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Sandwich panels with stiffeners

André Jorissen\textsuperscript{1}, Johnny van Rie\textsuperscript{2}, Thomas Houben\textsuperscript{3} and Herm Hofmeyer\textsuperscript{4}

ABSTRACT: This paper is the third in range presented at WCTE conferences. During the WCTE 2012 in Auckland the paper “sandwich structures with wood-based faces” \cite{1} dealt with the behaviour of traditional sandwich panels. During the WCTE 2014 in Quebec, the paper focussed on these panels with openings for e.g. skylights \cite{2}.

In this third paper the modelling of a sandwich panel with stiffeners is analysed. This particular type of sandwich panel promises a considerably higher load bearing capacity, along with other advantages such as less brittle properties, so-called strong points in the structure itself, which allow for connections, and of course the lack of cold bridging as known from other stressed skin and stiffened panels.

The paper presented here can be seen as a report on the research efforts carried out at Eindhoven University of Technology (TU/e), in cooperation with Industry, to provide scientific and experimental background to a building component which is widely used for mainly roof structures. For this, sandwich panels with stiffeners, applied as infill panels and roof panels are analysed analytically, numerically and experimentally.

KEYWORDS: sandwich elements, stiffeners

1 INTRODUCTION

Sandwich panels combine relative high strength and stiffness with high thermal insulation. In the paper called “sandwich structures with wood-based faces” \cite{1}, presented at the WCTE 2012 in Auckland, the structural performance of sandwich panels with wood based faces, applied for inclined roofs, was analysed. Additionally, that paper gave special attention to the bi-axial compression stresses at the supports. For the paper called “Sandwich panels with holes“ \cite{2}, presented at the WCTE 2014 in Quebec City, these traditional elements were further analysed regarding openings for e.g. skylights. To increase strength and stiffness even further, so-called stressed skin panels, see figure 1, can be a solution. However, these panels show areas with reduced thermal insulation, which in turn increases the risk for moisture problems.

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure1.png}
\caption{Stressed skin Panel with core stiffeners: 1,2 and 3: areas with reduced thermal insulation}
\end{figure}

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure2.png}
\caption{Stiffened Sandwich Panel}
\end{figure}

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The core consists of rigid foam thermal insulation material, which contain up to 98% of gas (i.e., air, CO₂, Pentane). Consequently, the core shows rather poor structural behaviour. The material does have some compression strength, however the modulus of elasticity and shear modulus are low. Thus, when these panels are loaded in bending, the bending moment is primarily taken by the faces and timber stiffeners.

Shear load is taken by the core (the insulation material) resulting in shear deformation. Whereas for rectangular timber beams shear deformation can normally be neglected (it generally accounts for less than 3% of the total deformation), here shear deformation of the insulation causes more than 30% of the total deflection. Furthermore, due to strengthening of the wood based faces by the added stiffeners, shear failure may be among the expected failure mechanisms. Consequently, shear failure limits the contribution to the strength by the stiffeners.

This paper informs on to what extend the usual approaches for bending stiffness, shear stiffness and effective width are still valid for this particular type of sandwich panel. To verify this, finite element simulations and experimental research has been carried out on four different types of panels, ranging from a normal sandwich (no stiffeners and laths) to a panel with stiffeners, as shown in figure 2 (in which a gypsum board is added for fire resistance).

All analyses described in this paper are based on a so-called four point bending test as shown in figure 3 in which the span \( L = 3000 \text{ mm} \). The load \( F \) is applied on the panel, distributed via a hinged bridge structure shown in figure 14 on a distance \( a = L/3 \) from the end.

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\[ \phi \text{ bending: } \phi \]
\[ \gamma \text{ shear: } \gamma \]

**Figure 3: Set-up of the four point bending test**

### 2 THEORETICAL ANALYSES

#### 2.1 Beam theories

Ordinary beam theory (Euler-Bernoulli [3]), shown in figure 4, only takes bending deformations into account by assuming that in the deformed situation cross-sections remain planar and perpendicular to the beam axis. Shear deformations are not regarded.

