Universal Intermittent Properties of Particle Trajectories in Highly Turbulent Flows

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We present a collection of eight data sets from state-of-the-art experiments and numerical simulations on turbulent velocity statistics along particle trajectories obtained in different flows with Reynolds numbers in the range $R_A \in [120:740]$. Lagrangian structure functions from all data sets are found to collapse onto each other on a wide range of time lags, pointing towards the existence of a universal behavior, within present statistical convergence, and calling for a unified theoretical description. Parisi-Frisch multifractal theory, suitably extended to the dissipative scales and to the Lagrangian domain, is found to capture the intermittency of velocity statistics over the whole three decades of temporal scales investigated here.

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Understanding the statistical properties of particle tracers advected by turbulent flows is a challenging theoretical and experimental problem [1,2]. It is a key ingredient for the development of stochastic models [3,4], in such diverse contexts as turbulent combustion, industrial mixing, pollutant dispersion, and cloud formation [5]. The main difficulty of Lagrangian investigations, following particle trajectories, stems from the necessity to resolve the wide range of time scales driving different particle behaviors: from the longest $T_L$, given by the stirring mechanism, to the shortest $\tau_\eta$, typical of viscous dissipation. Indeed the ratio $T_L/\tau_\eta \sim R_A$ grows with the Taylor Reynolds number $R_A$ that varies up to few thousands in laboratory flows. Some aspects of Lagrangian statistics have been experimentally measured: particle accelerations [2], velocity fluctuations in the inertial range [6,7], and two-particle dispersion [8,9]. Others, connected to the entire range of motions, have long been restricted to numerical simulations [10–14]. A fundamental open question is connected to intermittency, i.e., the observed strong deviations from Gaussian statistics, becoming larger and larger when considering fluctuations at smaller and smaller scales. Additionally, the dependency of velocity statistics at various temporal scales on large scale forcing and boundary conditions is the so-called problem of universality. Thus, universality features are linked to the degree of anisotropy and nonhomogeneities of turbulent statistics [15]. Similar problems have already been explored measuring the velocity fluctuations in the laboratory frame (Eulerian statistics), where clear evidence of universality has been obtained [16]. To build a general theory of turbulent statistics, universality is the first requirement and, if proved, may open the possibility for effective stochastic modeling [17] in many applied situations. This Letter is aimed at inves-
tivating intermittency and universality properties of velocity temporal fluctuations by quantitatively comparing data obtained from the most advanced laboratory [6–8] and numerical [10–13,18] experiments. The main outcomes of our analysis are twofold. First, we show that data collapse on a common functional form, providing evidence for universality of velocity fluctuations—up to moments currently achievable with high statistical accuracy. At intermediate and inertial scales, data show an intermittent behavior. Second, we propose a stochastic phenomenological modelization in the entire range of scales, using a multifractal description linking Eulerian and Lagrangian statistics.

We analyze the probability distribution of velocity fluctuations at all scales, focusing on moments of these distributions, namely the Lagrangian velocity structure functions (LVSF) of positive integer order \( p \):

\[
S_i^{(p)}(\tau) = \langle [v_i(t + \tau) - v_i(t)]^p \rangle = \langle (\delta_x v_i)^p \rangle,
\]

where \( i = x, y, z \) are the velocity components along a single particle path, and the average is defined over the ensemble of trajectories. As stationarity and homogeneity are assumed, moments of velocity increments only depend on the time lag \( \tau \). In the inertial range, for \( \tau \ll \tau < T_L \), nonlinear energy transfer governs the dynamics. Thus, from a dimensional viewpoint, only the scale \( \tau \) and the average energy dissipation rate for unit mass \( \epsilon \) should matter for the structure function behavior. The only admissible choice is \( S_i^{(p)}(\tau) \sim (\epsilon \tau)^{p/2} \), but it does not take into account the fluctuating nature of energy dissipation. Empirical studies have indeed shown that the tails of the probability density functions of \( \delta_x v \) become increasingly non-Gaussian at decreasing \( \tau/T_L \). In terms of moments of the velocity fluctuations, intermittency reveals itself in the anomalous scaling exponents, i.e., a breakdown of the dimensional law for which we have that

\[
S_i^{(p)}(\tau) \sim \tau^{\xi(p)},
\]

with \( \xi(p) \neq p/2 \). Notice that when dissipative effects dominate, typically for scales \( \tau \sim \tau \eta \) and smaller, the power-law behavior (2) is no longer valid, and refined arguments have to be employed, as we will see in the following.

