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The critical layer in sheared flow

by

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The critical layer in sheared flow

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Critical layers arise as a singularity of the linearized Euler equations when the phase speed of the disturbance is equal to the mean flow velocity. They are usually ignored when estimating the sound field, with their contribution assumed to be negligible. It is the aim of this paper to study fully both numerically and analytically a simple yet typical sheared ducted flow in order to distinguish between situations when the critical layer may or may not be ignored. The model is that of a linear-then-constant velocity profile with uniform density in a cylindrical duct, allowing for exact Green’s function solutions in terms of Bessel functions and Frobenius expansions. It is found that the critical layer contribution decays algebraically in the constant flow part, with an additional contribution of constant amplitude when the source is in the boundary layer, an additional contribution of constant amplitude is excited, representing the hydrodynamic trailing vorticity of the source. This immediately triggers, for thin boundary layers, the inherent convective instability in the flow. Extra care is required for high frequencies as the critical layer can be neglected only together with the pole beneath it. For low frequencies this pole is trapped in the critical layer branch cut.

I. Introduction

Critical layers arise in inviscid shear flows as a mathematical singularity of the linearized Euler equations at points where the phase velocity is equal to the local fluid velocity, and give rise to a branch point of a complex logarithm in the solution. This can be smoothed out by taking into account additional viscous or nonlinear terms in the neighborhood of the singular point (see [1–3]). However, one can avoid adding complexity to the problem by defining a proper branch cut for the complex logarithm [4] based on causality arguments, with the restriction that the Fourier inversion contour in the wavenumber plane should not cross the branch cut.

Critical layer singularities are associated with the continuous (hydrodynamic) spectrum [5,6], and have so far been proved to have an algebraic rather than exponential decay or growth rate, as is the case for swirling flows [7–9].

The reference paper for critical layers in a duct carrying sheared flow has so far been the one by Swinbanks [10] in 1975. Considering the sound field in a duct carrying sheared flow with arbitrary Dirichlet-Neumann boundary conditions, he found that the eigenfunction representation of the pressure field generated by a mass source breaks down at the critical layer. Thus, the normal modes no longer form a complete basis, and one has to also add a contribution from the continuous spectrum. This latter part is only present downstream. In the case of a hard-walled duct with a constant velocity profile except for a thin boundary layer, this contribution comes in, in the worst case scenario when the source is at the critical layer, as a singularity consisting of a simple pole and a logarithmic branch point. Inverting the Fourier transform [11] results in an algebraic decay (as $1/x^3$ for a point mass source, and as $1/x^{1/2}$ for a source of distributed nature). This was recently proved for a numerical solution by Felix and Pagneux [12] (still for hard-walled ducts only).

When it comes to determine the sound field in a lined duct, the critical layer is either explicitly [13] or tacitly [14] ignored in the majority of the cases, assuming its contribution to the total field to be insignificant. Numerical methods
detect the critical layer as a set of spurious eigenvalues clustered on the positive real wavenumber axis [15, 16]. It is our purpose here to investigate the effects of the critical layer for a simple model having as few parameters as possible (see Eq. (2)), and understand the effects linked to it, as well as its various contributions to the total field.

The paper is a study of the field generated by a time-harmonic point mass source in a circular duct with a constant-then-linear mean flow and a constant density profile. This choice is justified in the beginning of section II as the simplest possible scenario where a critical layer singularity occurs. Solutions to the Pridmore-Brown equation are given in terms of Bessel functions for the constant flow and Frobenius series for the constant shear, thus having the necessary tools for constructing the Green’s function for a point mass source. When the source is located in the constant flow part, the Green’s function has an equivalent expression to the one for uniform flow [17], as expected. In Section III we analyse the contributions from the poles, finding for the case when the source is at the critical layer (in the boundary layer) an additional pole on the branch cut [10] with a contribution of constant amplitude. This analysis is then illustrated in section IV with a collection of numerical examples, demonstrating the field of the pole on the branch cut and a comparison with the uniform flow case. We also show here the effects of two additional poles linked to the critical layer, one that always has to be considered together with the branch cut, and another weak convective instability. Motivated by these numerical results, we prove in section V that in the far field the branch cut integral is algebraically decaying as $1/k^4$. Finally, the essentially hydrodynamic nature of the pole on the branch cut is proved in section VI by taking the incompressible limit, showing that its field is the trailing vorticity of the source. A thorough explanation of the effects coming from the choice of source is given in Appendix A.

II. Formulation of the mathematical problem

A. Existence of critical layer singularities

Time-harmonic acoustic perturbations of frequency $\omega$ in sheared flow can be found by Fourier series expansion in the circumferential coordinate $\theta$ and Fourier transformation to the axial coordinate $x$ with wave number $k$. The resulting equation to be solved is known as the Pridmore-Brown equation [18]

$$\ddot{p}'' + \left(\frac{2kU'}{\omega - kU'} + \frac{1}{r} - \frac{\rho'_0}{\rho_0}\right)\dot{p}' + \left(\frac{(\omega - kU)^2}{c_0^2} - k^2 - \frac{m^2}{r^2}\right)\ddot{p} = 0,$$

(1)

where the mean velocity and density are $U(r)$ and $\rho_0(r)$ and the square of the speed of sound is $c_0^2 = \gamma \rho_0 / \rho_0$. For suitable solutions $\ddot{p} = p_m(r,k)$ and amplitudes $A_m(k)$ the physical pressure field is given by the (real part of the) sum over Fourier integrals

$$e^{i\omega t} \sum_{m=-\infty}^{\infty} e^{-im\theta} \int_{-\infty}^{\infty} A_m(k)p_m(r,k) e^{-ikx} \,dk.$$

Well-chosen indentations of the $k$-inversion contour are understood when singularities of any kind along the real axis are to be avoided. In this paper we will be interested in a single $m$-mode, represented by the $k$-integral, for the field of a point source.

Equation (1) contains a regular singularity at $r = r_c$, where $\omega - kU(r_c) = 0$. This singularity is referred to as a critical layer, and leads to a continuous hydrodynamic spectrum. Two linearly independent solutions for $\ddot{p}$ expanded about $r_c$ are

$$\ddot{p}_1(r) = (r - r_c)^3 + O((r - r_c)^4),$$

$$\ddot{p}_2(r) = A\ddot{p}_1(r) \log(r - r_c) + 1 - \frac{1}{3}(k^2 + m^2/r_c^2)(r - r_c)^2 + O((r - r_c)^4),$$

where

$$A = -\frac{1}{3} \left( k^2 + \frac{m^2}{r_c^2} \right) \left( \frac{U''(r_c)}{U'(r_c)} - \frac{\rho'_0(r_c)}{\rho_0(r_c)} - \frac{1}{r_c} \right) - \frac{2m^2}{3r_c^4}. $$

(2)

The log-singularity is removed when the coefficient $A$ is zero. In general, $A$ will be nonzero, even for planar shear (rather than, as is considered here, cylindrical shear) where the $1/r_c$ term in (2) is not present. The notable case when $A$ is identically zero is for linear planar shear of a uniform density fluid. In other words, unless the shear is planar, the density is uniform, and the velocity is either constant or linear, then the log-singularity will in general be present. A relation similar to (2) regarding the existence of the critical layer is mentioned in Ref. [19] for uniform density.
B. Solutions to the Pridmore-Brown equation

