

Article

# The feasibility of dynamic musculoskeletal function analysis of the vastus lateralis in endurance runners using continuous, hands-free ultrasound

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**Abstract:** Dynamic imaging of the skeletal muscles used to be strenuous and often impossible to perform manually. Accordingly, long-term dynamic musculoskeletal imaging has not been performed. The feasibility of long-term dynamic musculoskeletal functional analysis using hands-free ultrasound will be demonstrated in ten healthy endurance runners. After every kilometer, the *vastus lateralis* muscle was imaged whilst running using a fixated probe connected to a smart phone. The image quality was quantified by estimation of the probe-skin contact preservation and the field-of-view stability. Moreover, the pennation angles and muscle thicknesses were computed automatically. Long-term dynamic acquisition was successful in nine out of ten runners. Probe-skin contact loss ranged between 0 and 57 % of the gait cycle. The biggest change in field-of-view occurred during the first kilometer with an average decline in complex-wavelet structural similarity index of 0.21, followed by an onward total decrease of 0.09, on average. The mean pennation angle and thickness were approximately constant, with the average fluctuation being 0.94 degrees and 0.11 cm, respectively. The feasibility of long-term musculoskeletal function analysis has been demonstrated, with probe-skin contact loss the main limiting factor. Dynamic, hands-free ultrasound might enable research for a more profound insight in the prevention and rehabilitation of musculoskeletal injuries.

**Keywords:** musculoskeletal; dynamic ultrasound; vastus lateralis; hands-free ultrasound; marathon; endurance running; field-of-view stability; pennation angle; muscle thickness

## 1. Introduction

Musculoskeletal disorders affect 25% of the world population inducing prolonged inactivity and limiting daily activities, resulting in physical disabilities, poor quality of life, high economic costs, and a decreased labor capacity [1,2]. The pathophysiology of numerous musculoskeletal disorders is still poorly understood, and are hard to predict and prevent [3,4]. Moreover, understanding of musculoskeletal injury mechanisms and patterns may aid in diagnosis and injury prevention.

In athletes, risks of injury were observed to be associated with fatigue, weakness, previous injuries, and an imbalance between agonist and antagonist muscles [5]. Most injuries arise during movements across two joints [6]. Moreover, eccentric contractions are associated with a greater risk of injury [5,7]. Musculoskeletal disorders frequently lead to alterations in gait, resulting in secondary injuries. For the prevention of injuries becoming chronic, it is important to prevent repetition of trauma and to ensure full recovery prior to maximal loading of the previously injured muscle [5]. In some cases, symptoms only show during exercise, due to motion related

32 changes (e.g. muscle/tissue swelling, fatigue, friction, impact forces). Dynamic assessment of  
33 muscle architectural and mechanical parameters might attribute in the diagnosis of muscle-related  
34 impairments. Additionally, dynamic evaluation might provide more information on the origin and  
35 possible prevention of the musculoskeletal disorders caused by exercise, atrophy, disease, and ageing  
36 [8].

37

38 In the clinic, physical examination is used for muscle and joint function quantification (e.g.  
39 strength, range of motion) [9–11]. Electrical activation of the muscles is investigated using  
40 electromyography [12–14]. Joint kinetics and kinematics can be measured using 3-D motion  
41 capture systems and ground force plates [15–17]. However, to obtain a more profound and realistic  
42 understanding of muscle function in dynamic conditions, imaging of the muscle whilst performing  
43 exercise would be promising.

44 Ultrasound is generally the most suitable imaging modality in the musculoskeletal system. The  
45 benefits of ultrasound include a high spatial and temporal resolution, useful for detection of anatomical  
46 structures and motion analysis, respectively. Moreover, ultrasound is economical, cheap, non-invasive,  
47 safe for both the examiner and the subject, portable, and has a relatively short acquisition procedure.  
48 In musculoskeletal ultrasound, the muscle architecture can be shown including the aponeuroses, and  
49 muscle fascicles. The architectural muscle parameters that can be analyzed using ultrasound contain  
50 pennation angles, fascia lengths, and muscle thickness [18–20]. Dynamically assessed parameters  
51 include contraction velocity, strain, stiffness during muscle contractions, and fascia length in relation  
52 to exerted force [4,21]. Furthermore, the echo intensity of the muscle area might expose neurological  
53 disorders or is an indication of muscle acidification [22]. Structures adhering to the muscle (e.g.  
54 tendons and its fibers, cartilage, bursa, bones) can also be visualized with high quality [23,24].

