Modelling information routing with noninterference

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Modeling Information Routing with Noninterference

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Formal verification of MILS systems

MILS systems consist of a high-assurance separation kernel, high-assurance applications, and low-assurance applications.

Verified system requirements generally rely on the correctness of both separation kernel and some applications.

Formal verification strategy:

- Prove separation kernel correctness
- Prove correctness of vital applications
- Infer global system properties
Formal verification of MILS systems — example

- Network manager forwards messages between domains to authorized receivers only
- Global security requirement: low-assurance domains never receive secret information

Security property relies on correctness of network manager!
Noninterference (Van der Meyden variation)

Intransitive noninterference is a formal specification of the security properties of separation kernels:

- The system contains a set of domains;
- Domains can observe certain things about the system;
- Each domain can perform actions that change the system state;
- Valid domain interactions are described by a security policy $\rightsquigarrow$.
- Security requirement:

  “Action $a$ of domain $d$ may have observable consequences for domain $e$ only after execution of actions $a_1$ of $d_1$, $a_2$ of $d_2$, $\ldots$, $a_n$ of $d_n$ such that $d \rightsquigarrow d_1$, $d_1 \rightsquigarrow d_2$, $\ldots$, $d_n \rightsquigarrow e$. ”
Noninterference — example

Security policy:

Not allowed — direct influence from A to C:

Allowed — influence flows via B:
System verification with noninterference

Noninterference describes the security properties of a separation kernel for *unspecified abstract observation functions* and for arbitrary actions by domains.

- How do we formalize and reason about the exact information accessible to domains?
- How do we specify that high-assurance domains behave in particular ways?

If we want to formally verify properties for systems that include information-handling domains, we need to solve both problems!
Modelling information

Noninterference assumes an abstract observation function \( \text{obs}(\text{domain, state}) \) that cannot be changed by noninterfering domains.

But noninterference doesn’t say anything about the *contents* of this observation function.

Thus, we need to:

- encode domain-accessible information in the obs function
- formulate axioms on the behavior of this information
Informal information model

- A domain can observe *chunks of information about its own state*
- A domain can *forward observable chunks of information* to other domains
Formal information model

Observation function returns a *set of chunks of information*:

- \( \text{obs}(\text{domain}, \text{state}) \in \mathcal{P}(I) \)

Each chunk of information is *about* a certain domain:

- \( \text{subject}(i) \in \text{Domains} \)

A domain can get access to an information chunk if the information is about the domain, or the information was forwarded by a domain with access:

- \( (i \in \text{obs}(d, \text{step}(a, e, s)) \land i \notin \text{obs}(d, s)) \Rightarrow (\text{subject}(i) = d \lor i \in \text{obs}(e, s)) \)
Domain behavior

Noninterference models the security properties guaranteed by the separation kernel:

- *For all possible domain behaviors:* certain bad things do not happen

Real domains do not take arbitrary actions. They take the right action at the right time to achieve some purpose.

But noninterference does not give an obvious way to describe the behaviors of specific domains...
Domain program specifications

Noninterference quantifies over all action sequences by all domains.

A domain specification should specify: “domain $d$ only takes actions that satisfy some requirement $R$”.

```
  d_1  e_1  d_2  
  \-----\    \---->
  |      |    |      |
  |      |    |      |
  |      |    |      |
  d_2  e_2  d_2  
  \-----\    \---->
  |      |    |      |
  |      |    |      |
  |      |    |      |
  d_3  e_3  d_4  
```
Domain programs

A program for domain $d P$ is a function from states to actions of $d$

- Semantics: “domain $d$ will only perform action $P(s)$ in state $s$”

We can specify domain behavior using domain programs:

- “The action $P(s)$ will always satisfy some requirement $R(s)$”

System-global requirements can be verified using domain programs:

- Verify that for all action sequences $\alpha$ that obey program $P$, the global requirement holds over $\alpha$. 
Example formalization: network manager

Consider the network manager MILS system:

- There is a piece of information, Secret, known to High.
- The Network Manager relays information between domains, and is designed to never leak the Secret to either Low domain.
- Goal: Verify that Secret can never reach Low domains.
Network manager — formal verification

The global correctness goal should follow from the correctness of the network manager. We should be able to prove:

- Assuming that noninterference holds for the given information flow policy;
- Assuming that information in general behaves as specified by the information axioms;
- Assuming that $P$ is a network manager program that behaves as specified;
- Assuming that $Secret$ is unknown to Low in the initial state $s_0$;
- We should be able to conclude: for all action sequences $\alpha$ that obey $P$, $Secret \notin \text{obs}(Low, \text{run}(\alpha, s_0))$.
Network manager formal verification — results

The requirement on the network manager is a bit more subtle than naively expected:

- For all domains $d$ for which an authorized information flow path exists to a $Low$ domain without passing through the $NetworkManager$:
  
  \[
  \text{if } \text{Secret} \not\in \text{obs}(d, s); \text{ then } \\
  \text{Secret} \not\in \text{obs}(d, \text{step}(\text{NetworkManager}, P(s), s)).
  \]

- Otherwise, the $Secret$ can reach $Low$ indirectly!

The initial state should likewise cover all such domains.

For this version: global correctness proved and verified using the Isabelle/HOL proof assistant :)
Conclusions and future work

Fully formal verification of the high-assurance parts of a MILS system is feasible. Formal specification and verification of separation kernel and high-assurance applications can be used to verify the complete system.

However, accurate specification of the desired behavior of components remains difficult. The information model of the network manager is a good start; but it is not a good end.

- Much more research can be done to improve on this!
The end

Questions?