Here, we consider a linear shear with constant density in a cylindrical duct, and scale distances on the duct radius \( a \), velocities on the sound speed \( c_0 \), density on the mean density \( \rho_0 \), pressure on \( \rho_0 c_0^2 \) and impedance on \( \rho_0 c_0 \), thus having the duct wall at \( r = 1 \) and

\[
U(r) = \begin{cases} 
M, & 0 < r < 1 - h, \\
M(1 - r)/h, & 1 - h < r < 1,
\end{cases}
\]

with \( M \) the mean flow Mach number. Hence, equation (1) becomes

\[
p'' + \left( \frac{2kU'}{\omega - kU} + \frac{1}{r} \right) p' + \left( (\omega - kU)^2 - k^2 - \frac{m^2}{r^2} \right) p = 0.
\]

(3)

1. Solution within the constant-flow region

The solutions to Eq. (3) are given within the uniform-flow section \( r < 1 - h \) by

\[
p = A J_m(\alpha r) + B Y_m(\alpha r) \quad \text{or equivalently} \quad p = C_1 H_m^{(1)}(\alpha r) + C_2 H_m^{(2)}(\alpha r),
\]

where \( \alpha^2 = (\omega - M k)^2 - k^2 \). Since \( Y_m(z) \), \( H_m^{(1)}(z) \) and \( H_m^{(2)}(z) \) contain log-like singularities, a branch cut needs to be chosen for \( \alpha \), which (for fixed \( \omega \)) leads to two branch cuts in the \( k \)-plane. Branch cuts of Bessel functions are traditionally taken along the negative real \( z \) axis, although they could be taken anywhere using analytic continuation. However, the traditional branch cuts will be fine provided the branch cut chosen for \( \alpha \) means that \( \alpha r \) is never real and negative. Taking branch cuts along \( \alpha^2 = iq \) for \( q \in \mathbb{R}^+ \) gives the additional desirable property that no branch cut crosses the imaginary \( k \) axis for \( \omega \) having a negative imaginary part (see Figure 1a). For \( x < 0 \), the \( k \) inversion contour

\( a \) Undeformed inversion contour

\( b \) Deformed inversion contours

Figure 1. Schematic of the complex \( k \) plane, including branch cuts of \( \alpha \), the critical layer, modes, and integration contours. \( a \) The undeformed causal inversion contour. \( b \) The inversion contour deformed for \( x < 0 (C_- \text{ and } C'_-) \) and \( x > 0 (C_+, C'_+ \text{ and } C''_+) \).

needs to be closed in the upper half plane, giving an inversion contour \( C_- \cup C'_- \) shown in figure 1b, with \( C_- \) being the contribution from the poles in the upper-half plane and \( C'_- \) being the contribution from the \( \alpha \) branch cut. For \( x > 0 \), the \( k \) inversion contour similarly needs to be taken as \( C_+ \cup C'_+ \cup C''_+ \).

However, the branch cuts in the \( \alpha^2 \) plane are removable, at least as far as the Green’s function is concerned. This is because crossing a branch cut sends \( J_m(\alpha r) \) to \( J_m(-\alpha r) = (-1)^m J_m(\alpha r) \), and \( Y_m(\alpha r) \) to \( Y_m(-\alpha r) = A J_m(\alpha r) + B Y_m(\alpha r) \), where \( A \) and \( B \) are constants independent of \( \alpha \) or \( r \) (see Abramowitz & Stegun [20, p.361]). Therefore, if we are interested in the function \( f(r) = C J_m(\alpha r) + D Y_m(\alpha r) \), where constants \( C \) and \( D \) have been chosen so that \( f(r_1) \) and \( f'(r_1) \) take known values, then the function \( f(r) \) will be identical on either side of the branch cut. The integrals around the \( C'_+ \) and \( C''_+ \) contours are therefore identically zero, and so these branch cuts may be ignored.
2. Frobenius expansion for constant shear

For $1 - h < r < 1$, the mean flow becomes $U(r) = M(1 - r)/h$ and the Pridmore-Brown equation is singular at $r = r_c$, where $r_c = 1 - oh/(kM)$ (possibly complex). Substituting $R = r - r_c$ into Eq. (3) for this constant shear gives

$$p_{RR} + \left( \frac{1}{r_c + R} - \frac{2}{R} \right) p_R + \left( \eta^2 R^2 - k^2 - \frac{m^2}{(R + r_c)^2} \right) p = 0,$$

where a subscript $R$ denotes $\text{d}/\text{d}R$ and $\eta = Mk/h$. We pose a Frobenius expansion about this singularity, leading to the two linearly independent solutions:

$$p_1(r) = \sum_{n=0}^{\infty} a_n (r - r_c)^{n+3}, \quad \quad p_2(r) = \frac{1}{3r_c} \left( k^2 - \frac{m^2}{r_c^2} \right) p_1(r) \log(r - r_c) + \sum_{n=0}^{\infty} b_n (r - r_c)^n, \quad (4a)$$

$$a_n = \frac{1}{n(n + 3)} \left[ k^2 a_{n-2} - \eta^2 a_{n-4} - \sum_{q=0}^{n-1} a_{n-1-q} (-1)^q (n + 2 + (m^2 - 1)q)/r_c^{q+1} \right], \quad (4b)$$

$$b_n = \frac{1}{n(n - 3)} \left[ k^2 b_{n-2} - \eta^2 b_{n-4} - \sum_{q=0}^{n-1} b_{n-1-q} (-1)^q (n - 1 + (m^2 - 1)q)/r_c^{q+1} \right] - \frac{1}{3r_c} \left( k^2 - \frac{m^2}{r_c^2} \right) \left( 2n - 3 \right) a_{n-3} + \sum_{q=0}^{n-4} a_{n-4-q} (-1)^q/r_c^{q+1} \right], \quad (4c)$$

$$a_n = b_n = 0, \quad \text{for} \quad n < 0; \quad a_0 = b_0 = 1; \quad b_3 = 0.$$

The branch cut for the log term in (4a) is taken away from the real $r$ axis, so that $p_2(r)$ is a regular function of $r$ for the physically relevant range $r \in [0, 1]$. For varying $k$, the direction of this branch cut therefore changes when the branch point at $r_c$ crosses the interval $[0, 1]$ of the real $r$ axis, leading to a branch cut in the $k$ plane on the real $k$ axis for $k \in [\omega/M, \infty)$. It is this $k$ branch cut that is referred to as the critical layer. For $k$ below the critical layer branch cut, $\text{Im}(r_c) < 0$, and for $k$ above the critical layer branch cut, $\text{Im}(r_c) > 0$. The change in $p_2(r)$ for $k$ crossing the critical layer branch cut from below is therefore

$$\Delta p_2(r) = \begin{cases} -\frac{2\pi i}{3r_c} \left( k^2 - \frac{m^2}{r_c^2} \right) p_1(r), & r < \text{Re}(r_c) \\ 0, & r > \text{Re}(r_c), \end{cases}$$

while $p_1(r)$ remains continuous. We will also, on occasion, use the notation $p_2^{\pm}(r)$ to denote the solution $p_2(r)$ with the branch cut taken in the positive ($+$) or negative ($-$) imaginary $r$ directions, as these will be useful for analytic continuation.

C. Green’s function solution

Green’s function solutions capture all possible physics of the problem, since any arbitrary driving disturbance or initial condition can be applied using them. In this paper we are only concerned with the point mass source Green’s function (see also Appendix A for the relevance of choosing a mass source, rather than, for example, a point force). Nonetheless, the results we obtain using this Green’s function should be seen as, in some sense, general.

