = r.follow;
  current = r.current;
  assert( class_invariant() );
  return( *this );
}

ostream& operator<<( ostream& os, const LBFA& r ) {
  assert( r.class_invariant() );
  os << "\nLBFA\n; 
Q :; " << r.Q << ",";
  os << "a :; " << r.a << ",";
  os << "F = " << r.F << ",";
  os << "Qmap_inverse = " << r.Qmap_inverse << "\n; 
follow = \n" << r.follow << "\n; 
current = " << r.current << "\n; 
return( os );
}

Implementation class: DSLBFA

Files: dslbfa.h, dslbfa.cpp

Uses: CharRange, CRSet, StateRel, StateSet, Trans

Description: Class DSLBFA implements the abstract class interface required to construct a DFA from an LBFA. A DSLBFA is constructed in the LBFA member function determinism, and then passed to template function construct_components, which constructs the components of the DFA.

/* (c) Copyright 1994 by Bruce W. Watson */
/* $Revision: 1.2 $ */
This class is used to represent abstract States in a DFA that is still under construction. It is used in the construction of a DFA from an LBFA. The behaviour of a DSLBFA follows the simulation behaviour of an LBFA.

class DSLBFA {
public:
    // Must always have an argument-less constructor.
    inline DSLBFA();

    inline DSLBFA( const DSLBFA& r );

    // A special constructor:
    DSLBFA( const StateSet& rq,
    const Trans *Qmap_inverse,
    const StateRel *follow,
    const StateSet *F );

    inline const DSLBFA& operator=( const DSLBFA& r );

    // The required member functions:
    inline int final() const;
    CRSSet out_labels() const;
    DSLBFA out_transition( const CharRange a ) const;
    inline int operator==( const DSLBFA& r ) const;
    inline int operator!=( const DSLBFA& r ) const;

    friend ostream& operator<<( ostream& os, const DSLBFA& r );

    inline int class_invariant() const;

private:
    StateSet which;
    const Trans *Qmap_inverse;
    const StateRel *follow;
    const StateSet *F;
};

// Must always have an argument-less constructor.
inline DSLBFA::DSLBFA() :
    which(),
    Qmap_inverse( 0 ),
    follow( 0 ),
    F( 0 ) {
    // No assertion of the class invariant since it isn't satisfied yet.
}

inline DSLBFA::DSLBFA( const DSLBFA& r ) :
    which( r.which ),
    Qmap_inverse( r.Qmap_inverse ),
    follow( r.follow ),
    F( r.F ) {
    assert( class_invariant() );
inline const DSLBFA& DSLBFA::operator=( const DSLBFA& r ) {
    assert( r.class_invariant() );
    // *this does not satisfy the class invariant yet.
    which = r.which;
    Qmap_inverse = r.Qmap_inverse;
    follow = r.follow;
    F = r.F;
    assert( class_invariant() );
    return( *this );
}

inline int DSLBFA::final() const {
    assert( class_invariant() );
    return( which.not_disjoint( *F ) );
}

inline int DSLBFA::operator==( const DSLBFA& r ) const {
    assert( class_invariant() );
    assert( Qmap_inverse == r.Qmap_inverse && follow == r.follow && F == r.F );
    return( which == r.which );
}

inline int DSLBFA::operator!=( const DSLBFA& r ) const {
    return( operator==( r ) );
}

inline int DSLBFA::class_invariant() const {
    return( Qmap_inverse != 0 && follow != 0 && F != 0 && which.domain() == Qmap_inverse->range() && which.domain() == follow->domain() && which.domain() == F->domain() );
}

#include "dslbfa.h"

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 13:59:52 $  
#include "dslbfa.h"

// A special constructor:
DSLBFA::DSLBFA( const StateSet& rq,
    const Trans*Qmap_inverse,
    const StateRel*follow,
    const StateSet*rF ) :
    which( rq ),
    Qmap_inverse( rQmap_inverse ),
    follow( rfollow ),
    F( rF ) {
    assert( class_invariant() );
}

CRSet DSLBFA::out_labels() const {
    assert( class_invariant() );
    // *Qmap_inverse contains the transitions into State's.
    // So, we take the image of which under follow to get which's out-transitions.
    return( Qmap_inverse->labels_into( follow->image( which ) ) );

Implementation: A DSLBFA contains a StateSet, representing the set of LBFA States that make up a DFA state in the subset construction. It also includes pointers to some components of the LBFA that constructed it.
Pretty much follow the stuff in lbfa.cpp

```cpp
// Pretty much follow the stuff in lbfa.cpp
DSLBFA DSLBFA::out_transition( const CharRange a ) const {
    assert( class_invariant() );
    return( DSLBFA( follow->image( which ).intersection(
        Qmap_inverse->range_transition( a ) ),
        Qmap_inverse,
        follow,
        F ) );
}

ostream& operator<<( ostream& os, const DSLBFA& r ) {
    os << "\nDSLBFA\n" << r.which << *r.Qmap_inverse << *r.follow << *r.F << '\n';
    return( os );
}
```
15 Right-biased finite automata

