Lagrangian velocity autocorrelations in statistically steady rotating turbulence

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(Received 7 November 2010; revised manuscript received 26 February 2011; published 16 May 2011)

Lagrangian statistics of passive tracers in rotating turbulence is investigated by particle tracking velocimetry. A confined and steadily forced turbulent flow is subjected to five different rotation rates. The PDFs of the velocity components clearly reveal the anisotropy induced by background rotation. Although the statistical properties of the horizontal turbulent flow field are approximately isotropic, in agreement with previously reported results by van Bokhoven and coworkers [Phys. Fluids 21, 096601 (2009)], the velocity component parallel to the (vertical) rotation axis gets strongly reduced (compared to the horizontal ones) while the rotation is increased. The auto-correlation coefficients of all three components are progressively enhanced for increasing rotation rates, although the vertical one shows a tendency to decrease for slow rotation rates. The decorrelation is approximately exponential. Lagrangian data compare favorably with previously reported Eulerian data for horizontal velocity components but show a different behavior for the vertical velocity components at higher rotation rates.

DOI: 10.1103/PhysRevE.83.056316 PACS number(s): 47.27.−i, 47.32.Ef

I. INTRODUCTION

The influence of the rotation of the Earth on oceanic and atmospheric currents, as well as the effects of a rapid rotation on the flow inside industrial machineries like mixers, turbines, and compressors, are only the most typical examples of fluid flows affected by rotation. Despite the fact that the Coriolis acceleration term appears in the Navier-Stokes equations with a straightforward transformation of coordinates from the inertial system to the rotating noninertial one, the physical mechanisms of the Coriolis acceleration are subtle and not yet fully understood. Several fluid flows affected by rotation have been studied by means of direct numerical simulations (DNS) and analytical models. For example, DNS studies addressing the role of rotation on velocity correlations and mixing [1,2], the role of vertical confinement [3], energy spectra in (decaying) rotating turbulence [4–7], and scaling laws in rotating turbulence [8] have been reported. Several experimental studies of rotating turbulence have been carried out [9–19]. However, quantitative experimental data are rather scarce and purely of Eulerian nature [18,19].

The present work addresses experimentally the topic, focusing on a class of fluid flows of utmost importance: confined and continuously forced rotating turbulence. In recent experimental investigations on (decaying) rotating turbulence quantitative information is extracted by means of particle image velocimetry (PIV) [19] and stereo PIV [18]; the present investigation is based on particle tracking velocimetry (PTV), acquiring Lagrangian statistics of rotating turbulence in laboratory settings.

A useful insight into the structure of a turbulent flow field is represented by the auto-correlations of the velocity field in the Lagrangian frame. The integral time scales derived from the Lagrangian velocity correlations give a rough estimate of the time a fluid particle remains trapped inside a large-scale eddy, and therefore it might be used as a lower bound for the typical lifetime of the large eddies. Lagrangian correlations of velocity have been recognized as the key ingredient of the process of turbulent diffusion since the work by Taylor [20,21]. Since then, the Lagrangian viewpoint has received growing attention; for a recent review, see Ref. [22]. Lagrangian correlations of velocity in nonrotating turbulence were recently measured with an acoustic technique at very high Taylor-based Reynolds number (ReL = 800) and a decay of the correlation coefficients of single velocity components proportional to e−τ/τ0 was proposed, with τ0 comparable to the energy injection time scale [23,24]. The same decay has been observed by Gervais et al. [25], who compared Eulerian and Lagrangian correlations of velocity in a ReL = 320 turbulent flow, also relying on acoustic measurements. Here, some of these issues are addressed for rotating turbulence as measured by means of PTV.