55

56 Dynamic imaging of the skeletal muscles is strenuous and often impossible to perform manually, since  
57 the transducer has to be held in a fixed position. Manual acquisitions might be feasible during low  
58 intensity exercise, though the musculoskeletal function parameters are likely to vary between different  
59 exercise intensity levels. In static interval measurements, the imaging plane is difficult to reproduce.  
60 Out-of-plane motion as a consequence of an unstable field-of-view renders measurements such as  
61 Doppler velocity imaging and strain impossible. A constant field-of-view is crucial for accurate  
62 estimation of muscle tissue parameters [25].

63 Fixation of the transducer enables dynamic imaging, and has been shown to overcome part of the  
64 limitations associated with manual acquisitions. Probe fixation has been shown to yield improved or  
65 similar field-of-view stability and repeatability of ultrasound acquisitions [18,26,27]. Additionally,  
66 probe fixation has shown to decline shoulder abduction and forearm muscle activation of sonographers  
67 without influencing the acquisition time in echocardiography [28]. A demonstration of short-term  
68 probe fixation during a few minutes of cycling exercise was already presented [18]. However, the  
69 feasibility of dynamic musculoskeletal ultrasound acquisitions during long-term (running) exercise  
70 still has to be demonstrated.

71

72 In this study, the feasibility of obtaining dynamic ultrasound acquisitions and evaluating the  
73 skeletal muscle function is investigated in ten endurance runners. To the best of our knowledge,  
74 no hands-free, outdoor, long distance, ultrasound acquisitions have been obtained previously. In  
75 endurance running, the risk of probe displacement due to external factors (e.g. other participants,  
76 attributes, the ground) is minimal. Additionally, in endurance running, the exercise performed is  
77 fairly invariable, implying deviations in functional measurements are most likely caused by probe  
78 dislocation or detachment [29,30].

79 The objectives of this study were to quantitatively analyze the image quality and demonstrate the  
80 possibility of functional parameter computation from ultrasound images obtained hands-free during  
81 endurance exercise. The image quality was assessed by estimation of maintained probe-skin contact,

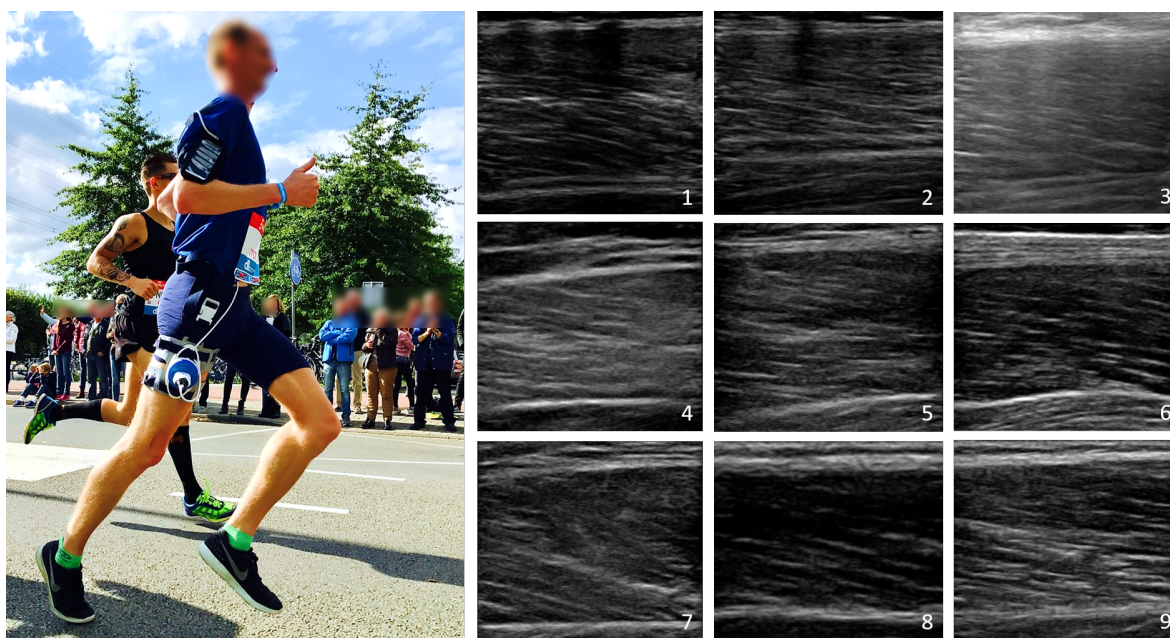
82 and field-of-view stability analysis using the complex-wavelet structural similarity index method  
83 (CW-SSIM). Potential probe-skin contact loss was expected to occur due to sweating, or slight probe  
84 fixation device shifts. The field-of-view was hypothesized to stay constant, based on a previous  
85 study executed during a couple of minutes of cycling exercise [18]. Furthermore, the functional  
86 measurements were expected to remain constant over time and distance ran, since this study was  
87 performed during endurance exercise. The pennation angle and muscle thickness have shown to  
88 remain constant when measured prior and post endurance running [29–31].