Implementation class: RBFA

Files: rbfa.h, rbfa.cpp

Uses: DFA, FAabs, RFA, State, StatePool, StateRel, Trans

Description: Class RBFA implements right-biased finite automata, as defined in [Wat93a, Construction 4.43]. It inherits from FAabs, and implements the interface defined by abstract base class FAabs. A constructor taking an RFA provides a method of (indirectly) constructing an RBFA from regular expressions. The constructor implements isomorphism $R \circ \text{decode} \circ R$ as defined in [Wat93a, p. 41]. A special member function takes a reference to an RFA and implements the non-isomorphic mapping $R \circ \text{convert} \circ R$ defined in [Wat93a, p. 43]. This mapping provides an alternative way of constructing an RBFA from an RFA (see [Wat93a, p. 42-43]).

/* (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 14:00:45 $  
#ifndef RBFA_H
#define RBFA_H

#include "faabs.h"
#include "st-pool.h"
#include "stateset.h"
#include "staterel.h"
#include "trans.h"
#include "rfa.h"
#include <assert.h>
#include <iostream.h>

// Implement right-biased FA's (Construction 4.43 in the Taxonomy).

class RBFA : virtual public FAabs {
public:
    // Constructors, destructors, operator=:
    // Default constructor builds the empty language acceptor.
    RBFA();
    // Default constr, copy constr, destr, operator= are okay.
    // Special constructor (from RFA) implementing R; decode; R (see
    // Construction 4.45 of the Taxonomy):
    RBFA( const RFA& r );

    // Standard FAabs member functions. Don't override acceptable():
    virtual int num_states() const;
    virtual void restart();
    virtual void advance( char a );
    virtual int in_final() const;
    virtual int stuck();
    virtual DFA determinism() const;

    // Some Sigma-algebra conversions:
    // as the duals of those given in Definitions 4.28 and 4.35
    virtual RBFA& decode( const RFA& r );
    virtual RBFA& convert( const RFA& r );

    // Special member functions:

};
friend ostream& operator<<( ostream& os, const RBFA& r );

inline int class_invariant() const;

protected:
// Implementation stuff, protected for Reg<RBFA>:
StatePool Q;
StateSet S;
// Single final state as required (Construction 4.45):
State f;
// See rfa.h and Rfa.h for explanation of Qmap_inverse:
Trans Qmap_inverse;
StateRel follow;

// Simulation stuff:
StateSet current;

};

inline int RBFA::class_invariant() const {
return( Q.contains( f )
&& Q.size() == S.domain()
&& Q.size() == Qmap_inverse.range()
&& Q.size() == follow.domain()
&& Q.size() == current.domain()
&& S.class_invariant()
&& Qmap_inverse.class_invariant()
&& follow.class_invariant()
&& current.class_invariant() );
}

#endif

Implementation: Class RBFA is a friend of class RFA. Most of the member functions are implemented in a straight-forward manner.

*/ (c) Copyright 1994 by Bruce Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:08 $
#include "rbfa.h"
#include "dfaseed.h"

RBFA::RBFA() {
// Give *this the properties required of Construction 4.45
f = Q.allocate();
S.set_domain( Q.size() );
Qmap_inverse.set_range( Q.size() );
follow.set_domain( Q.size() );
current.set_domain( Q.size() );
assert( class_invariant() );
}

// Implement R; decode: R (Construction 4.45 of the Taxonomy):
RBFA::RBFA( const RFA& r ) :
Q( r.Q ),
S( r.S ),
Qmap_inverse( r.Qmap_inverse ),
follow( r.follow ) {
assert( r.class_invariant() );
// Create the new final state.
f = Q.allocate();
RIGHT-BIASED FINITE AUTOMATA

```c++
void RBFA::restart() {
    assert( class_invariant() );
    current = S;
    assert( class_invariant() );
}

void RBFA::advance( char a ) {
    // Compute which states we can even transition out of, then
    // transition out of them.
    assert( class_invariant() );
    current = follow.image( current.intersection( Qmap_inverse[a] ) );
    assert( class_invariant() );
}

int RBFA::in_final() const {
    assert( class_invariant() );
    return( current.contains( f ) );
}

int RBFA::is_stuck() {
    assert( class_invariant() );
    return( current.empty() );
}

DFA RBFA::determinism() const {
    // Make sure that *this is structurally sound.
    assert( class_invariant() );
    // Now construct the DFA components.
    return( construct_components( DSRBFA( S, &Qmap_inverse, &follow, f ) ) );
}
```