The statistics of velocity fluctuations at varying time lag \( \tau \) can be quantitatively captured by the logarithmic derivatives of \( S_i^{(p)}(\tau) \) versus \( S_i^{(2)}(\tau) \) [19–21]. This defines the local scaling exponents

\[
\xi_i(p, \tau) = \frac{d \log S_i^{(p)}(\tau)}{d \log S_i^{(2)}(\tau)}.
\]

For statistically isotropic turbulence, all components are equivalent, so that their spread quantifies the degree of anisotropy present in the flow. The \( \tau \) dependence of \( \xi_i(p, \tau) \) allows for a scale-by-scale characterization of intermittency.

Figure 1 shows the local exponents of order \( p = 4 \) from a collection of eight data sets, see Tables I and II, for different Reynolds numbers. Most of these data sets are new as is the analysis performed here. We focused on the fourth order moment, since it is the highest order achievable with statistical convergence for all data sets. Two observations can be done. First, all data sets show a similar strong variation around the dissipative time \( \tau/\tau \eta \sim O(1) \) that depends on the Reynolds number, and then a clear tendency toward a plateau for larger lags \( \tau > 10\tau \eta \). Second, all data sets, with comparable Reynolds numbers, agree well in the whole range of time lags. The relative scatter increases only for large \( \tau \), due to the combined effects of the lack of statistics, the anisotropy of the flows, and the different values of \( R_L \). In particular, finite volume effects in experimental particle tracking can produce a small—but systematic—downward shift of the points at long-lag times [21,22]. It is worth noticing that error bars estimated from anisotropic contributions decrease by going to small \( \tau \), indicating that isotropy tends to be recovered at sufficiently small scales; i.e., large scale anisotropic contributions become less and less important. In addition, the fact that, at comparable Reynolds numbers, all data sets recover the same behavior by going to smaller and smaller time lags provides a clear indication of Lagrangian universality of the energy cascade. Such an agreement has not been observed before and is comparable with that found for the corresponding Eulerian quantities [16].

The quality of data shown in Fig. 1 opens the possibility of quantitatively testing phenomenological models for LVSF, scale-by-scale. The Parisi-Frisch multifractal (MF) model of the inertial range [23], and its generalization to the dissipative range [24–27], has proved to give a satisfactory description of Eulerian and Lagrangian fluctuations [14,28–30]. It is thus appealing to search for a link between Eulerian and Lagrangian statistics [14,28–30], since this points to a unique interpretation of turbulent fluctuations. Moreover, it would reduce the number of free parameters. According to the MF model, Eulerian velocity increments at inertial scales are characterized by a local Hölder exponent \( h \), i.e., \( \delta_x u \sim r^h \), whose probability \( P(h) \sim r^{3-D(h)} \) is weighted by the Eulerian fractal dimension \( D(h) \) of the set where \( h \) is observed [23]. The dimensional relation \( \tau \sim r/\delta_x u \) bridges Lagrangian fluctuations over a time lag \( \tau \) to the Eulerian ones at scale \( r \). Following Refs. [27,28], it is shown in Ref. [30] how to extend the MF framework to get a unified description at all time scales for Lagrangian turbulence. Accordingly, Lagrangian increments display a continuous and differentiable behavior at the transition from the dissipative to the inertial range,
affecting the results. In particular, for each data set, the largest time lag always satisfies 

\[ \tau < T_L \] 

The minimal time lag is set by the dissipative scale \([14,28,30]\), \(D = \lambda / \eta \), achieved at small time lags where structure functions do become differentiable. Notice that two nonintermittent value \(\zeta(4, \tau) = 2\), achieved at small time lags where structure functions do become differentiable. Notice that two among the DNS are sufficiently resolved to get the mentioned dimensional scaling in the high frequency limit.

\[
\delta_s \nu(h) = V_0 \frac{\tau}{T_L} \left[ \left( \frac{\tau}{T_L} \right)^\beta + \left( \frac{T_L}{\tau} \right)^\gamma \right]^{(2h-1)/\beta(1-h)}, \tag{4}
\]

\(\beta\) being a free parameter controlling the crossover around \(\tau \sim \tau_\eta\), and \(V_0\) the root mean square velocity. In order to get a prediction for the behavior of the LVSF, given by

\[
\langle (\delta_s \nu)^p \rangle \sim \int dh P(h, \tau_\eta) [\delta_s \nu(h)]^p, \tag{5}
\]

we have to consider, in (4), the intermittent fluctuations of the dissipative scale \([14,28,30]\), \(\tau_\eta(h)/T_L \sim R^{2(\eta-1)/(1+h)}\).