II. EXPERIMENTAL SETUP

The experimental setup consists of a fluid container, made of transparent perspex in order to ensure optical accessibility, equipped with a turbulence generator, and an optical measurement system. A side view of the setup is shown in Fig. 1, and a photograph of the setup partially mounted is shown in Fig. 2. Four digital cameras (Photron Fastcam X-1024 PCI, three of them partially visible in Fig. 2) acquire images of the central-bottom region of the flow domain through the top lid. The fluid is illuminated by means of an LED array composed of 238 Luxeon K2 LEDs (1.4-kW total dissipation and roughly 150 W of light) mounted on a thick aluminium block provided with water-cooling channels. The illumination system and its cooling connections are visible in Fig. 2. These key elements are mounted on a rotating table, so the flow is measured in the rotating frame of reference. The inner dimensions of the container define a flow domain of 500 × 500 × 250 mm3 (length × width × height); note that the free surface deformation is inhibited by a perfectly sealed top lid. The turbulence generator is an adaptation of a well-known electromagnetic forcing system commonly used for shallow-flow experiments [26–28] and currently operational in our laboratory for both shallow flow and rotating turbulence experiments [18,29,30]. The tank is filled with a highly concentrated sodium chloride (NaCl) solution in water, 28.1% brix (corresponding to

1539-3755/2011/83(5)/056316(1)

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25 g NaCl in 100 g of water). The fluid density $\rho_f$ is 1.19 g/cm$^3$ and the kinematic viscosity $\nu$ is 1.319 mm$^2$/s. Two titanium elongated electrodes are placed near the bottom at opposite sidewalls of the container. A remote-controlled power supply (KEPCO BOP 50 8P) is connected to the electrodes and provides a stable electric current of 8.39 A. An array of axially magnetized permanent (neodymium) magnets is placed directly underneath the bulk fluid. Figure 2 reveals the array of magnets before the fluid container is mounted on the table. The magnets have a magnetic field strength of approximately 1.4 T at the center of the magnet surface, and they are arranged following a chessboard scheme, i.e., alternating north and south poles for the magnets top faces. The magnets, kept in position by a polyvinyl chloride (PVC) frame, are fixed on a 10-mm-thick steel plate to increase the density of the magnetic field lines in the fluid bulk. A range of flow scales is forced by using two differently sized magnets, viz., (i) elongated bar magnets, 10 $\times$ 10 $\times$ 20 mm$^3$ in size, and (ii) flat bar magnets, 40 $\times$ 40 $\times$ 20 mm$^3$ in size [18]. With such an arrangement, the largest scales that are forced are comparable with the spacing between adjacent large magnets, i.e., $\mathcal{L}_F = 70$ mm.

The Lagrangian correlations are measured by means of particle tracking velocimetry, making use of the code developed at ETH, Zürich [31–35]. Poly methyl methacrylate (PMMA) particles, with a mean diameter $d_p = 127 \pm 3$ mm and particle density $\rho_p = 1.19$ g/cm$^3$, are used as flow tracers. The concentration of the salt solution is adjusted to match the PMMA density. The Stokes number (St) for these tracers expresses the ratio between the particle response time and a typical time scale of the flow. For the present experiments it can be estimated as $\text{St} = \tau_p/\tau_0 = O(10^{-3})$, where $\tau_p = d_p^2/(18\nu)$ is the particle response time (with $\rho_p/\rho_f = 1$) and $\tau_0$ is the Kolmogorov time scale of the turbulent flow, which values are given in the following section. The chosen seeding particles can thus be considered as passive flow tracers both in terms of buoyancy and inertial effects. An accurate calibration of the measurement system on a 3D target, followed by the optimization of the calibration parameters on seeded flow images, permits retrieval of the 3D positions of the particles with a maximum error of 9 $\mu$m in the horizontal directions and 18 $\mu$m in the vertical one. The data are then processed in the Lagrangian frame, where the trajectories are filtered to remove the measurement noise produced by the positioning inaccuracy: Third-order polynomials are fitted along limited segments of the trajectories around each particle position (for details, see Ref. [36]). From the coefficients of the polynomial in each point, the 3D time-dependent signals of position and velocity are extracted. With the present setup, up to 2500 particles per time step have been tracked on average in a volume with size 100 $\times$ 100 $\times$ 100 mm$^3$, thus roughly 1.5$\mathcal{L}_F$ along each coordinate direction.