## 89 2. Materials and Methods

### 90 *Participants*

91 Nine healthy trained endurance runners were asked to participate in this study, of which two  
92 subject participated twice. The volunteers consisted of five males and four females between the age of  
93 25 and 35 with no musculoskeletal injuries or known cardiovascular abnormalities. Unfortunately, one  
94 of the female runners was excluded from the study, since the fixated probe lost contact after running  
95 three kilometers. All runners were already enrolled in a professionally organized endurance running  
96 event prior to recruitment.

97 The local Medical Ethics Committee of the Máxima Medical Centre, Veldhoven, The Netherlands  
98 waived ethical approval (N18.124, October 12, 2018, and N19.076, September 16, 2019). In 2017,  
99 the study involved measurements with CE marked devices on endurance runners, who were not  
100 specifically asked to participate in a professionally organized endurance running event for this study,  
101 and all gave their written informed consent for the ultrasound measurements during the endurance  
102 running event. For that purpose, protocol evaluation by a METC was not considered standard practice  
103 at the time, which encompasses three volunteers. All volunteers provided written consent. The  
104 procedures were carried out in accordance with the Declaration of Helsinki.



**Figure 1.** Experimental set-up of the endurance runners. (Left) The transducer is fixated onto the upper leg to image the belly of the vastus lateralis muscle in the longitudinal direction. The transducer is connected to a mobile phone, which is attached to the upper arm of the volunteer. (Right) A representative ultrasound image obtained at the 5<sup>th</sup> kilometer of all included volunteers.

### 105 *Acquisition protocols and equipment*

106 A portable, broadband linear array transducer (Lumify L12-4, Philips, USA ) with ultrasonic  
 107 gel (Aquasonic 100 Ultrasonic Gel, Parker) was embedded in a fixation device (ProbeFix Dynamic,  
 108 USONO, Eindhoven, The Netherlands), which was attached to the right leg of the participant. The  
 109 imaging plane encompassed the belly of the vastus lateralis muscle in the longitudinal cross section.  
 110 The transducer was connected to a smartphone, which was attached to the right upper arm of the  
 111 participants. Nine of the participants engaged in half a Marathon (21 km) and one participant ran 10  
 112 km during another professionally organized event.

113

114 After approximately every kilometer, the participants acquired ten seconds of conventional  
 115 2-D ultrasound images using the Lumify ultrasound application on their smart phone, whilst running.  
 116 These interval acquisitions were repeated until complete battery depletion occurred, or the finish line  
 117 was reached. Acquisitions were started after the first kilometer to account for possible probe shifts  
 118 whilst initiating exercise. The B-mode ultrasound images were acquired at a frame rate of 24 to 30 Hz  
 119 and with imaging depths between 3.5 and 6.0 cm. The musculoskeletal, vascular, and lung presets  
 120 were used in volunteers 1 and 2, 3, and 4 - 10, respectively. The different presets were employed  
 121 to determine the optimal image setting for dynamic acquisitions. In the volunteers, the imaging  
 122 parameters were kept constant as long as probe-skin contact was still preserved during part of the gait  
 123 cycle.