The last necessary ingredient is to specify the probability of observing fluctuations of \(h\). This is done in analogy to Eq. (4):

\[
P_h(\tau, \tau_\eta) = Z^{-1}(\tau) \left[ \left( \frac{\tau}{T_L} \right)^\beta + \left( \frac{T_L}{\tau} \right)^\gamma \right]^{(3-D(h))/\beta(1-h)}, \tag{6}
\]

where \(Z\) is a normalizing function \([30]\) and \(D(h)\) is the

\begin{table}[h]
\centering
\begin{tabular}{c c c c c c}
\hline
\textbf{EXP} & \textbf{DNS} & \textbf{TR} & \textbf{Tech.} & \textbf{Ref.} \\
\hline
1 & 124 & 140 & 256 & 1.6 \times 10^6 & PTV [8] \\
2 & 690 & 1024 & 6.0 \times 10^6 & PTV [7] \\
3 & 740 & 600 & 1856 & 9.5 \times 10^3 & AD [6] \\
4 & & 300 & 2048 & 3 \times 10^5 & C [10] \\
5 & & 650 & 2048 & 4 \times 10^5 & N [12] \\
\hline
\end{tabular}
\end{table}

FIG. 1 (color online). Log-lin plot of the fourth order local exponent \(\zeta(4, \tau)\) averaged over velocity components, as a function of the normalized time lag \(\tau/\tau_\eta\). Data sets come from three experiments (EXP) (see Table I) and five direct numerical simulations (DNS) (see Table II). Error bars are estimated from the spread between the three components, except in EXP3 where only two components were measured. Each data set is plotted only in the time range where recognized experimental or numerical limitations are not affecting the results. In particular, for each data set, the largest time lag always satisfies \(\tau < T_L\). The minimal time lag is set by the highest fully resolved frequency. The shaded area displays the prediction obtained by the MF model by using \(D_0(h)\) or \(D_\nu(h)\), with \(\beta = 4\), for a range of \(R_s \in [150:800]\), comparable with the range of \(R_s\) in the data. Notice that the MF predictions have been obtained by fixing equal to 7 the multiplicative constant in the definition of \(\tau_\eta\). The straight dashed line corresponds to the dimensional nonintermittent value \(\zeta(4, \tau) = 2\), achieved at small time lags where structure functions do become differentiable. Notice that two among the DNS are sufficiently resolved to get the mentioned dimensional scaling in the high frequency limit.

\[
\delta_s \nu(h) = V_0 \frac{\tau}{T_L} \left[ \left( \frac{\tau}{T_L} \right)^\beta + \left( \frac{T_L}{\tau} \right)^\gamma \right]^{(2h-1)/\beta(1-h)}, \tag{4}
\]

\(\beta\) being a free parameter controlling the crossover around \(\tau \sim \tau_\eta\), and \(V_0\) the root mean square velocity. In order to get a prediction for the behavior of the LVSF, given by

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\langle (\delta_s \nu)^p \rangle \sim \int dh P(h, \tau_\eta) [\delta_s \nu(h)]^p, \tag{5}
\]

we have to consider, in (4), the intermittent fluctuations of the dissipative scale \([14,28,30]\), \(\tau_\eta(h)/T_L \sim R^{2(\eta-1)/(1+h)}\).

The last necessary ingredient is to specify the probability of observing fluctuations of \(h\). This is done in analogy to Eq. (4):

\[
P_h(\tau, \tau_\eta) = Z^{-1}(\tau) \left[ \left( \frac{\tau}{T_L} \right)^\beta + \left( \frac{T_L}{\tau} \right)^\gamma \right]^{(3-D(h))/\beta(1-h)}, \tag{6}
\]

where \(Z\) is a normalizing function \([30]\) and \(D(h)\) is the
fractal dimension of the support of the exponents $h$. Once the Reynolds number has been specified, we are left with two parameters, the exponent $\beta$ and a multiplicative constant in the definition of $\tau_\eta$, while the function $D(h)$ comes from the knowledge of the Eulerian statistics. Eulerian velocity structure functions (EVSF) have been measured in the past two decades (see Ref. [16] for a data collection) providing a way to estimate the function $D(h)$ based on empirical data. Many functional forms have been proposed in the literature that are consistent with data, up to statistical uncertainties. Eulerian velocity statistics can be measured in terms of longitudinal or transverse fluctuations. Fluid velocity along particle paths is naturally sensitive to both kinds of fluctuations. We thus evaluated the EVSF in (5) using the fractal dimensions $D_{\ell_{\eta}}(h)$ and $D_{\ell}(h)$ obtained by longitudinal [16] and transverse [31] moments of Eulerian fluctuations, respectively.