A detailed description of the experimental setup and the data processing routines, together with an in-depth characterization of the flow, can be found in Ref. [37].

### III. CHARACTERIZATION OF THE FLOW

The flow is subjected to different background rotation rates $\Omega \in [0; 0.2; 0.5; 1.0; 2.0; 5.0]$ rad/s around the vertical $z$ axis. The measurements are performed when the turbulence is statistically steady (measured by the kinetic energy of the flow). The mean kinetic energy of the turbulent flow is then constant in time and decays in space along the upward vertical direction. The flow is fully turbulent in the bottom region of the container where the measurement domain is situated. Eulerian
characterization of the (rotating) turbulent flow with stereo PIV measurements has been reported elsewhere [18].

The values of important flow quantities in the measurement domain are reported in Table I: the root-mean-square (rms) of each velocity component \( u_{x,\text{rms}} \equiv \langle u_x^2 \rangle^{1/2} \) and the ratio of horizontal and vertical rms values \( \xi \equiv 0.5(u_{x,\text{rms}} + u_{z,\text{rms}})/u_{y,\text{rms}} \); the Rossby number \( \text{Ro} \equiv u_{\text{rms}}/(2\Omega L_1^2) \); Ekman number \( \text{Ek} \equiv \nu/(\Omega L_1^2) \), with \( L_1 = 250 \text{ mm} \) the vertical size of the flow domain; and thickness of the Ekman boundary layer \( \delta_{\text{Ek}} \equiv \sqrt{\nu/\Omega} \), for each experiment.

<table>
<thead>
<tr>
<th>( \Omega ) (rad/s)</th>
<th>0</th>
<th>0.2</th>
<th>0.5</th>
<th>1.0</th>
<th>2.0</th>
<th>5.0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Root mean square</td>
<td>( x )</td>
<td>9.6</td>
<td>9.4</td>
<td>9.8</td>
<td>12.0</td>
<td>17.0</td>
</tr>
<tr>
<td>( \langle u_x^2 \rangle^{1/2} ), with ( i = y )</td>
<td>9.6</td>
<td>9.1</td>
<td>9.8</td>
<td>12.1</td>
<td>17.5</td>
<td>12.2</td>
</tr>
<tr>
<td>( \langle u_x^2 \rangle^{1/2} ), with ( i = z )</td>
<td>8.3</td>
<td>7.7</td>
<td>7.8</td>
<td>6.6</td>
<td>7.3</td>
<td>2.2</td>
</tr>
<tr>
<td>( \xi(\sim) )</td>
<td>0.86</td>
<td>0.83</td>
<td>0.80</td>
<td>0.55</td>
<td>0.42</td>
<td>0.17</td>
</tr>
<tr>
<td>( \text{Ro}(\sim) )</td>
<td>( \infty )</td>
<td>0.47</td>
<td>0.20</td>
<td>0.13</td>
<td>0.09</td>
<td>0.02</td>
</tr>
<tr>
<td>( \text{Ek} \times 10^3(\sim) )</td>
<td>( \infty )</td>
<td>10</td>
<td>4</td>
<td>2</td>
<td>1</td>
<td>0.4</td>
</tr>
<tr>
<td>( \frac{\text{Ek}}{\Omega} \text{, mm} \text{)}(\sim) )</td>
<td>( \infty )</td>
<td>2.5</td>
<td>1.6</td>
<td>1.1</td>
<td>0.8</td>
<td>0.5</td>
</tr>
</tbody>
</table>

FIG. 3. Profiles of the rms velocity magnitude \( u_{\text{rms}} \equiv \langle u_x^2 \rangle^{1/2} \) averaged over planes perpendicular to the coordinate direction under consideration, for the nonrotating experiment. The large symbols on the \( z \) profile indicate the corresponding values as measured with stereo PIV during previous experimental campaigns (circles: 4.00 A; triangles: 8.00 A forcing current).