### 124 *Data analysis*

125 The ultrasound data were transferred to an external computer in DICOM format. These DICOM  
 126 files were analyzed by algorithms implemented in MATLAB (MATLAB 2018b, MathWorks, Natick,  
 127 MA, USA).

### 128 *Image decomposition*

129 For the structural similarity analysis, and the detection of aponeuroses and muscle fascicles, the  
 130 ultrasound images were decomposed using a steerable, oriented pyramid employing complex and  
 131 oriented wavelets [32]. The oriented wavelets were created by successive application of low and high  
 132 pass filters, and a mask selecting only a specific orientation range of the resulting bandpass filter.  
 133 Additionally, complex instead of real wavelets were employed, since most structure information is  
 134 provided by the relative phase patterns of the wavelet coefficients [33].

135 In this study, the frequency spectra of the ultrasound images were separated using maximally six  
 136 decomposition levels. The detail images resulting from this decomposition contained image structures  
 137 of an increasing size range with increasing decomposition level (Table 1). Orientation zero of the  
 138 wavelets was defined as 0 rad, which was parallel to the ultrasound beam, and was incrementally  
 139 increased with  $\frac{\pi}{n}$  rad, with  $n$  the number of chosen orientations.

**Table 1.** Full width at half maximum ranges of the bandpass filters in the spatial domain.  
 The pixel sizes of the acquisitions ranged between 0.07 and 0.15 mm

Decomposition level	Bandpass filter size range (pixels)
1	1.5 - 2.6
2	3.0 - 5.3
3	5.8 - 10.4
4	11.4 - 20.2
5	21.6 - 38.9
6	41.7 - 73.0

## 140 Image quality

141 Image quality quantification was performed through probe-skin contact preservation assessment,  
142 and field-of-view stability evaluation measured using the complex-wave structural similarity index.

### 143 Probe-skin contact

144 Probe-skin contact loss might occur due to sweating, the cyclic motion of the legs, and the impact  
145 forces from the ground. Accordingly, the duration percentage of probe-skin contact was quantified  
146 for all acquisitions. In case the transducer lost complete contact with the skin, a black ultrasound  
147 image was observed with a bright, white, hyper-echoic line-shaped artifact present near the transducer  
148 position, resulting from the high acoustic impedance between the ultrasound transducer and air  
149 causing total reflection (Fig. 3a). Hence, contact loss was empirically defined as a frame containing a  
150 black area of at least 80 % of the image.

### 152 Field-of-view stability

153 The field-of-view stability was evaluated utilizing the complex wavelet structural similarity index  
154 method (CW-SSIM). The CW-SSIM is a full-reference method based on human vision, which compares  
155 the structures visible within an image to those of a chosen reference image. The similarity between  
156 the images is computed using the brightness (mean pixel intensity), contrast (variance), and image  
157 structures (covariance) [34]. The CW-SSIM has been shown to be an adequate comparison method  
158 for ultrasound data [35], since it compares the detail images of the highest decomposition level.  
159 Accordingly, the method a) disregards noise and ultrasound speckle, b) predominantly compares the  
160 principal image features, and c) adopts the benefit of the relatively higher precision with which lower  
161 frequencies can be determined. Moreover, small rigid rotations and translations, and modest image  
162 brightness alterations have no effect on the CW-SSIM index. For example, a brightness modification  
163 of 10% leads to a CW-SSIM index reduction from its maximum value 1 to minimally 0.996 [34]. The  
164 CW-SSIM index will decrease to approximately zero in case the image structures are completely  
165 different, and will be equal to one in case the images compared are identical.