The shaded area in Fig. 1 represents the range of variation of the MF prediction computed from $D_{\ell_{\eta}}(h)$ or $D_{\ell}(h)$, measured in the Eulerian statistics (see below), and at changing Reynolds numbers. This must be interpreted as our uncertainty. The prediction works very well: all data fall within the shaded area. The role of the parameters is clear. Changing $\beta$ modifies the sharpness and shape of the dip region at $\tau_\eta$ — the larger $\beta$ the more pronounced the dip; while changing the multiplicative constant in the definition of $\tau_\eta$ has no effect on the curve shape, but it rigidly shifts the whole curve along the time axis. Increasing the Reynolds number $R_\lambda$, the flat region at large lags develops a longer plateau. In the limit $R_\lambda \to \infty$ the MF model predicts $\zeta(4) \approx 1.71$ from $D_{\ell_{\eta}}(h)$ and $\zeta(4) \approx 1.59$ from $D_{\ell}(h)$ statistics.

For the Eulerian $D(h)$, we used the following log-Poisson [23] functional form,

$$D(h) = \frac{3(h - h^*)}{\log(\gamma)} \left[ \log\left(\frac{3(h^* - h)}{d^* \log(\gamma)}\right) - 1 \right] + 3 - d^*.$$  

(7)

Different couples of parameters $(h^*, \gamma)$ have been chosen to fit longitudinal and transverse Eulerian fluctuations. The parameter $d^* = (1 - 3h^*)/(1 - \gamma)$ is fixed by imposing the exact relation for third order EVSF. For the longitudinal exponents [16], we used $(h_{\ell}^* = 1/9, \gamma_{\ell} = 2/3)$ [23]. For the transverse exponents, we used $(h_{\ell}^* = 1/9, \gamma_{\ell} = 1/2)$, which fits the data in Ref. [31] (see [32] for details.)

This comprehensive comparison of the best available experiments and direct numerical simulations provides strong evidence of the universality of Lagrangian statistics. One important open question is the effect of a mean flow, as in turbulent jets [33] and wall bounded turbulence, where strong persistence of anisotropy may break the recovery of small-scale universality. We showed that a multifractal description is in good agreement with data, even in the dissipative range where intermittency is significantly increased. The multifractal description captures the intermittency at all scales with only a few parameters, independent of the Reynolds number. This is the universal feature of Lagrangian turbulence revealed by this study. There exists a long debate on the statistical importance of vortex filaments around dissipative time and length scales [23,34]. Simulations [10,20,35] show that the dip region for $\tau \sim \tau_\eta$ can be depleted (enhanced) by decreasing (increasing) the probability of particles being trapped in vortex filaments. The multifractal model is able to capture the intermittency around $\tau_\eta$ with the help of the free parameter $\beta$. Different values of $\beta$ should then correspond to different statistical weights of vortex filaments along particle trajectories. Only further advances in both experimental techniques and numerical power will allow us to test the same questions here addressed also for the higher order statistics.

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The functions $D_{lo}(h)$ and $D_{tr}(h)$ are convex; the strongest fluctuations, corresponding to the smallest Hölder exponent $h$, are realized for $h = h^*_{lo}$ and $h^*_{tr}$, respectively. The maxima of fractal dimensions, $D_{lo}(h^{max}_{lo}) = D_{tr}(h^{max}_{tr}) = 3$, are attained for $h^{max}_{lo} = 0.382$ and $h^{max}_{tr} = 0.57$. Since only the range $h^* \leq h \leq h^{max}$ is relevant to the fit of EVSF of positive order [23], the extremes of integration in Eq. (5) have been set in the interval $[h^*_{lo}, h^{max}_{lo}]$ and $[h^*_{tr}, h^{max}_{tr}]$, respectively. Modifying $h^{max}$ alters the MF prediction for $\tau \sim T_L$, but does not change the behavior of the curves in the inertial range.