// Implement homomorphism R; decode : R (Construction 4.45):
RBFA& RBFA::decode( const RFA& r ) {
    // Implement R; decode : R of the Taxonomy (p. 41).
    assert( r.class_invariant() );
    Q = r.Q;
    S = r.first;
    Qmap_inverse = r.Qmap_inverse;
    follow = r.follow;
    // Allocate the new final state.
    f = Q.allocate();
    S.set_domain( Q.size() );
    Qmap_inverse.set_range( Q.size() );
    follow.set_domain( Q.size() );
    current.set_domain( Q.size() );
    if( r Nullable ) {
        S.add( f );
    }
    auto StateSet last = r.last;
    last.set_domain( Q.size() );
    follow.union_cross( last, f );
    assert( class_invariant() );
}

int RBFA::num_states() const {
    assert( class_invariant() );
    return( Q.size() );
}
```
current.clear();

if( r.NuStsMe ) {  
    S.add( f );
}
auto StateSet la( r.last );
la.set_domain( Q.size() );
follow.union_cross( la, f );

assert( class_invariant() );
return( *this );
}

// Implement non-homomorphic RFA->RBFA mapping R; convert ; R (see
// page 43 of the Taxonomy):
RBFA& RBFA::convert( const RFA& r ) {
    // Implement R; convert ; R of the Taxonomy (p. 43).
    assert( r.class_invariant() );
    Q = r.Q;
    // r.last must be a singleton for this to work.
    // (See Property 4.37 of the Taxonomy):
    f = r.last.smallest();
    assert( r.last.size() == 1 );
    S = r.first;
    Qmap_inverse = r.Qmap_inverse;
    follow = r.follow;

    current = r.current;
    assert( class_invariant() );
    return( *this );
}

ostream& operator<<( ostream& os, const RBFA& r ) {
    assert( r.class_invariant() );
    os << "\RBFA\n";
    os << "Q = " << r.Q << "\n";
    os << "S = " << r.S << "\n";
    os << "f = " << r.f << "\n";
    os << "Qmap_inverse = " << r.Qmap_inverse << "\n";
    os << "follow = " << r.follow << "\n";
    os << "current = " << r.current << "\n";
    return( os );
}

Implementation class: **DSRBFA**

**Files:** dsrcba.h, dsrcba.cpp

**Uses:** CharRange, CRSet, StateRel, StateSet, Trans

**Description:** Class **DSRBFA** implements the abstract class interface required to construct a **DFA** from an **RBFA**. A **DSRBFA** is constructed in the **RBFA** member function **determinism**, and then passed to template function **construct.components**, which constructs the components of the **DFA**.

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 14:00:34 $  
#ifndef DSRBFA_H
#define DSRBFA_H
#define DSRBFA_H
/include "charrang.h"
#include "crset.h"
#include "state.h"
#include "stateset.h"
#include "staterel.h"
#include "transrel.h"
#include <assert.h>
#include <iostream.h>

// This class is used to represent abstract States in a DFA that is still under
// construction. It is used in the construction of a DFA from an RBFA. The behaviour
// of a DSRBFA follows the simulation behaviour of an RBFA.

class DSRBFA {
public:
    // Must always have an argument-less constructor.
    DSRBFA();

    inline DSRBFA( const DSRBFA & r );

    // A special constructor:
    DSRBFA( const StateSet & rq,
            const Trans *Qmap_inverse,
            const StateRel *follow,
            const State rf );

    inline const DSRBFA & operator=( const DSRBFA & r );

    // The required member functions:
    inline int final() const;
    CRSet out_labels() const;
    DSRBFA out_transition( const CharRange a ) const;
    inline int operator==( const DSRBFA & r ) const;
    inline int operator!=( const DSRBFA & r ) const;

    friend ostream & operator<<( ostream & os, const DSRBFA & r );

    inline int classInvariant() const;

private:
    StateSet which;
    const Trans *Qmap_inverse;
    const StateRel *follow;
    State f;
};

// Must always have an argument-less constructor.
inline DSRBFA::DSRBFA() :
    which()
    Qmap_inverse( 0 ),
    follow( 0 ),
    { ( Invalid ) {
        // *this will not yet satisfy the class invariant.
    }

inline DSRBFA::DSRBFA( const DSRBFA & r ) :
    which( r.which ),
    Qmap_inverse( r.Qmap_inverse ),
    follow( r.follow ),
    { ( r.f ) {
        assert( classInvariant() );
    }

inline const DSRBFA & DSRBFA::operator=( const DSRBFA & r ) {
    assert( r.classInvariant() );
}
Implementation: A DSRBFA contains a StateSet, representing the set of RBFA States that make up a DFA state in the subset construction. It also includes pointers to some components of the RBFA which constructed it.