166 Prior to the CW-SSIM analysis, the images were decomposed as previously described, using  
167 six levels and 16 orientations. For each of the 16 oriented detail images of level six, the local CW-SSIM  
168 indices are computed using:

$$169 S(c_I, c_{II}) = \frac{2|\sum c_{I,i} c_{II,i}^*|}{\sum |c_{I,i}|^2 + \sum |c_{II,i}|^2} \quad (1)$$

170 with  $c_I = \{c_{I,i}|i = 1, \dots, N\}$  and  $c_{II} = \{c_{II,i}|i = 1, \dots, N\}$  the local wavelet coefficients acquired  
171 from the same spatial location in the oriented detail image of the reference image and the image it is  
172 being compared to, and  $c^*$  the complex conjugate of  $c$  [34]. These local CW-SSIM indices are combined  
173 into a single index per oriented detail image using a  $7 \times 7$  Gaussian filter. The standard deviation of  
174 the Gaussian was defined as a quarter of the size of the detail image [34]. Subsequently, the mean of  
175 the CW-SSIM indices of the oriented detail images is obtained, resulting in the final CW-SSIM index  
176 describing the similarity between the two images.

177  
178  
179 In this study, the CW-SSIM indices over time were obtained by calculating a representative  
180 CW-SSIM index. The representative CW-SSIM indices were calculated from the ten second ultrasound  
181 clips, which were obtained after every kilometer ran by the athlete. Ten randomly chosen reference  
182 frames of first and the previous acquisition were compared to all frames of an ultrasound clip. The  
183 random choice of reference frames prevented bias and ensured the inclusion of reference frames from  
184 different time points in the gait cycle. For every reference frame, the ten highest CW-SSIM indices  
185 were considered, since every acquisition contained minimally ten gait cycles, and averaged. Finally,  
186

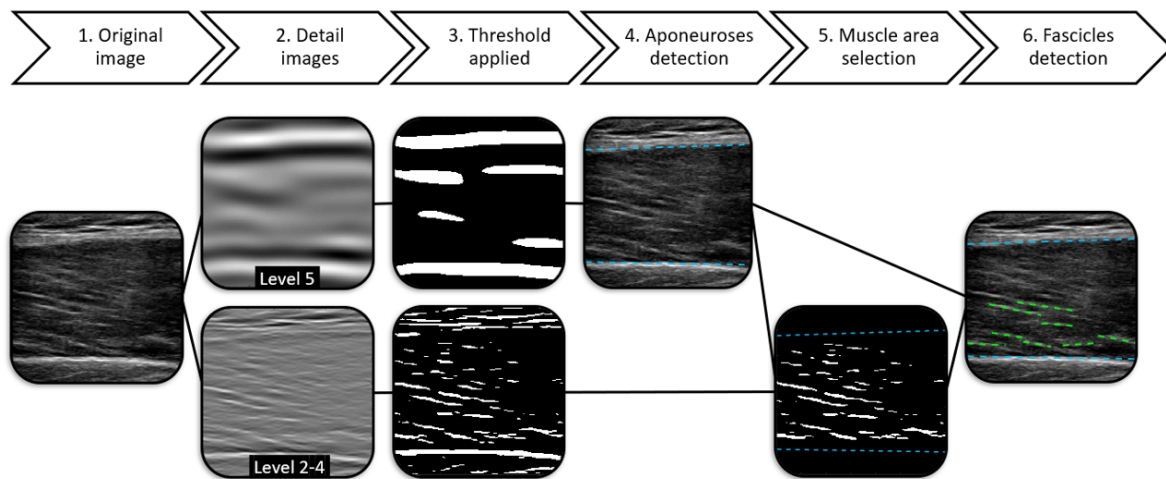
187 for every kilometer, the maximum of the ten averaged CW-SSIM indices was taken, to obtain the  
 188 representative CW-SSIM index. Frames showing probe-skin contact loss were excluded from the  
 189 field-of-view stability analysis.

## 190 Functional evaluation

191 For functional evaluation, the muscle thickness and pennation angle of the fascicles were  
 192 computed. For this computation, an adapted version of the method described in Heres et al. [18]  
 193 was used, which was optimized for the imaging settings used in this study.