The field generated by a point mass source of strength $S = 1$ located at $(x, \theta, r) = (0, 0, r_0)$ is given by

$$G'' + \left( \frac{1}{r} + \frac{2kU'}{\omega - Uk} \right) G' + \left( \omega - Uk \right)^2 - k^2 - \frac{m^2}{r^2} \right) G = -i(\omega - U(r_0)k) \delta(r - r_0),$$

with the Green’s function solution

$$G = -i(\omega - U(r_0)k) \frac{1}{2\pi r_0 W(r_0; \psi_1, \psi_2)} \psi_1(r_<) \psi_2(r_>) \quad (5),$$

where $W = \psi_1 \psi_2 - \psi_1' \psi_2', r_c = \min\{r, r_0\}$, and $r_0 = \max\{r, r_0\}$. The function $\psi_1$ is the solution to the homogeneous Pridmore-Brown equation (3) satisfying $\psi_1(0) = 0$ for $m \neq 0$ and $\psi_1'(0) = 0$ for $m = 0$. The function $\psi_2$ is a solution of the same equation, satisfying the impedance boundary condition

$$iZG' - \omega G = 0 \quad \text{at} \quad r = 1.$$
Both $\psi_1$ and $\psi_2$ are required to be $C^1$ continuous at $r = 1 - h$. We take,

$$
\psi_1 = \begin{cases} 
J_m(\alpha r) & r \leq 1 - h, \\
C_1 p_1(r) + D_1 p_2(r) & r \geq 1 - h,
\end{cases}
$$

(6a)

$$
\psi_2 = \begin{cases} 
A_2 \text{H}_m^{(1)}(\alpha r) + B_2 \text{H}_m^{(2)}(\alpha r) & r \leq 1 - h, \\
C_2 p_1(r) + D_2 p_2(r) & r \geq 1 - h,
\end{cases}
$$

(6b)

where $A_2$, $B_2$, $C_1$ and $D_1$ are chosen to give $C^1$ continuity at $r = 1 - h$, and $C_2$ and $D_2$ are chosen to satisfy the boundary conditions at $r = 1$, which for definiteness we take to be $\psi_2(1) = 1$ and $\psi_2(1) = -i\omega / Z$. This eventually leads to

$$
C_1 = \frac{J_m(\alpha r) p_2' - \alpha J_m'(\alpha r) p_2}{W} \bigg|_{r=1-h}, \\
C_2 = \frac{p'_2 + \frac{i\omega}{Z} p_2}{W} \bigg|_{r=1},
$$

(7a)

$$
D_1 = -\frac{J_m(\alpha r) p_1' - \alpha J_m'(\alpha r) p_1}{W} \bigg|_{r=1-h}, \\
D_2 = -\frac{p'_1 + \frac{i\omega}{Z} p_1}{W} \bigg|_{r=1},
$$

(7b)

$$
\left( \begin{array}{c} A_2 \\ B_2 \end{array} \right) = \frac{i \pi (1 - h)}{4W(1)} \left( \begin{array}{cc} \alpha \text{H}_m^{(2)'}(\alpha r) & -\text{H}_m^{(2)}(\alpha r) \\ -\alpha \text{H}_m^{(1)'}(\alpha r) & \text{H}_m^{(1)}(\alpha r) \end{array} \right) \left( \begin{array}{cc} p_1' & p_2' \\ p_1 & p_2 \end{array} \right) \bigg|_{r=1-h} \left( \begin{array}{c} p'_2 - p_2 \\ p'_1 \end{array} \right) \bigg|_{r=1} \left( \begin{array}{c} 1 \\ -i\omega / Z \end{array} \right),
$$

(7c)

where $\tilde{W}(r) = p_1(r) p_2'(r) - p_1'(r) p_2(r)$, and we have used the identity $W(\text{H}_m^{(1)}(\alpha r), \text{H}_m^{(2)}(\alpha r)) = -4i/(\pi r)$ from Abramowitz & Stegun [20] for the final line. The function $\tilde{W}(r)$ may be calculated directly by substituting into (1), to give

$$
\tilde{W}' + \left( \frac{1}{r} + \frac{2k U'}{\omega - UK} \right) \tilde{W} = 0, \quad \Rightarrow \quad \tilde{W} = \tilde{W}_0 \frac{(\omega - UK)^2}{r},
$$

where $\tilde{W}_0$ is a constant. From the normalization of $p_1$ and $p_2$ used in (4a,b), the constant $\tilde{W}_0$ may be determined by considering the limit $r \to r_\infty$, giving

$$
\tilde{W}_0 = \frac{-3r_c h^2}{U_0^2 k^2} \quad \Rightarrow \quad \tilde{W}(r) = -3r_c \frac{r_c - r}{r_c}.
$$

(8)

We now consider the two cases $r_0 < 1 - h$ and $r_0 > 1 - h$ separately, before ultimately combining them.

1. **Green’s function for $r_0 < 1 - h$**

In this case, the source is in the constant flow region, so that $\psi_1(r_0)$ and $\psi_2(r_0)$ are given in terms of Bessel functions by (6a) and (6b). Expanding $W(r_0; \psi_1, \psi_2)$ in (5) in this case and making further use Bessel function identities from Ref. 20, we finally arrive at

$$
G = \frac{-i(\omega - U_0 k)}{2\pi(1 - h) Q} \psi_1(r_\infty) \psi_2(r_\infty),
$$

where $Q = \tilde{W}(1-h) \tilde{W}(1) (C_1 D_2 - C_2 D_1)$, so that

$$
Q = \left( J_m(\alpha r) p'_1 - \alpha J'_m(\alpha r) p_1 \right) \bigg|_{r=1-h} \left( p'_2 + \frac{i\omega}{Z} p_2 \right) \bigg|_{r=1},
$$

(9)

$$
\begin{eqnarray}
Z_1 &=& \left[ p'_2(1) + \frac{i\omega}{Z} p_2(1) \right] p_1(1-h) - \left[ p'_1(1) + \frac{i\omega}{Z} p_1(1) \right] p_2(1-h) \\
&=& \left[ p'_2(1) + \frac{i\omega}{Z} p_2(1) \right] p_1(1-h) - \left[ p'_1(1) + \frac{i\omega}{Z} p_1(1) \right] p_2(1-h),
\end{eqnarray}
$$

(10)

and we observe that by setting $h = 0$ we recover the Green’s function for uniform flow from Ref. [17].
2. Green’s function for \( r_0 > 1 - h \)

If \( r_0 > 1 - h \), the Green’s function source is located within the boundary layer. In this case, the Green’s function is given by (5), with \( W(r_0; \psi_1, \psi_2) = (C_1D_2 - C_2D_1)\tilde{W}(r_0) \). Using (7a), (7b) and (8) gives

\[
G = \frac{-i(\omega - U(r_0))k}{2\pi r_0}\tilde{W}(1)\tilde{W}(1 - h)\frac{\psi_1(r_\sim)\psi_2(r_\sim)}{W(r_0)Q}e^{-ikx},
\]

with \( Q \) as defined in (9).

3. Greens function for arbitrary \( r_0 \)

Note that the previous two sections’ results for \( r_0 > 1 - h \) and \( r_0 < 1 - h \) may be combined by defining \( r^* = \max\{r_0, 1 - h\} \) and setting

\[
G = \frac{\omega - U(r^*)k}{2\pi r^*}\tilde{W}(1)\tilde{W}(1 - h)\frac{\psi_1(r_\sim)\psi_2(r_\sim)}{Q}e^{-ikx},
\]

with \( Q \) being given by (9).