```
// *this may not satisfy the invariant yet.
which = r.which;
Qmap_inverse = r.Qmap_inverse;
follow = r.follow;
f = r.f;
assert( class_invariant() );
return( *this );

inline int DSRBFA::final() const {
    assert( class_invariant() );
    return( which.contains( f ) );
}

inline int DSRBFA::operator==( const DSRBFA& r ) const {
    assert( class_invariant() );
    assert( r.class_invariant() );
    assert( Qmap_inverse == r.Qmap_inverse && follow == r.follow && f == r.f );
    return( which == r.which );
}

inline int DSRBFA::operator!=( const DSRBFA& r ) const {
    return( !operator==( r ) );
}

inline int DSRBFA::class_invariant() const {
    return( Qmap_inverse != 0 && follow != 0 && 0 <= f && f < follow->domain() && which.domain() == Qmap_inverse->range() && which.domain() == follow->domain() );
}
```
.intersection( which )
Qmap\_inverse,
follow,
f );

ostream& operator<<( ostream& os, const DSRBFA& r ) {
    os << "\DSRBFA\n" << r\_which << *r\_Qmap\_inverse << *r\_follow << r\_f << "\n";
    return( os );
}
16 Automata constructions

The finite automata construction functions are functions which take an RE (or a pointer to an RE) and return an automaton of some type (one of FA, RFA, LBFA, RBFA, or DFA). Functions implementing Brzozowski’s construction [Wat93a, Section 5.3] are given in dconstrs.cpp and dconstrs.h. Functions implementing the item set constructions [Wat93a, Section 5.5] are given in iconstrs.cpp and iconstrs.h. Files constrs.h and constrs.cpp contain all of the remaining functions (from [Wat93a, Section 4]).

All of the function declarations (or prototypes) are accompanied by their corresponding reference in [Wat93a].
// Construction 4.50 (variation of Aho-Sethi-Ullman)
inline DFA ASU_shortcut( const RE& r ) {
    return( RFA( r ).determinism() );
}

// LBFA constructions:
// using RFA's.

// Construction 4.32
inline LBFA BerrySethi( const RE& r ) {
    return( RFA( r ) );
}

// Construction 4.38
LBFA BS_variation( const RE& r );

// DFA from LBFA construction:
// Construction 4.39
inline DFA MYG( const RE& r ) {
    return( BerrySethi( r ).determinism() );
}

// RBFA constructions:
// using RFAs'.

// Construction 4.45
inline RBFA BerrySethi_dual( const RE& r ) {
    return( RFA( r ) );
}

// Construction 4.48
RBFA BS_variation_dual( const RE& r );

// Construction 4.50
inline DFA ASU( const RE& r ) {
    return( BS_variation_dual( r ).determinism() );
}

#endif

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 13:59:42 $
#include "constrs.h"

LBFA BS_variation( const RE& r ) {
    assert( r.class_invariant() );

    // Construct the homomorphic image of r.
    auto RFA !( r );

    // Construct the begin-marker.
    auto Reg<REFA> m;
    m.symbol( '$' );

    // Attach the begin-marker.
    m.concat( (const Reg<REFA>&)m );

    // Construct the dummy LBFA, for use with the non-homomorphic mapping
    // convert (Defn. 4.35 of the Taxonomy)
    auto LBFA LB;

    return( LB.convert( m ) );
}
RBFA BS_variation_dual( const RE& r ) {
    // See above.
    assert( r.class_invariant() );

    auto RFA I( r );
    // Construct the end-marker.
    auto Reg<RFA> m;
    m.symbol( '$' );

    // Attach the end-marker.
    ((Reg<RFA>&)I).concat( m );

    auto RBFA RB;

    return( RB.convert( 1 ) );
}

DFA Brz( const RE& r ) {
    assert( r.class_invariant() );
    return( construct.components( DSRE( r ) ) );
}

DFA Brz_optimized( const RE& r ) {
    assert( r.class_invariant() );
    return( construct.components( DSREopt( r ) ) );
}

ifndef DCONSTRS_H
define DCONSTRS_H

#include "re.h"
#include "dfa.h"
#include <assert.h>

// The numbers in parentheses refer to the Construction number in the Taxonomy.

// DFA constructions:
// Brzowski's constructions:
// Normal (Construction 5.34)
DFA Brz( const RE& r );

// With strong similarity (Construction 5.34 + Remark 5.52)
DFA Brz_optimized( const RE& r );

endif
/ * (c) Copyright 1994 by Bruce W. Watson */

// The numbers in parentheses refer to the Construction number in the Taxonomy.

/ * Item set constructions: */

/ * Iconstr (Construction 5.89) */

DFA Iconstr( const RE *r ) {
    assert( r->class_invariant() );
    return( construct_components( DSIS( r ) ) );
}

DFA DeRemer( const RE *r ) {
    assert( r->class_invariant() );
    return( construct_components( DSDeRemer( r ) ) );
}

DFA Oconstr( const RE *r ) {
    assert( r->class_invariant() );
    return( construct_components( DSIS_opt( r ) ) );
}
Part IV
Minimizing DFAs

An interesting DFA minimization function is the one due to Brzozowski (appearing in [Wat93b, Section 2]).

**User function:** `DFA::min_Brzozowski`

**Files:** `dfa.h`

**Uses:** see the entry for class `DFA`

**Description:** Brzozowski’s minimization algorithm differs from all of the other minimization algorithms, and appears as inline DFA member function `min_Brzozowski`. The member function simply minimizes the DFA.

**Implementation:** The implementation appears in file `dfa.h`. The implementation follows directly from [Wat93b, Section 2].

The remainder of Part IV deals with the other minimization functions, based upon their derivations in [Wat93b].
17 Helper functions

Two member functions of class DFA are used as helpers in those minimization functions which are based upon an equivalence relation (see [Wat93b, Section 3]).

Implementation function: DFA::compress

Files: dfa.cpp

Uses: see the entry for class DFA

Description: Member function compress is overloaded to take either a StateEqRel (an equivalence relation on States), or a SymRel (a symmetrical relation on States). The relation is assumed to be a refinement of relation E [Wat93b, Definition 3.3]. The member function implements function merge defined in [Wat93b, Transformation 3.1].

Implementation: The implementation appears in file dfa.cpp. The implementation follows directly from [Wat93b, Transformation 3.1].

Implementation function: DFA::split

Files: min.cpp

Uses: CharRange, DFA, State, StateEqRel, StateSet

Description: Member function split takes two States (p and q), a CharRange a, and a StateEqRel. The two States are assumed to be representatives in the StateEqRel. The equivalence class of p is then split into those States (equivalent to p) which transition on a to a State equivalent to q, and those that do not. If in fact there was a split (the equivalence class of p is split into two equivalence classes), p will still be the unique representative of one of the two new equivalence classes; in this case, the (unique) representative of the other equivalence class is returned. If no such split occurred, function split returns Invalid.

Implementation: The implementation is a simple, iterative one. It implements the equivalent of the assignment to $Q'_p$ in Algorithm 4.4 of [Wat93b].