FIG. 4. Eulerian longitudinal integral length scales \( L_z^E \) in the horizontal directions against the rotation rate \( \Omega \) for the midheight horizontal slice, \( z \in [40; 60] \text{ mm} \) (open symbols). The corresponding horizontal length scales measured by means of stereo PIV at \( z = 50 \text{ mm} \) are also indicated on the plot (solid symbols).
IV. RESULTS

We present and discuss here the PDFs of velocity and the Lagrangian autocorrelations of velocity as obtained from the described experiment.

A. Probability distribution functions of velocity

We first report on the PDFs of velocity (each one computed on roughly $4 \times 10^6$ data points). The PDFs are shown in Fig. 5 in linear-logarithmic scale for all experiments together. Using the assumptions of horizontal homogeneity and isotropy, the PDFs of the $x$ and $y$ component are averaged together and shown in the top panel of the figure; in the bottom panel, the PDF of the $z$ component is reported. The background rotation is seen to induce only a slight anisotropy of the horizontal components of velocity (the PDFs for $\Omega = 2.0$ rad/s clearly reflect a larger $u_{rms}$). The most important effect of rotation is seen on the vertical velocity component, for which the standard deviation of the PDF gets strongly damped for $\Omega = 5.0$ rad/s. The distributions for $\Omega \in \{0; 1.0; 5.0\}$ rad/s are in good quantitative agreement with the ones published by van Bokhoven et al. [18] (see Figs. 8 and 14 therein). The PDFs have in both cases almost Gaussian shapes (minor skewness, except for $\Omega = 5.0$ rad/s) and the kurtosis is only slightly larger than the Gaussian value. We found $3.0 \lesssim \langle u_i^4 \rangle / \langle u_i^2 \rangle^2 \lesssim 4.0$, except for the vertical velocity component at $\Omega = 5.0$ rad/s which shows a substantially larger value for the kurtosis. Once more, the latter describes the well-known effect of rotation, which suppresses the fluid motion in the direction of the rotation axis, hence inducing a strong 2D character of the flow field.

B. Lagrangian velocity autocorrelations

The autocorrelation coefficients $R_{ui}(\tau)$ for each velocity component $u_i(t)$ (with $i \in 1, 2, 3$ denoting the $x$, $y$, and $z$ component, respectively), which are functions of the time separation $\tau$, are obtained by averaging over a sufficient number of trajectories and normalizing with the variance of the fluid motion in the direction of the rotation axis, hence inducing a strong 2D character of the flow field.

FIG. 5. PDFs of the velocity components for all experiments, in linear-logarithmic scale. (Top panel) Average of the PDFs of the two horizontal components. (Bottom panel) PDF of the vertical component. The two plots share the same legend.

FIG. 6. Lagrangian autocorrelation coefficients of velocity for all rotating experiments, with time normalized with the Kolmogorov time scale $\tau_\eta$. (Top panel) Average of the correlation coefficients of the horizontal components $u_x$ and $u_y$. (Bottom panel) Correlation coefficient of the vertical component $u_z$. Only one symbol every 10 data points is plotted for readability.
the single component, i.e.:

$$\mathcal{R}_{ii}(t) = \frac{\langle u_i(t) u_i(t + \tau) \rangle}{\langle u_i^2(t) \rangle}. \tag{1}$$

It is also useful to define the three associated integral time scales:

$$T_{ii}^L = \int_0^{\infty} \mathcal{R}_{ii}(\tau) d\tau. \tag{2}$$

For strongly anisotropic turbulence, as the one influenced by fast background rotation, the individual scales in directions parallel and perpendicular to the rotation axis may differ substantially. Their comparison permits quantification of the anisotropy of the large-scale flow.