### III. Contribution from poles

As described in the previous section and illustrated schematically in Figure 1, the Green’s function solution \( G \) after Fourier inversion will consist of a sum of residues of poles and an integral around the critical layer branch cut. In this section we investigate the contribution from the poles.

Since the only poles of \( G(r; r_0) \) come from zeros of the denominator of (11), there are two possibilities. If \( Q = 0 \) (implying that \( C_1D_2 - C_2D_1 = 0 \)), then we have a mode in the normal sense, in that both \( \psi_1 \) and \( \psi_2 \) satisfy both boundary conditions at \( r = 0 \) and \( r = 1 \). These poles’ contribution to the Fourier integral is (with the contour in the positive sense around the pole)

\[
\frac{\omega - U(r^*)k}{2\pi r^*}\tilde{W}(1)\tilde{W}(1 - h)\frac{\psi_1(r_\sim)\psi_2(r_\sim)}{\partial Q/\partial k}e^{-ikx}.
\]

Note that the inversion contour goes around poles in the positive sense for \( x < 0 \) and in the negative sense for \( x > 0 \).

If the source is in the boundary layer, a second type of singularity is possible for which \( \tilde{W}(r_0) = 0 \). Since \( p_1 \) and \( p_2 \) have been chosen to be linearly independent, this can only happen at a singular point of the Pridmore–Brown equation; i.e. when \( r_0 = r_c \). At this point, we find

\[
G(r; r_0) = \frac{\psi_1(r_\sim)\psi_2(r_\sim)}{C_1D_2 - C_2D_1} \left[ \frac{-i\omega k_0}{6\pi(1 - r_0)^2r_0} \left( \frac{1}{k - k_0} + \left( 3 - \frac{1}{r_0} \right) \frac{1}{k_0} + O(k - k_0) \right) \right],
\]

where

\[
k_0 = \frac{\omega h}{(1 - r_0)M},
\]

so that there is a pole on the branch cut at \( k = k_0 \).

The contribution from this pole is less than straightforward to calculate, since it is tied up with the integral around the critical layer branch cut. The integration contour we must use is shown in figure 2 (after having been collapsed onto the branch cut), and the residue of the pole is different below and above the branch cut. The integral required is

\[
I = \frac{1}{2\pi} \int_{C_1 \cup C_3} (G_+(r, k) - G_-(r, k)) e^{-ikx} dk + \frac{1}{2\pi} \int_{C_2} G_+(r, k) e^{-ikx} dk - \frac{1}{2\pi} \int_{C_2} G_-(r, k) e^{-ikx} dk,
\]

where \( G_+(r, k) = \lim_{\epsilon \to 0^+} G(r, k + i\epsilon) \) and \( G_-(r, k) = \lim_{\epsilon \to 0^-} G(r, k - i\epsilon) \) are the Greens’ function evaluated above and below the branch cut respectively. (In effect, \( G_\pm \) is with \( p_2^\pm(r) \) taken in place of \( p_2(r) \).) Taking the pole at \( k_0 \) given in (12) to be \( p_+^\pm(r)/(k - k_0) \) evaluated above the branch cut and \( p_-(r)/(k - k_0) \) evaluated below the branch cut, we would like to eliminate the \( C_\mp \) contours by removing the pole and integrating along the branch cut, yielding

\[
I' = \frac{1}{2\pi} \int_{\infty}^{\infty} \left( G_+(r, k) - \frac{P_+(r)e^{-\mu(k - k_0)}}{k - k_0} - G_-(r, k) + \frac{P_-(r)e^{-\mu(k - k_0)}}{k - k_0} \right) e^{-ikx} dk,
\]
where $\mu > 0$ is a positive real constant chosen to maintain the exponential decay of the integrand as $k \to \infty$. The integrals $I'$ and $I$ are related by

$$I = I' + \frac{1}{2\pi} \int_{C_1 \cup C_2 \cup C_3} \frac{P_+(r) - P_-(r)}{k - k_0} e^{-ikx - \mu(k-k_0)} \, dk$$

$$+ \frac{1}{2\pi} \int_{C_+} \frac{P_+(r)}{k - k_0} e^{-ikx - \mu(k-k_0)} \, dk - \frac{1}{2\pi} \int_{C_-} \frac{P_+(r)}{k - k_0} e^{-ikx - \mu(k-k_0)} \, dk.$$

Since the first integral is exponentially small in the lower half of the $k$ plane as $k \to \infty$ for $x > 0$, and contains no poles other than $k_0$, we may deform the contour of integration into the lower-half $k$-plane onto a steepest descent contour. The final two integrals are meromorphic within the region bounded by their contours of integration, and therefore combine to give $-iP_+(r) e^{-ik_0x}$ by the residue theorem. Setting $k = \omega/U + \xi/(i + \mu/x)$, so that real $\xi$ describes the steepest descent contour, finally yields

$$I = I' - iP_+(r) e^{-ik_0x} + \frac{P_+(r) - P_-(r)}{2\pi} e^{-i\pi x + \mu(k_0 - \xi)} E\left(i\left(\frac{\omega}{\mu} - k_0\right)(x - i\mu)\right),$$

where

$$E(z) = \int_0^\infty \frac{e^{-t}}{z + t} \, dt = e^z E_1(z),$$

and $E_1$ is the exponential integral function [20, §5.1] defined by

$$E_1(z) = \int_{z}^{\infty} \frac{e^{-t}}{t} \, dt \quad \text{for} \quad |\arg(z)| < \pi \quad \text{and a branch cut along the negative real axis.}$$

Since $E(z) = 1/(z) + O(1/z^2)$ as $z \to \infty$, $I - I'$ is dominated in the far field by the $e^{-ik_0x}$ term which remains $O(1)$ as $x \to \infty$.

Numerically integrating $E(z)$ is relatively easy due to the exponential non-oscillatory decay of the integrand for real $x$ (and indeed $E_1$ is a standard special function). Evaluating the remaining integral $I'$ is computationally more expensive but otherwise poses no major difficulty.

**IV. Numerical results**

In this section, a number of numerical results are presented to illustrate the method described so far, and to inform the further analytical discussion that follows. Throughout this section we have taken a mean flow Mach number $M = 0.5$ and an impedance of resistance $\text{Re}(Z) = 2$. Whenever relevant, we have investigated stability by a Briggs-Bers analysis [23, 24], with a simple impedance model of Helmholtz Resonator type.
Numerical experiments reveal a downstream propagating instability pole (denoted $k_+$) in the upper half $k$ plane just above the critical layer branch cut, and another pole (denoted $k_-$) closely related to the critical layer. The $k_-$ pole is situated below the branch cut for high frequencies, and leaks to the other Riemann sheet for frequencies below a critical value (which depends on the impedance of the boundary and the thickness of the boundary layer). In addition to these, for $r_0 > 1 - h$ there is also the pole $k_0$ present on the branch cut. A schematic of this situation is shown in Figure 3. It is insightful to compare the order of magnitude of the contributions from these modes, and the integral around the critical layer branch cut. Such a comparison is shown in Figure 4. As can be seen from Figure 4a,f, the branch cut ($I'$) and the $k_-$-field are important individually, and both are of the same order of magnitude as the instability ($k_+$), but when summed they almost cancel each other out (see Figure 4b). This leads to an important observation: ignoring the critical layer but including the residue of $k_-$ in the modal sum produces serious errors in the total field. Moreover, the sum of the branch cut integral $I'$ and the $k_-$ field is also almost totally cancelled out by the exponential integral $E(\cdot)$ resulting from the removal of the $k_0$ pole from the branch cut integral, with what remains being strongly localized about the mass source (Figure 4c).