**Figure 4: Euler-Bernoulli beam**

Here, due to significant shear effects, this ordinary beam theory cannot be applied anymore. When it is assumed that for shear the relatively stiff wood based faces deform similarly to the core (i.e., cross-section remain planar), as shown in figure 5 on the right, analyses can be carried out according to Timoshenko’s [4] theory, shown in figure 6.

**Figure 5: Bending and shear deformations**

As mentioned, this is only possible when the wood based faces can be regarded as relatively thin and are able to match the shear deformations. In that case the faces are uniformly loaded in tension or compression (no bending) and the core is uniformly loaded in shear.

**Figure 6: Timoshenko beam; \( \gamma \) is constant over the beam height.**

For sandwich elements with rather thick faces it can no longer be assumed that the deformation of the faces is similar to the deformation of the core and a more advanced analysis according to Ready-Bickford, indicated in figure 7, has to be applied [3]. In this case the faces are not loaded uniformly over the face thickness: the faces are loaded in bending as well.
It is clear that the selection of either the Timoshenko or the Ready-Bickford model depends on the bending stiffness of the faces; thick faces have a considerable bending stiffness, thin faces have not. Allen [8] defines, that the bending stiffness of the faces \( E I_{\text{tot}} \) can be ignored if this is less than 1% of the total panel bending stiffness \( E I_{\text{fac}} \). The values for \( E I_{\text{tot}} \) and \( E I_{\text{fac}} \) are explained in figure 8.

The four-point bending set-up as shown in figure 3 allows a study of both the bending and shear stiffness separately. For a Timoshenko beam the maximum deflection can be determined using eq. 4.

\[
\text{w}_{\text{max}} = \frac{23}{1296} \frac{F L^3}{E I_{\text{tot}}} + \frac{F L}{6 G A_{\text{tot}}}
\]  

(4)

With: \( w_{\text{max}} \) = maximum deflection (at mid span) [mm]  
\( F \) = total load applied, see figure 7 [N]  
\( L \) = span [mm]  
\( E I_{\text{tot}} \) = bending stiffness according to eq. (1)  
\( G A_{\text{tot}} \) = shear stiffness according to eq. (5), based on [5].

\[
G A_{\text{tot}} = \left( \frac{1}{b e^2} \left( \frac{d_1}{2 G_1} + \frac{d_2}{2 G_2} + \frac{d_3}{2 G_3} \right) \right)^{-1}
\]  

(5)

Remark: see figure 8 for the symbols used in equation (5).

### 2.2 Effective width

A so-called effective width is defined for stressed-skin (figure 1) and stiffened panels to model the part of the faces that contribute to the strength and stiffness. In the case of a stressed skin the load carrying part is modelled as an I-shaped cross section of which the flange width equals the effective width described by Möhler [6]. In this study equation (6) from SKH 09-01 [7], resulting in exactly the same values for the effective width as evaluated by Möhler, is used. The effective width according to equation (6) and Möhler are both shown in figure 9.

For the case of the sandwich panels with stiffeners as described in this paper, it is assumed that the effective width approach is valid too, taking into account two aspects. First, it should be checked that the shear stresses in the thin flange (face) do not exceed the shear strength. Second, the flange (face) might suffer from out of plane buckling, however, this is considered not to be relevant here since the flange is fully glued to the core. Consequently, the effective width as defined by equation (6) underestimates the “real” effective width (and is therefore conservative i.e. on the safe side).

\[
b_{\text{ef}} = \frac{\tanh \left( \frac{\pi a_{\text{l}}}{2 L} \frac{E_{\text{t,panel}}}{G_{\text{panel}}} \right)}{2 L} \frac{E_{\text{t,panel}}}{G_{\text{panel}}}
\]  

(6)

With: \( b_{\text{ef}} \) = effective width < the spacing between the stiffeners [mm]  
\( a_{\text{l}} \) = spacing between the stiffeners [mm]  
\( L \) = span = 3000 [mm]  
\( E_{\text{t,panel}} \) = Young’s Modulus = 2400 [N/mm²]  
\( G_{\text{panel}} \) = Shear Modulus = 200[N/mm²]
FINITE ELEMENT SIMULATIONS

In order to study the effects of the stiffeners, a finite element model has been developed (using Abaqus 6.14 standard). The aim was to create a parametric geometrical model, able to model all the variants in this paper. The main aim of the model is to give insight in the local 3 dimensional effects caused by the stiffeners and laths; the question is whether these can be ignored or not. Once the model is validated using experimental results described in this paper, it can be used for different geometries and material properties not included in the experiments.