The Lagrangian autocorrelation coefficients of velocity for all experiments are shown in Fig. 6 with time $\tau$ normalized with the Kolmogorov time $\tau_\eta$. The top panel shows the average of the correlation coefficients of the two horizontal components of velocity; the bottom one shows the correlation coefficient of the vertical velocity component. For times separations $\tau$ longer than $10\tau_\eta$, some of the correlations show a nonperfect statistical convergence, which is due to the limited recording time available with the present camera system (equipped with onboard RAM memory). Despite this, the correlations describe clearly a monotonic influence of rotation: The coefficients get progressively higher for increasing $\Omega$, both for the horizontal components and for the vertical one. Additionally, a stronger Lagrangian autocorrelation is found for the vertical velocity component (relative to those of the horizontal components) than previously reported for the Eulerian temporal velocity correlations [18]. The linear-logarithmic plots reveal that the decorrelation is roughly exponential, at least until the coefficients drop under 0.4, in good agreement with the relevant literature (see, e.g., Refs. [23–25]). The exponential decay of the velocity autocorrelation plays an essential role in some dispersion models, strongly characterizing them [40]. Following Ref. [23], we fit the function $e^{-\tau/\tau_0}$ over all curves, limited to the time interval over which each curve shows a convincing exponential decay. The Lagrangian integral time scales $T_{ii}^L$ are then estimated as the constant $\tau_0$ retrieved from each fit. In order to facilitate the comparison between horizontal and vertical time scales, we average together the two horizontal scales, in view of the symmetry of our flow around the $x$ and $y$ axis (horizontal isotropy). The results are plotted against the rotation rate and compared with the vertical time scale in Fig. 7. Despite the limited accuracy of the estimated Lagrangian integral time scales, the trends summarized in Fig. 7 reflect the results shown in Fig. 6 and allow an easier quantification of the process. The horizontal scale progressively increases with increasing rotation rate (and are of similar size as the earlier reported Eulerian integral time scales [18]). The vertical one, on the contrary, shows a tendency to decrease slightly for $\Omega$ up to 1.0 rad/s, and increases only for higher rotation rates.

V. CONCLUSIONS

We set up an experiment to investigate the statistical properties of a continuously forced statistically steady turbulent flow subjected to different background rotation rates. The flow was first characterized in terms of the velocity rms, Rossby and Ekman numbers. The profiles in the three coordinate directions were inspected, revealing the horizontal homogeneity of the flow and describing the vertical decay of energy due to the increasing distance from the forcing system. The data obtained with a different measurement system in similar experiments (with access to the full range of vertical velocity fluctuations in a horizontal plane) [18] confirm the same vertical decay of energy and reveal that the flow is isotropic at midheight in the measurement domain. The good agreement between the two data sets was also shown in terms of the Eulerian horizontal integral length scales, which are seen to increase substantially for mild background rotation rates and to decrease slightly for higher rotation rates. The influence on the PDFs of the velocity components is shown, revealing the two-dimensionalization process induced by rotation. We then used the PTV data to explore the autocorrelations of the velocity components in the Lagrangian frame in order to quantify the memory of the velocity of fluid parcels along their trajectories. All autocorrelation coefficients are progressively enhanced for increasing rotation rates, although the vertical one first decreases slightly for slow rotation rates. The decorrelation process is found to be approximately exponential. Comparison of the Lagrangian data with the Eulerian measurements from similar rotating turbulence experiments [18] suggests that fluid parcels, being restricted to coherent flow structures, have limited access to vertical velocity variations when the rotation rate is increased. Eulerian measurements would overestimate the sampling over vertical velocity fluctuations. This is particularly shown by the enhanced memory in the Lagrangian vertical velocity autocorrelation compared to its Eulerian counterpart.

ACKNOWLEDGMENTS

This project has been funded by the Netherlands Organisation for Scientific Research (NWO) under the Innovation Research Incentives Scheme Grant No. ESF.6239. The Institute of Geodesy and Photogrammetry and the Institute of...
Environmental Engineering of ETH (Zürich) are acknowledged for making the PTV code available. The authors would like to thank Beat Lüthi and Arkady Tsinober for useful scientific discussions.