To sum up, we can split the total pressure field into an acoustic part (obtained by summing up the acoustic modes), the field of the branch cut (in which we include any $k_-$ mode, $k_0$ mode, and $I'$ and $E(\cdot)$ terms) and the contribution of the instability mode $k_+$. The field of the critical layer comes from integrating along the branch cut and adding the residue of $k_-$, in case this is not already “captured” in the integral, and we can observe the fast decay of this in Figure 4c. However if the source is in the boundary layer, we have in addition to this the field generated by $k_0$, which is described in detail in section VI. Not too far downstream, we can see that for certain parameter values, the branch cut ($I'$) and the poles related to it ($k_-$ and $k_0$) can have a contribution of the order of magnitude of that of the instability pole (Figure 4).

Further on we compare direct numerical integration along the Fourier inversion contour to the solution obtained by summing the contribution from the acoustic poles. The direct numerical integration was performed using a 4th-order-accurate integrator on equally-spaced points. For $x < 0$ the contour was deformed into the upper-half $k$-plane, and for $x > 0$ into the lower-half $k$-plane, in order to speed up convergence. This numerical integration includes only the effect of the acoustic poles, and ignores the contribution from the critical layer branch cut.

For summing the contribution of poles, all poles with $\text{Im}(k) < 400$ were used. This converged rapidly for $x \neq 0$, although the number of poles was insufficient to determine the solution at $x = 0$, as shown by the oscillatory radial behaviour at $x = 0$ in Figure 5. One of the advantages of the modal approach is that it separates modal and non-modal behaviour, and allows us to compare the magnitude of the effect of the critical layer. Besides that, it is stable in the far field for high frequencies (see Figure 5d) and predicts with better accuracy the acoustic field.

It is clear from Figures 5 and 6 that there is an instability mode present. For thicker boundary layers, this instability has a small growth rate (we remark that, in Figure 5a, there is a growth in amplitude upon adding the residue $k_+$ (iv))
Figure 4. Comparison of the five different contributions to the Greens function from around the branch cut: a) the integral around the branch cut with the $k_0$-pole removed ($I'$); b) figure a + the pole below the branch cut; c) figure b + the $E(z)$ term in (15) due to the integral around the branch cut of the pole removal terms. d) the pole above the branch cut; e) the $k_0$-pole on the branch cut; f) the pole below the branch cut in isolation. The plots are of $|G(x, r)|$, with different scales as shown beside each plot ($Z = 2 + i, \omega = 10, h = 0.05, r_0 = 0.96$).
Figure 5. The pressure field in $(x, r)$ plane computed by (in the order L-R 1st line, L-R 2nd line): (i) direct numerical Fourier inversion (ignoring the branch cut contribution); (ii) summing the acoustic poles; (iii) summing the acoustic poles and adding the branch cut integrals and $k_0$ and $k_-$ poles; (iv) summing all contributions (iii) plus the hydrodynamic pole $k_+$.

to the field in (iii)) and may further turn into a neutrally stable, or possibly decaying mode. When the source is in the boundary layer, the instability is immediately excited, as for a vortex sheet Helmholtz instability from a trailing edge. When the source is outside the boundary layer, the excitation is moved further downstream (see Figure 6c), as for a free vortex sheet [25–27].

The critical layer is negligible when the source is in the mean flow, the pressure field being almost equivalent to that in a uniform flow with Ingard–Myers boundary condition [28, 29] (see Eq. (10) and Figure 7). However, the critical layer becomes important when the source is in the boundary layer, and indeed it is obviously dominant in Figure 6b where all the acoustic modes are cut-off.

V. Asymptotic evaluation of the branch cut contribution

In this section, we aim to make further analytical predictions about the contribution to the overall Green’s function from the branch cut. For example, we aim to explain why such significant cancellation was seen in Figure 4 between the contribution from the branch cut ($I'$) and the residue of the $k_-$ pole.

The contribution of the branch cut is seen by taking the large $x$ limit of the Fourier inversion integral around it, while subtracting the residue of the $k_0$ pole if the source is in the boundary layer. For $r_0 < 1 - h$, this integral is

$$I = \frac{1}{2\pi} \int_{\rho_0/M}^{\infty} (G_+(r, k) - G_-(r, k)) e^{-ikx} \, dk,$$

(16)
Figure 6. Total pressure field in \((x, r)\) plane for (a)-(b) \(\omega = 10, m = 24, Z = 2 - i, h = 0.05\); (c)-(d) \(\omega = 10, m = 0, Z = 2 + i, h = 0.001\), and different source locations.

Figure 7. The Green’s function with source in mean flow region for (left) uniform flow with Ingard-Myers condition; (right) constant-then-linear flow profile \((\omega = 10, m = 0, Z = 2 - i, h = 0.001, r_0 = 0.4)\).
and is given by (14) for \( r_0 > 1 - h \). In the large \( x \) limit, we may therefore deform the integration contour into the steepest descent contour \( k = \omega/M - i\xi \) with \( \xi > 0 \), and then apply Watson’s lemma to obtain the asymptotic behaviour of this integral. However, in deforming the contour we must be careful not to allow the contour to cross any poles. Figure 8 shows an example of such a deformation. The \( k^- \) pole, being below the branch cut, is only a pole of \( G^- \) in (16). The pole contribution from integrating around this pole is therefore the negative of the pole contribution from \( k^- \) in the modal sum of all downstream-propagating modes, and therefore the two exactly cancel. In effect, this deformation of the branch cut contour onto the steepest descent contour removes the \( k^- \) pole from the modal sum.

We hypothesize that there are no poles of \( G^+ \) that are crossed in this contour deformation, since such poles would necessarily lead to a discontinuous solution in \( r \). We are therefore left with just the integral along the steepest descent contour, which we then expect to be significantly smaller in magnitude than the integral along the critical layer branch cut; this expectation is formalized below. In the case \( r_0 > 1 - h \), the integral \( I \) consists of a pole contribution from \( G^+ \) at \( k = k_0 \) but otherwise the pole-removal as in (14) is not necessary when we deform the contour to the steepest descent (SD) contour. So we have

\[
I = \frac{1}{2\pi} \int_{SD} (G^+(r,k) - G^-(r,k)) e^{-ikx} \, dk - iP^+(r) e^{-ik_0x},
\]

The result is the same as for the \( r_0 < 1 - h \) case with the addition of the pole at \( k = k_0 \).