3.1 General

The 3D geometrical models are shown in figure 10; see also figure 2. The span \( L = 3000 \text{ mm} \).

All simulations are linear elastic. Nonlinear material behaviour is not taken into account and consequently the finite element simulations will deviate from the experimental results as soon as experimental strains surpass the elastic limit.

The Young’s modulus and the Shear modulus are used as separate parameters (not depending upon each other); for the face material these values are listed in the legend to equation (4).

3.2 Set up

The model consists of a 3D geometry for which the outer surfaces (faces) are meshed with so-called S4R shell elements. These elements include bending stiffness for the case the face thickness cannot be ignored and use ‘reduced integration’ and ‘hourglass control’. The core of the model is meshed with C3D20R volume elements. These are solid, continuous elements with 20 nodes and 8 integration points. Also here ‘reduced-integration’ is used.

Remark: the panels from series 1 are, as expected, by far the weakest and the faces are sensitive to wrinkling due to bi-axial compression in/on the faces at the supports and the load locations as described in [1]. Panels out of series 3 and 4 do not have that particular problem due to the stiffeners and the counterbattens (laths).
Figures 11 (vertical deformations), 12 (longitudinal shear stresses) and 13 (local bending stresses) show some results for series 4.

**Figure 11:** Vertical displacements.

**Figure 12:** Longitudinal shear stresses.

In figure 12 both a longitudinal and a cross-sectional cut has been made to show that shear stresses differ lengthwise as well as laterally. It seems that at the location of the stiffeners and counter battens (laths), considerable higher shear stresses develop. The shear function is, in principle, the derivative of the bending moment function. Consequently differences in bending stresses along the beam axis (in x-direction) have to be taken care of by shear stresses. Since these differences are high near the stiffeners / counter battens the shear stresses are high at these locations.

In figure 13 the tensile and compression stresses in the cross section at the counter batten and the stiffener of series 4 are presented. The stresses in the faces can be regarded as being constant (due to the low face thickness of 3.2 mm). The stresses in the stiffeners and counter batten are not constant due to the relative high bending stiffness of these elements.

As such Timoshenko’s beam theory might not be applicable. This can also be checked using equations (1) and (2) referring to the 1% statement of Allen [8] mentioned in 2.1; the local bending stiffness of the faces ($EI_f$, equation (2), including the stiffeners and counter battens) reaches about 1.4% of the total panel stiffness $EI_{tot}$ (equation (1)).

### 4 EXPERIMENTS

Experiments have been carried out in the Pieter van Musschenbroek laboratory of the Eindhoven University of Technology (TU/e). In total 20 specimens have been tested in a four point bending test set up, 5 for each series. Dimensions are presented in table 1, with the span length $L = 3000$ mm for all series.

<table>
<thead>
<tr>
<th>series</th>
<th>number of stiffeners</th>
<th>number of battens</th>
<th>number of samples</th>
<th>length [mm]</th>
<th>width [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>5</td>
<td>3500</td>
<td>900</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>3</td>
<td>5</td>
<td>3500</td>
<td>900</td>
</tr>
<tr>
<td>3</td>
<td>2+2</td>
<td>3</td>
<td>5</td>
<td>3500</td>
<td>1020</td>
</tr>
<tr>
<td>4</td>
<td>3+3</td>
<td>3</td>
<td>5</td>
<td>3500</td>
<td>1020</td>
</tr>
</tbody>
</table>

The face material is for all specimen P5 particle board; the core material is EPS 80 (expanded polystyrene with compression strength of 80 kN/m$^2$). The bottom face has a white finish and the top face is green (this causes a slight difference in stress strain relationship; see [9])

The test set up is shown in figure 14.
Figure 14: Test set up with measurement locations.