```c
/* (c) Copyright 1994 by Bruce W. Watson */
/* $Revision: 1.2 $ */
/* $Date: 1994/08/15 14:00:07 $ */
#include "charrang.h"
#include "state.h"
#include "stateset.h"
#include "st-eqrel.h"
#include "dfa.h"

State DFA::split( const State p, const State q, const CharRange a, StateEqRel& P ) const {
    assert( class_invariant() );
    assert( P.class_invariant() );

    // p and q must be representatives of their eq. classes.
    assert( p == P.eq_class_representative( p ) );
    assert( q == P.eq_class_representative( q ) );

    // Split [p] with respect to [q] and CharRange a.
    auto StateSet part;
    part.set_domain( Q.size() );

    // Iterate over [p], and see whether each member transitions into [q]
    // on CharRange a.
    auto State st;
    for( P.equiv_class( p ), iter.start( st );
```
P.equiv_class( p ).iter_end( st );
P.equiv_class( p ).iter_next( st ) {  
    auto State dest( T.transition_on_range( st, a ) );
    // It could be that dest == Invalid.
    // if not, check if dest is in [q].
    if( dest != Invalid && P.equiv( dest, q ) ) {
        part.add( st );
    }
}

// The following containment must hold after the splitting.
assert( P.equiv_class( p ).contains( part ) );

// Return non-zero if something was split.
if( (part != P.equiv_class( p )) && !part.empty() ) {
    // Now figure out what the other piece is.
    auto StateSet otherpiece( P.equiv_class( p ) );
    otherpiece.remove( part );
    assert( !otherpiece.empty() );
    P.split( part );
    assert( class_invariant() );

    // Now, we must return the representative of the newly created
    // equivalence class.
    auto State x( P.eq_class_representative( otherpiece.smallest() ) );
    assert( x != Invalid );
    // It could be that p is not in part.
    auto State y( P.eq_class_representative( part.smallest() ) );
    assert( y != Invalid );
    assert( x != y );

    if( p == x ) {
        // If p is the representative of 'otherpiece', then
        // return the representative of 'part'.
        assert( otherpiece.contains( p ) );
        return( y );
    } else {
        // If p is the representative of 'part', then return the
        // representative of 'otherpiece'.
        assert( part.contains( p ) );
        return( x );
    }
} else {
    assert( (part == P.equiv_class( p )) || (part.empty()) );
    // No splitting to be done.
    return( Invalid );
}
18 Aho, Sethi, and Ullman's algorithm

User function: DFA::min_dragon

Files: min-asu.cpp

Uses: CRSet, DFA, State, StateEqRel, StateSet

Description: Member function min_dragon is an implementation of Algorithm 4.6 in [Wat93b]. It is named the "dragon" function after Aho, Sethi, and Ullman's "dragon book" [ASU86].

Implementation: The algorithm begins with the approximation $E_0$ to the State equivalence relation $E$. It then repeatedly partitions the equivalence classes until the greatest fixed point ($E$) is reached.

```cpp
// Implement Algorithm 4.6 of the Taxonomy.
DFA& DFA::min_dragon() {  
  assert( class_invariant() );  
  assert( Useful() );  

  // We'll need the combination of all of the out-transitions of all of the States, when splitting equivalence classes.
  auto CRSet C;  
  auto State st;  
  for( st = 0; st < Q.size(); st++) {  
    C.combine( T.out_labels( st ) );  
  }

  // P is the equivalence relation approximation to E. It is initialized to the total relation with domain Q.size().
  auto StateEqRel P( Q.size() );  
  // We now initialize it to $E_0$.
  P.split( F );  

  // reps is the set of representatives of P.
  auto StateSet reps( P.representatives() );  

  // [st] is going to be split w.r.t. something.