In conclusion, the contribution from any poles below the branch cut, together with the integral along the branch cut itself, consists of the pole contribution at \( k_0 \) in the case \( r_0 > 1 - h \), and the steepest-descent contribution

\[
I_{sd} = \frac{e^{-i\omega x/M}}{2\pi i} \int_0^\infty (G^+(r,\omega/M - i\xi) - G^-(r,\omega/M - i\xi)) e^{-\xi x} \, d\xi.
\]

If, to leading order for small \( \xi \),

\[
G^+(r,\omega/M - i\xi) - G^-(r,\omega/M - i\xi) \sim A(r)\xi^v + O(\xi^{v+1})
\]

with \( v > -1 \), then Watson’s lemma would give, in the large-\( x \) limit,

\[
I_{sd} \sim \frac{A(r)\Gamma(v + 1) e^{-i\omega x/M}}{2\pi i x^{v+1}} + O(1/x^{v+2});
\]

that is, the contribution from the branch cut plus all poles underneath it is an algebraically decaying wave convected with the bulk mean flow (i.e. the phase speed is \( M \)), plus, in the case of a point source within the boundary layer \( r_0 > 1 - h \), a propagating hydrodynamic wave with wavenumber \( k_0 \).
Preliminary calculations indicate that, for both the source and observer in the main flow (i.e. \( r_0 < 1 - h \) and \( r < 1 - h \)), Eq. (17) does indeed hold with \( v = 3 \). Not only does this suggest decay of \( O(1/x^4) \), but we also find that, making suitable assumptions about the magnitudes of \( h \) and \( \omega \), the prefactor \( A(r) = O(h^2M^6/\omega^5) \) is typically tiny. For the source within the boundary layer, the decay appears to follow an even higher rate of \( O(1/x^5) \). Since these predictions differ from those of Swinbanks[10], work is ongoing to verify them against numerical calculations and to locate the reason for the discrepancy with Swinbanks.

VI. The trailing vorticity field behind a point source in incompressible linear shear flow

The field due to the pole \( k = k_0 \) is really of hydrodynamical nature, as it remains qualitatively the same in the incompressible limit. By means of an elementary, quintessential model of the field of a line source in simple shear flow, we will show that this field of the pole \( k_0 \) is really the trailing vorticity of the source.

The present solution seems to be new, in spite of its rather basic configuration. The closest solution we found is the velocity field given by Criminale & Drazin [21] for the initial value problem of an impulsive point source in a linear shear layer. Therefore, we will give the solution in detail. First we will Fourier transform in \( x \), similar to the solution of the acoustic problem of the rest of the paper. Here, however, due to the simplifications of the model (2D, incompressible) we will have to deal with not normally convergent integrals which have to be considered as integrals of generalised functions.

Next to the free field situation, we will also consider the same problem but with an impedance wall, where the mean flow vanishes at the wall (although in less detailed). This problem is in many aspects similar (there is again the problem of generalised functions.

A. In free field

Consider the 2D model problem of perturbations of a linear sheared mean flow, due to a point source in \( x = y = 0 \), described after Fourier transformation in \( x \) by the following set of equations (in dimensional quantities).

\[
\begin{align*}
\frac{i\Omega}{c_0} \tilde{p} - ik\rho_0 \tilde{u} + \rho_0 \tilde{v}' &= \rho_0 S\delta(y), \\
i\rho_0 \Omega \tilde{u} + \rho_0 U' \tilde{v} - i k \tilde{p} &= 0, \\
i\rho_0 \Omega \tilde{v} + \tilde{p}' &= 0,
\end{align*}
\]

(18)

where \( \Omega = \omega - kU \). This system may be further reduced to a form of the Pridmore-Brown equation by eliminating \( \tilde{v} \) and \( \tilde{u} \), which, upon considering the incompressible limit in a doubly-infinite linear shear flow with \( U(y) = U_0 + \sigma y \) (note that \( \sigma \) has the dimension of frequency), becomes

\[
\tilde{p}'' + \frac{2k\sigma}{\Omega} \tilde{p}' - k^2 \tilde{p} = -i\rho_0 S\Omega_0 \delta(y).
\]

The homogeneous equation has two independent solutions \( e^{\pm ky}(\Omega \pm \sigma) \), or

\[
\begin{align*}
\tilde{p}_1(y) &= e^{k|y|} (\Omega + \text{sign}(\text{Re} k)\sigma), \\
\tilde{p}_2(y) &= e^{-k|y|} (\Omega - \text{sign}(\text{Re} k)\sigma),
\end{align*}
\]

where \( |k| = \text{sign}(\text{Re} k)k = \sqrt{k^2} \). (Note that neither of these solutions has a log-like singularity or requires a branch cut in the complex-\( y \) plane\(^a\).) The Wronskian is

\[
W(y; k) = \tilde{p}_2(y)\tilde{p}_1(y) - \tilde{p}_1(y)\tilde{p}_2(y) = -2|k|\Omega^2,
\]

and the Green’s function

\[
\tilde{p}(y, k) = \frac{\pm i\rho_0 S}{|k|\Omega_0} e^{-|k|y}(\Omega\Omega_0 - \sigma^2|k|y - \sigma^2).
\]

\(^a\)This is as predicted by (2), since there is no curvature term \((1/r_c\) in Eq. 2\), the density is constant and the shear is linear.
The physical field in the $x, y$-domain is hence obtained by inverse Fourier transformation

$$p(x, y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{p}(y, k) e^{-ikx} \, dk = \frac{i\rho_0 S}{4\pi} \int_{-\infty}^{\infty} \frac{e^{-ikx - |ky|}}{|k|\Omega_0} (\Omega\Omega_0 - \sigma^2|ky| - \sigma^2) \, dk,$$

which has singularities at $k = 0$ (if $\alpha^2 \neq \sigma^2$) and at $k = k_0 = \omega/U_0$ from $\Omega_0 = -U_0(k - k_0) = 0$, which is indeed the equivalent of (13) in the duct problem (see below). To study the trailing vorticity we are mainly interested in the contribution of the pole $k_0$, which is the downstream hydrodynamic wave part of

$$p(x, y) = \frac{\rho_0 S}{2\omega} \sigma^2 H(x)(1 + k_0|y|) e^{-ik_0x - k_0|y|} + \frac{i\rho_0 S}{2\pi} \int_{0}^{\infty} \frac{\log \lambda}{\log \Omega_0^\pm} \left[ \left( \Omega_0^\pm - \sigma^2 \right) \cos \lambda y - \sigma^2 \lambda y \sin \lambda y \right] \, d\lambda,$$

where $\Omega_0^\pm = \omega \pm i\lambda U$, $\pm = \text{sign}(x)$, $H(x)$ is Heaviside’s step function, and we used the fact that $\cos \varepsilon$ and $\varepsilon \sin \varepsilon$ are even functions.

The singularity at $k = 0$, on the other hand, is not a pole and has a different origin. Due to this singularity the inverse Fourier representation of the pressure is too singular to be interpreted normally. This results – in this 2D incompressible model – from $p$ being not Fourier transformable, not because $p$ itself is singular. As it turns out, $p$ diverges as $\sim \log(x^2 + y^2)$ for $x^2 + y^2 \to \infty$ and hence is not integrable. When we consider the incompressible problem as an inner problem of a larger compressible problem, this diverging behaviour changes in the far field into an outward radiating acoustic wave of some kind.