4.1 Shear stiffness measurements

The shear stiffness is measured according EN 408 2010[10] This method uses a diagonal cross along the side of the sample. When the sample is loaded, the diagonals will change in length from which the shear angle and the shear stiffness can be determine; see fig 15 and equations (7) and (8).

\[
\gamma = \frac{\alpha \Delta V}{GA} = \frac{\Delta w_2 - \Delta w_1}{h_0} \tag{7}
\]

\[
GA = \frac{\alpha \Delta V h_0}{\Delta w_2 - \Delta w_1} \tag{8}
\]

Figure 15: Device for shear stiffness measurement

With \( \Delta w_{1,2} \) = length change [mm] at of both LVDT’s due to a change in shear force

\( \Delta V \) = change in shear force [N]

\( \alpha \) = ratio max shear-to average shear stress

\( h_0 \) = projected height between top and bottom of the device

Table 2 shows the results of the shear modulus measurements. In addition, for comparison, the numerical results and the analytical results according to equation (5) are also shown in table 2.

Table 2: Shear stiffness \( GA \)

<table>
<thead>
<tr>
<th>series</th>
<th>experimental</th>
<th>numerical</th>
<th>analytical</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>457</td>
<td>588</td>
<td>454</td>
</tr>
<tr>
<td>2</td>
<td>387</td>
<td>419</td>
<td>454</td>
</tr>
<tr>
<td>3</td>
<td>425</td>
<td>468</td>
<td>514</td>
</tr>
<tr>
<td>4</td>
<td>436</td>
<td>488</td>
<td>514</td>
</tr>
</tbody>
</table>

It is remarkable that the experimentally and numerically determined shear stiffness for series 2 is lower than for series 1. The reason for this is that the measurement is carried out locally (at the panel edge, where a counter batten (lath) is present). The stresses near the counter batten are higher (as discussed before); the locally higher shear stresses, not accounted for in the global shear load with which \( GA \) is calculated, result in higher shear deformations and, consequently, a lower \( GA \) value. In the globally determined \( GA \) according to equation (5) the total cross section is taken into account and exceeds therefore the experimental and numerical values.

4.2 Deflection

Figure 16 shows the experimental load deformation graphs for all experiments and the average for each series.

Figure 16: Load versus displacement: Stiffness

All the series show a linear-elastic branch, slowly changing in a nonlinear branch, ending with a rather sudden failure. The failure load is clearly increasing from series 1 to 4. It is remarkable that the difference in between series 3 and 4 is rather small, so the added stiffeners in the middle do not seem to be very effective. Both series 3 and 4 show shear failure in the core material which explains that the load carrying capacity of series 4 is hardly increased compared to series 3.

The experimental results show a slightly more stiff behaviour than is expected according the FEM and the
analytical values. This is shown in figure 17, as an example for series 3.

In general, it can be seen that the strain is reduced at stiffener locations. This is to be expected since this is actually the background for the effective width described in 2.2. Figure 16 also indicated that the panel curves (not flat) over the panel width.

5 CONCLUSIONS

The finite element simulations reveal the stresses in the counter battens (laths), faces and stiffeners, among others representing bending stresses, as is shown in figure 13. These local effects are not taken into account in the SKH 09-01 publication [8] (equations (4), (5), (6)). However, the global behaviour of the panel, as expressed in the load-deformation behaviour graphs of figure 15, does not seem to be affected seriously by these local effects.

The shear stresses in the core increase compared to these stresses in panels without stiffeners which may result in shear failure of the core material. Indeed, these failures have been observed during the experiments on panels out of series 3 and 4, which additionally indicate that the extra stiffener applied in the series 4 panels do not or hardly contribute to the load carrying capacity.

Near the stiffeners and counter battens the shear stresses in the faces are much higher compared to the shear stresses in the face materials without the stiffeners. Although a shear or buckling failure due to these higher stresses did not occur during the experiments, this failure mode has to be considered and studied in more detail.

Finally, panels with stiffeners do not remain flat in width direction as indicated by figure 18.

REFERENCES