  // The following is slightly convoluted.
  reps.iter_start( st );  
  while( !reps.iter_end( st ) ) {  
    auto State q;  

    // Keep track of whether something was indeed split.
    // Having to use this variable could be avoided with a goto
    auto int something_split( 0 );

    // Iterate over all q, and try to split [st] w.r.t. all other equivalence classes [q].
    // Stop as early as possible.
    for( reps.iter_start( q ); !reps.iter_end( q ) ) {  
      &something_split;  
      reps.iter_next( q ) {  
        // Iterate over the possible transition labels, and
        // do a split if possible.
        auto int i;
```

/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 14:00:03 $  
#include "crset.h"  
#include "state.h"  
#include "stateset.h"  
#include "st-eqrel.h"  
#include "dfa.h"
```
for( i = 0; !C.iter_end( i ) && !something_split; i++ ) {
    something_split = (split( st, q, C.iterator( i ), P ) != Invalid);
}

// If something was split, restart the outer repetition.
if( something_split ) {
    // The set of representatives will have changed due to
    // the split.
    reps = P.representatives();
    reps.iter_start( st );
    // Now continue the outer repetition with the restarted
    // representatives.
} else {
    // Just go on as usual.
    reps.iter_next( st );
}

compress( P );
assert( class_invariant() );
return( ~this );
19 Hopcroft and Ullman's algorithm

User function: **DFA::min_HopcroftUllman**

Files: **min-hu.cpp**

Uses: **CRSet**, **DFA**, **State**, **StateSet**, **SymRel**

Description: This member function provides a very convoluted implementation of Algorithm 4.7 of [Wat93b]. It computes the distinguishability relation (relation $D$ in [Wat93b]).

Implementation: The algorithm is not quite the same as that presented in [Wat93b, Algorithm 4.7]. The member function computes the equivalence relation (on States) by first computing distinguishability relation $D$. Initially, the pairs of distinguishable States are those pairs $p, q$ where one is a final State and the other is not. Pairs of States that reach $p, q$ are then also distinguishable (according to the efficiency improvement property given in [Wat93b, Section 4.7, p. 16]). Iteration terminates when all distinguishable States have been considered.