The inverse Fourier integral, however, can be found if the singular integral is interpreted in the generalised sense, and the singular part is split off. Following [22, p.105], we define the generalised function

$$\lambda^{-1} H(\lambda) = \frac{d}{d\lambda} H(\lambda) \log |\lambda|$$

and integrate by parts to obtain the convergent integrals

$$p(x, y) = \frac{\rho_0 S}{2\omega} \sigma^2 H(x)(1 + k_0|y|) e^{-ik_0x - k_0|y|} - \frac{i\rho_0 S}{2\pi} \int_{0}^{\infty} \log \lambda \frac{d}{d\lambda} \left[ e^{-\lambda|y|} \Omega_0^\pm \cos \lambda y \right] \, d\lambda$$

$$+ \frac{i\rho_0 S}{2\pi} \sigma^2 \int_{0}^{\infty} \log \lambda \frac{d}{d\lambda} \left[ e^{-\lambda|y|} \frac{\cos \lambda y + \lambda y \sin \lambda y}{\Omega_0^\pm} \right] \, d\lambda.$$

Each one can be integrated as follows

$$\omega \int_{0}^{\infty} \log \lambda \frac{d}{d\lambda} \left[ e^{-\lambda|y|} \Omega_0^\pm \cos \lambda y \right] \, d\lambda = \omega \gamma + \frac{1}{2} \omega \log(x^2 + y^2) - iU \frac{x}{x^2 + y^2}$$

$$+ \frac{1}{2}(1 + k_0 y) E(-ik_0x - k_0y) + \frac{1}{2}(1 - k_0 y) E(-ik_0x + k_0y)$$

where $\gamma = 0.5772156649...$ is Euler’s constant. We have then altogether

$$p(x, y) = -\rho_0 U_0^2 S \frac{2\pi \omega}{(1 + k_1 y)] \frac{k_0x}{x^2 + y^2} - \frac{i\rho_0 U_0^2 S}{2\pi \omega} (k_0^2 - k_1^2) \left( \gamma - \log k_0 + \frac{1}{2} \log(k_0^2 x^2 + k_0^2 y^2) \right)$$

$$+ \frac{i\rho_0 U_0^2 S}{2\pi \omega} \frac{k_1^2}{k_0^2} \left[ -2\pi i H(x)(1 + k_0|y|) e^{-ik_0x - k_0|y|} + (1 - k_0 y) E(-ik_0x + k_0y) + (1 + k_0 y) E(-ik_0x - k_0y) \right]$$

Note that the constant term (with $\gamma - \log k_0$) is a result of the generalised integral but is otherwise physically not relevant because only $\nabla p$ is defined by the problem. Any additive constant should be determined from matching with a compressible outer field.

As opposed to $p$, the integrals for $v$ or $u$ are convergent (outside the source) and can be found without resorting to generalised functions. We have

$$\tilde{v}(y, k) = \frac{i}{2} S e^{-|ky|} \left( \text{sign}(y) + \text{sign}(\text{Re} k) \frac{\sigma}{\Omega_0} \right)$$

$$\tilde{u}(y, k) = \frac{i}{2} S e^{-|ky|} \left( \text{sign}(\text{Re} k) + \text{sign}(y) \frac{\sigma}{\Omega_0} \right).$$
and obtain, with \( k_1 = \frac{\sigma}{U_0} \),

\[
\begin{align*}
v(x, y) &= \frac{S}{2\pi} \int_0^\infty e^{-\lambda |x|} \sin \lambda y \, d\lambda + \frac{i}{2} \frac{S k_1}{2\pi} H(x) e^{-k_0 y - ik_0 x} - \frac{S}{2\pi} k_1 \int_0^\infty \frac{e^{-\lambda |x|} \cos \lambda y}{\lambda + ik_0} \, d\lambda \\
&= \frac{S}{2\pi} \frac{y}{x^2 + y^2} + \frac{S}{4\pi} k_1 \left[ 2\pi i H(x) e^{-ik_0 y} - E(-ik_0 x + k_0 y) - E(-ik_0 x - k_0 y) \right]
\end{align*}
\]

\[
\begin{align*}
u(x, y) &= \pm \frac{S}{2\pi} \int_0^\infty e^{-\lambda |x|} \cos \lambda y \, d\lambda - \frac{i}{2} \frac{S k_1}{2\pi} H(x) \text{sign}(y) e^{-ik_0 y} + \frac{S}{2\pi} k_1 \int_0^\infty \frac{e^{-\lambda |x|} \sin \lambda y}{\lambda + ik_0} \, d\lambda \\
&= \frac{S}{2\pi} \frac{x}{x^2 + y^2} + \frac{S}{4\pi} k_1 \left[ 2\pi i H(x) \text{sign}(y) e^{-ik_0 y} + E(-ik_0 x + k_0 y) - E(-ik_0 x - k_0 y) \right]
\end{align*}
\]

Note that the branch cuts of the exponential integrals (in the \( E \)-functions) cancel the jumps due to the \( H(x) \)-terms, to produce continuous \( p \) and \( v \) fields. Only \( u \) has a tangential discontinuity along \( y = 0, x > 0 \) due to the \( \text{sign}(y) \)-term. This corresponds to the \( \delta(y) \)-function behaviour of the vorticity mentioned in Appendix A.

A graphical example of this solution is given in figure 9.

![Pressure and velocity field](image)

Figure 9. Pressure and velocity field of line source in incompressible linear mean shear flow for \( \omega = 10, \sigma = 20 \) and \( U_0 = 2, x \in [-3, 5] \).

For the comparison with the acoustic problem, we note that in the shear layer of the circular duct we have

\[
U(r) = \frac{M}{h} \left( 1 - \frac{r}{r_0} \right) = \frac{M}{h} \left( 1 - r_0 / r_0 \right) + \frac{M}{h} \left( r_0 / r - r_0 \right)
\]

which is equivalent to the 2D problem if we identify \( y = a(r_0 - r), U_0 = c_0 M (1 - r_0) / h, \) and \( \sigma = c_0 M / a h \) and \( \omega := \omega c_0 / a \), such that the dimensionless duct equivalent of \( k_0 \) and \( k_1 \) are

\[
k_0 := k_0 a = \frac{a \omega}{U_0} = \frac{\omega h}{M(1 - r_0)}, \quad k_1 := k_1 a = \frac{1}{1 - r_0}.
\]

B. Near an impedance wall

Consider the same equations (18) as before, but now in a region \( y \in [0, \infty) \), with a source at \( y = y_0 \), and an impedance wall at \( y = 0 \). We have with \( \Omega = \omega - k U, U(y) = U_0 + \sigma(y - y_0), U_0 = \sigma y_0, \Omega_0 = \omega - k U_0, k_0 = \omega / U_0 \) and
\[ \ddot{p}(0) = -\rho_0 U_0 \zeta \hat{v}(0) \] at \( y = 0 \), the Pridmore-Brown-type equation

\[ \dddot{p} + \frac{2k \sigma}{\Omega} \dot{p} - k^2 p = -i \rho_0 S \Omega_0 \delta(y - y_0). \]

with

\[ ik_0 \ddot{p}(0) = \zeta \dddot{p}(0). \]

Similarly to the free field configuration, the solution can be constructed and is found to be

\[
p = \frac{i \rho_0 S}{2|k|\Omega_0} e^{-|k|y_>} (\Omega_+ - \text{sign}(\text{Re} k)\sigma) \cdot 
\left( e^{i|k|y_>} (\Omega_- + \text{sign}(\text{Re} k)\sigma) + \frac{k - i\zeta^{-1}(k_1 + \text{sign}(\text{Re} k)k_0)}{k - i\zeta^{-1}(k_1 - \text{sign}(\text{Re} k)k_0)} e^{-i|k|y_>} (\Omega_- - \text{sign}(\text{Re} k)\sigma) \right)
\]

where \( y_+ = \min(y, y_0), y_\times = \max(y, y_0), \Omega_\times = \Omega(y_\times) \), and \( k_1 = \sigma/\Omega_0 \).

Again, the physical field in the \( x, y \)-domain is obtained by inverse Fourier transformation,

\[
p(x, y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{p}(y, k) e^{-ikx} dk
\]

with a pole at \( k = k_0 \) (yielding the vorticity shed from the source), and, for certain parameter values, at

\[ k = k_2 = \frac{i}{\zeta} (k_1 - \text{sign}(\text{Re} k_2)k_0) = \frac{\text{Im} \zeta + i \text{Re} \zeta \sigma - \text{sign}(\text{Re} k_2)\omega}{|\zeta|^2} \frac{\text{Re} \Omega_0}{U_0}.
\]

This pole must have a counterpart in the compressible 3D problem, but due to time constraints we have not finished this analysis yet. Further research is underway.