Performance: This algorithm can be expected to run quite slowly, since it makes use of reverse transitions in the deterministic transition relation ($DTransRel$). The transition relations ($TransRel$ and $DTransRel$) are optimized for forward transitions.

```cpp
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $  
// $Date: 1994/08/15 14:00:06 $  
#include "crset.h"  
#include "state.h"  
#include "stateset.h"  
#include "symrel.h"  
#include "dfa.h"  

// Implement (a version of) Algorithm 4.7 of the minimization Taxonomy.
DFA& DFA::min_HopcroftUllman() {  
  assert( class_invariant() );  
  assert( Useful() );  

  // We need the combination of all transition labels, to iterate over  
  // transitions.  
  auto State st;  
  auto CRSet C;  
  for( st = 0; st < Q.size(); st++ ) {  
    C.combine( T.out_labels( st ) );  
  }

  // First, figure out which are the non-final States.  
  auto StateSet nonfinal( F );  
  nonfinal.complement();  

  // Use Z to keep track of the pairs that still need to be considered for distinguishedness.  
  auto SymRel Z;  
  Z.set_domain( Q.size() );  

  // We begin with those pairs that are definitely distinguished.  
  // this includes pairs with different parity.  
  Z.add_pairs( F, nonfinal );  

  // It also includes pairs with differing out-transitions.  
  // iterate over C (the CRSet) and check the haves and have-nots  
  auto StateSet have;  
  have.set_domain( Q.size() );  
  auto StateSet havenot;  
  havenot.set_domain( Q.size() );

  auto int it;
for( it = 0; !it.iter_end( it ); it++ ) {
    // have and havenot must be empty for the update to be correct.
    assert( have.empty() && havenot.empty() );
    auto State p;
    // Iterate over the States and check which have a transition.
    for( p = 0; p < Q.size(); p++ ) {
        // Does p have the transition?
        if( T.transition_on_range( p, C.iterator( it ) ) != Invalid ) {
            have.add( p );
        } else {
            havenot.add( p );
        }
    }
    // have and havenot are distinguished from one another.
    // (under the assumption that UseSelf() holds)
    Z.add_pairs( have, havenot );

    have.clear();
    havenot.clear();
}

// G will be used to accumulate the (distinguishability) relation D.
auto SymRel G;
G.set_domain( Q.size() );

// Now consider all of the pairs until nothing changes.
while( 1 ) {
    auto State p;
    // Go looking for the next pair to do.
    for( p = 0; p < Q.size() && Z.image( p ).empty(); p++ );

    // There may be nothing left to do.
    if( p == Q.size() ) {
        break;
    } else {
        assert( !Z.image( p ).empty() );
        // Choose q such that {p,q} is in Z.
        // We know that such a q exists.
        auto State q( Z.image( p ).smallest() );
        assert( q != Invalid );

        // Move {p,q} from Z across to G.
        Z.remove_pair( p, q );
        G.add_pair( p, q );

        // Now, check out the reverse transitions from p and q.
        auto int i;
        // Iterate over all of the labels.
        for( i = 0; !C.iter_end( i ); i++ ) {
            auto StateSet pprime( T.reverse_transition( p, C.iterator( i ) ) );
            auto StateSet qprime( T.reverse_transition( q, C.iterator( i ) ) );
            // pprime and qprime are all distinguished.
            // Iterate over both sets and flag them as distinguished.
            auto State pp;
            for( pprime.iter_start( pp ); !ppprime.iter_end( pp );
                pprime.iter_next( pp ) ) {
                auto State qp;
                for( qprime.iter_start( qp );
                    !qprime.iter_end( qp );
                    qprime.iter_next( qp ) ) {
                    // Mark pp, qp for processing if they haven't already been done.
                    if( !G.contains_pair( pp, qp ) ) {
                        Z.add_pair( pp, qp );
                    } // if
                } // for
            } // for
        } // for
    } // else
} // while

Now, compute $E$ from $D$.
$G$.complement();
// And use it to compress the DFA.
compress( $G$ );
assert( class_invariant() );
return( *this );
20 Hopcroft's algorithm

User function: DFA::min_Hopcroft

Files: min-hop.cpp

Uses: CRSet, DFA, State, StateEqRel, StateSet

Description: Member function min_Hopcroft implements Hopcroft's \( n \log n \) minimization algorithm, as presented in [Wat93b, Algorithm 4.8].

Implementation: The member function uses some encoding tricks to effectively implement the abstract algorithm. The combination of the out-transitions of all of the States is stored in a CRSet C. Set \( L \) from the abstract algorithm is implemented as a mapping from States to int (an array of int is used). Array \( L \) should be interpreted as follows: if State \( q \) a representative, then the following pairs still require processing (are still in abstract set \( L \)):

\[(q, C_0), \ldots, (q, C_{L(q) - 1})\]

The remaining pairs do not require processing:

\[(q, C_{L(q)}), \ldots, (q, C_{|C|-1})\]

This implementation facilitates quick scanning of \( L \) for the next valid State-CharRange pair.

```c++
/* (c) Copyright 1994 by Bruce W. Watson */
// $Revision: 1.2 $
// $Date: 1994/08/15 14:00:05 $
#include "crset.h"
#include "state.h"
#include "stateset.h"
#include "st-eqrel.h"
#include "dfa.h"

DFA& DFA::min_Hopcroft() {
    assert( class_invariant() );
    // This algorithm requires that the DFA not have any final unreachable States.
    assert( Usefull() );

    auto State q;
    // Keep track of the combination of all of the out labels of State's.
    auto CRSet C;
    for( q = 0; q < Q.size(); q++ ) {
        C.combine( T.out_labels( q ) );
    }
    // Encode set L as a mapping from State to [0,|C|] where:
    // if q is a representative of a class in the partition P, then
    // L (the abstract list) contains
    // (q, C_0), (q, C_1), \ldots, (q, C_{L(q)-1})
    // but not
    // (q, C_{L(q)}), \ldots, (q, C_{|C|-1})
    auto int *const L( new int[Q.size()] );
    for( q = 0; q < Q.size(); q++ ) {
        L[q] = 0;
    }
    // Initialize P to be the total equivalence relation.
    auto StateEqRel P( Q.size() );
    // Now set P to be E_0.
```
P.split( F );

// Now, build the set of representatives and initialize L.
auto StateSet repr( P.representatives() );
if( F.size() <= (Q.size() - P.size()) ) {
    repr.intersection( F );
} else {
    repr.remove( F );
}

// Do the final set up of L
for( repr.iter_start( q ); !repr.iter_end( q ); repr.iter_next( q ) ) {
    L[q] = C.size();
}

// Use a break to get of this loop.
while( 1 ) {
// Find the first pair in L that still needs processing.
    for( q = 0; q < Q.size() && !L[q]; q++ );

// It may be that we're at the end of the processing.
    if( q == Q.size() ) {
        break;
    } else {
// Mark this element of L as processed.
        L[q]--;  

// Iterate over all eq. classes, and try to split them.
        auto State p;
        repr = P.representatives();
        for( repr.iter_start( p ); !repr.iter_end( p );
             repr.iter_next( p ) ) {
// Now split p w.r.t. (q, C(L[q]))
            auto State r( split( p, q, C.iterator( L[q] ), P ) );
// r is the representative of the new split of the
// eq. class that was represented by p.
            if( r != Invalid ) {
// p and r are the new representatives.
// Now update L with the smallest of
// [p] and [r].
                if( P.equiv_class( p ).size() < P.equiv_class( r ).size() ) {
                    L[p] = L[q];
                    L[r] = C.size();
                } else {
                    L[r] = C.size();
                } // if
            } // if
        } // for
    } // while

// L is no longer needed.
delete L;

// We can now use P to compress the DFA.
compress( P );

assert( class_invariant() );
return( *this );
21 A new minimization algorithm

User function: DFA::min_Watson

Files: min-bww.cpp

Uses: CRSet, DFA, State, StateEqRel, SymRel

Description: Member function min_Watson implements the new minimization algorithm appearing in [Wat93b, Sections 4.6-4.7]. The algorithm computes the equivalence relation $E$ (on states) from below. The importance of this is explained in [Wat93b, p. 16].

Implementation: Function min_Watson is an implementation of Algorithm 4.10 (of [Wat93b]). The helper function are_eq is an implementation of the second algorithm appearing in Section 4.6 of [Wat93b]. Function are_eq takes two parameters more than the version appearing in [Wat93b]: $H$ (a StateEqRel) and $Z$ (a SymRel). These parameters are used to discover equivalence (or distinguishability) of States earlier than the abstract algorithm would.

Performance: Memoization in function are_eq would provide a great speedup.

```c++
#include "state.h"
#include "erset.h"
#include "symrel.h"
#include "st-eqrel.h"
#include "dfa.h"
#include <assert.h>

// The following is function equiv from Section 4.6 of the min. Taxonomy.
int DFA::are_eq(State p, State q, SymRel& S, const StateEqRel& H, const SymRel& Z) const {
    if (S.contains_pair(p, q) || H.equivalent(p, q)) {
        // p and q are definitely equivalent.
        return(1);
    } else if (!Z.contains_pair(p, q)) {
        assert(!S.contains_pair(p, q));
        assert(!H.equivalent(p, q));
        // p and q were already compared (in the past) and found to be
        // inequivalent.
        return(0);
    } else {
        assert(!H.equivalent(p, q));
        assert(Z.contains_pair(p, q));
        // Now figure out all of the valid out-transitions from p and q.
        auto CRSet C(T.out_labels(p));
        C.combine(T.out_labels(q));
        // Just make sure that p and q have the same out-transitions.
        auto int it;
        for (it = 0; !C.iter_end(it); it++) {
            if (T.transition_on_range(p, C.iterator(it)) == Invalid)
                if (T.transition_on_range(q, C.iterator(it)) == Invalid)
                    // There's something that one transitions on, but
                    // the other doesn't
                    return(0);
        }
        // if
    }
    // p and q have out-transitions on equivalent labels.
    // Keep track of whether checking needs to continue.
    S.add_pair(p, q);
    for (it = 0; !C.iter_end(it); it++) {
        // for
    }
```
```cpp
auto State pdest( T.transition_on_range( p, C.iterator( it ) ) );
auto State qdest( T.transition_on_range( q, C.iterator( it ) ) );
if( !are_eq( pdest, qdest, S, H, Z ) ) {
    // p and q have been found distinguished.
    S.remove_pair( p, q );
    return( 0 );
}
} // for

// p and q have been found equivalent.
S.remove_pair( p, q );
return( 1 );

DFA& DFA::min_Watson() {
    assert( class_invariantO );
    assert( Useful() );

    // (Symmetrical) State relation S is from p.14 of the min. Taxonomy.
    auto SymRel S;
    S.set_domain( Q.size() );

    // H is used to accumulate equivalence relation E.
    auto StateEqRel H( Q.size() );
    // Start with the identity since this is approximation from below
    // w.r.t. refinement.
    H.identity();

    // Z is a SymRel containing pairs of States still to be considered.
    auto SymRel Z;
    Z.set_domain( Q.size() );
    Z.identity();
    // We will need the set of non-final States to initialize Z.
    auto StateSet nonfinal( F );
    nonfinal.complement();
    Z.add_pairs( F, nonfinal );
    // Z now contains those pairs that definitely do not need comparison.
    Z.complement();
    // Z initialized properly now.

    auto State p;
    // Consider each p.
    for( p = 0; p < Q.size(); p++ ) {
        auto State q;
        // Consider each q that p still needs to be compared to.
        for( Z.image( p ).iter_start( q ); !Z.image( p ).iter_end( q ); Z.image( p ).iter_next( q ) ) {
            // Now compare p and q.
            if( are_eq( p, q, S, H, Z ) ) {
                // p and q are equivalent.
                H.equivalize( p, q );
            } else {
                // Don't do anything since we aren't computing
                // distinguishability explicitly.
                } } // for

            // Comparing q to p is the same as comparing [q] and [p]
            // all at once.
            // Mark them as such.
            Z.remove_pairs( H.equiv_class( p ), H.equiv_class( q ) );
        } // for
    compress( H );
}
assert(class_invariant());
return(*this);
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