\section*{VII. Conclusions}

The Green’s function for a mass source in a cylindrical duct with constant mean flow and a linear-shear boundary layer of thickness \( h \) has been given, with no restriction on \( h \) being either small or large. In sheared flow, there are three possible contributions to the pressure field, being acoustic modes, surface modes [30, 31], and the critical layer branch cut (or, as it is sometimes called, the continuous spectrum). The first two occur as poles of the Green’s function, the only difficult question in these cases being whether modes should be considered to be left-running (present for \( x < 0 \)) or right-running (present for \( x > 0 \)), which may be ascertained by applying the Briggs–Bers criterion [23, 24]. One of the reasons for this paper was to address the third problem: that of the critical layer branch cut.

The continuous spectrum, through a Briggs–Bers analysis, is found to only take effect downstream of the point forcing and contributes to the critical layer in five ways:

1. through the pole just above the branch cut \((k_+)\);
2. through the pole just below or behind the branch cut \((k_-)\);
3. through the integral along the branch cut, with possible pole at \( k_0 \) removed (the pole being present for a point forcing within the boundary layer, \( r_0 > 1 - h \));
4. if \( r_0 > 1 - h \), through the pole at \( k = k_0 \); and
5. if \( r_0 > 1 - h \), through the exponential integral \( E(\cdot) \) in (15).

If, as hypothesized in section V, there are no poles of \( G_+ \) in the lower-half \( k \)-plane below the branch cut (or, in other words, if there are no modes hiding behind the critical layer branch cut in the lower-half \( k \)-plane with \( \text{Re}(k) > \omega/\Omega_0 \)), then the contributions from 2, 3 and 5 almost totally cancel and decay algebraically away from \( x = 0 \) (determined here to be as \( 1/x^d \) if \( r_0 < 1 - h \)). If there are such poles, they would add a residue contribution in the same way as for the acoustic and surface modes, and this contribution would necessarily be discontinuous in \( r \) and necessarily decay exponentially downstream. Note that either of 2 or 3 themselves may give rather a large contribution, so that, for instance, including the \( k_- \) pole below the branch cut but ignoring the branch cut itself would give significantly inaccurate results. The dominant effect of the branch cut is due to the poles either just above or on it, with the pole
$k_0$ being present for $r_0 > 1 - h$. Of these, the $k_+$ pole just above the branch cut is (in all cases considered here) a convective instability that dominates far downstream of the forcing point, while the pole on the branch cut (if present) is a neutrally-stable propagating mode, with a phase velocity equal to the velocity of the mean flow. The field due to latter is the trailing vorticity of the source and is of hydrodynamical nature, remaining qualitatively the same in the incompressible limit.

VIII. Acknowledgement

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Appendix

A. An investigation on the type of source

Since some of the results presented in this paper depend essentially on the type of source assumed, in this appendix we investigate the type of source in further detail.

Consider the equations for conservation of mass and momentum with a mass source $Q$ and an external force $F$. By first principle arguments [32] of integral balance of mass and linear momentum in inviscid flow, we obtain

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = Q$$

$$\frac{\partial \rho \mathbf{v}}{\partial t} + \nabla \cdot (\rho \mathbf{v} \mathbf{v}) + \nabla p = F + Q \mathbf{v}.$$ 

Note that the issuing mass adds momentum by an amount of $Q \mathbf{v}$. The momentum equation contains the left-hand-side of the mass equation and is in the usual way reduced to

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla p = F.$$ 

In the model studied here, we assume only a mass source $Q$ and no body force, i.e. $F = 0$. However, in general the presence of a mass source in a mean flow may disturb the flow such that an associated force is to be included, for example to model effects of turbulence, viscosity, separation or vortex shedding. In order to sketch the effect of this we consider a combination of a time-harmonic line point mass source and a line point force in a mean flow of linear shear. (A line source is relevant because in our duct problem the point source is broken up into a Fourier sum of circular line sources.) We have for the effectively 2D problem

$$\rho = \rho_0 + \epsilon_0^{-2} p \ e^{i \omega t}, \ \mathbf{v} = (U(y) + u \ e^{i \omega t}, v \ e^{i \omega t}), \ \rho = \rho_0 + p \ e^{i \omega t}, \ Q = q \ e^{i \omega t}, \ F = (f, g) \ e^{i \omega t}$$

$$\frac{1}{\epsilon_0^2} \left( i \omega + U \frac{\partial}{\partial x} \right) p + \rho_0 \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = q$$

$$\rho_0 \left( i \omega + U \frac{\partial}{\partial x} \right) u + \rho_0 \frac{dU}{dy} v + \frac{\partial p}{\partial x} = f$$

$$\rho_0 \left( i \omega + U \frac{\partial}{\partial x} \right) v + \frac{\partial p}{\partial y} = g$$

When we split up the velocity in a solenoidal and a vortical part

$$u = \frac{\partial \phi}{\partial x} + \frac{\partial \psi}{\partial y}, \ v = \frac{\partial \phi}{\partial y} - \frac{\partial \psi}{\partial x}, \ \chi = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = -\nabla^2 \psi,$$

where $\chi$ is the ($z$-component of) the vorticity, and assume the mean flow being given by

$$U(y) = U_0 + \sigma y$$
we obtain after taking the curl of the momentum equation

\[
\frac{1}{c_0^2} \left( i\omega + U \frac{\partial}{\partial x} \right) p + \rho_0 \nabla^2 \phi = q, \\
\rho_0 \left( i\omega + U \frac{\partial}{\partial x} \right) \left( \chi + \frac{\sigma}{\rho_0 c_0^2} p \right) = \sigma q - \frac{\partial f}{\partial y} + \frac{\partial g}{\partial x}.
\]

Consider a point source and point force

\[ q = \rho_0 \delta(x) \delta(y), \quad (f, g) = \rho_0 U_0(A, B) \delta(x) \delta(y). \]

to obtain

\[
\left( i\omega + U \frac{\partial}{\partial x} \right) \left( \chi + \frac{\sigma}{\rho_0 c_0^2} p \right) = \sigma S \delta(x) \delta(y) - AU_0 \delta(x) \delta'(y) + BU_0 \delta'(x) \delta(y)
\]

with (causal) solution

\[
\chi + \frac{\sigma}{\rho_0 c_0^2} p = (k_1 S - k_1 A - ik_0 B) H(x) e^{ik_0 x} \delta(y) - A H(x) \delta'(y) + B \delta(x) \delta(y),
\]

\[ k_0 = \frac{\omega}{U_0}, \quad k_1 = \frac{\sigma}{U_0}, \]

because \( h(x) \delta'(y) = h(0) \delta'(y) - h'(0) \delta(y) \).

We conclude that with \( A = B = 0 \) an undulating vortex sheet is produced extending behind the point source, which is not unexpected. (Of course, no vorticity is really produced, because the time-averaged \( \chi \) is zero. It is only a redistribution.) The field with \( A, B \neq 0 \), on the other hand, is much more singular. Therefore we will choose here no associated force field.

Note that for uniform mean flow (\( \sigma = 0 \)) vorticity is always produced by an external force field (for example at a trailing edge [33]), but not by a pure mass source.

References


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