194 First of all, the frequency spectra of the images were decomposed, as explained previously, into five  
 195 levels with four orientations. Each level of detail images contains a specific structure size range  
 196 (Table 1). Accordingly, for aponeurosis detection level 5 was used, whereas for fascicle detection  
 197 levels 2-4 were adopted (Fig. 2, 2<sup>nd</sup> step). For both, the third orientation ( $\pi$  rad) was used, since the  
 198 structures selected from this orientation are perpendicular to the ultrasound beam. Selection of only  
 199 this orientation leads to a reduction in noise in the resulting detail images depicting the aponeuroses  
 200 and fascicles. Subsequently, an adaptive threshold was applied to the detail images of the aponeuroses  
 201 and fascicles [36], which segmented the image into three clusters with minimal variance within each  
 202 cluster. Finally, the clusters containing the aponeuroses or fascicles was selected (Fig. 2, 3<sup>rd</sup> step).

203



**Figure 2.** The workflow of the muscle architecture detection. (1) The original image (2) is decomposed into five oriented detail images with four orientations. Level 2-4 and level 5 are used for fascicles and aponeuroses detection, respectively. For both, the structure orientation perpendicular to the ultrasound beam is used. (3) Subsequently, a threshold is applied to the detail images of the aponeuroses and fascicles. (4) In the aponeuroses detail image, the edges of the anterior and posterior aponeurosis adhering to the muscle are identified, respectively. (5) Only the region between these aponeuroses is selected for fascicles detection. (6) The detected aponeuroses and fascicles super imposed onto the original image.

204

205

206 For aponeurosis detection, the coordinates of the middle point of the anterior and posterior  
 207 aponeurosis were manually selected in the first frame only. In some cases, another collagen structure  
 208 was present near the aponeuroses. Therefore, for both the anterior and posterior aponeurosis, the  
 209 biggest structure was selected in the detail image depicting the aponeuroses within a range of  $\pm$  two  
 210 millimeters from these manually selected coordinates. The coordinates of the two points were updated  
 211 to the center of the selected biggest structures within this four millimeter range. Subsequently, the  
 212 edges of the anterior and posterior aponeurosis adhering to the muscle were detected. A first order  
 213 polynomial was fit through these edges, resulting in the segmentation of the muscle (Fig. 2, 4<sup>th</sup> step).

214 The anterior-posterior muscle thickness was estimated by averaging the vertical distances between both  
215 segmented edges for the entire field-of-view. In rare cases, a thick muscle fiber bundle was captured as  
216 the posterior aponeurosis. Hence, in case the angle of the posterior aponeurosis was bigger than three  
217 degrees, the frame was ignored in the functional analysis. In some frames, an artery was visible and  
218 mistaken for aponeurosis. These falsely detected aponeuroses were excluded through visual inspection.

219

220 For fascicle detection, the segmented muscle area was selected in the thresholded detail image  
221 displaying the fascicles (Fig. 2, 5<sup>th</sup> step). The outer two millimeters of the selected area were  
222 disregarded, since these regions mostly contained noisy structures, which affected fascicles detection  
223 negatively. In addition, all structures smaller than the empirically determined threshold of 200  
224 pixels were also removed, since these were too small for pennation angle computation. Through the  
225 remainder of the structures within the muscle, a first polynomial was fit through the center of masses  
226 of the left and right part of each fascicle (Fig. 2, last step). Subsequently, the pennation angle of the  
227 fascicles was calculated with respect to the posterior aponeurosis. A representative pennation angle  
228 per frame was estimated by obtaining the median of the pennation angles within the frame.

### 229 3. Results

230 The datasets from nine out of the ten volunteers were analyzed during post-processing, since  
231 in one of the volunteers the probe and its fixation device lost complete contact after running three  
232 kilometers. Only in one of the subjects, acquisitions were obtained during the full race. In the other  
233 subjects, the battery died prior to finishing the race. In subjects 8 and 9, the straps of the fixation  
234 device were tightened after running 11 kilometers. In the remainder of the subjects, the probe and its  
235 fixation stayed in the same position, without manual interference during the measurements. The best  
236 image quality for the dynamic musculoskeletal measurements was produced using the ultrasound  
237 preset named "Lung" (Fig. 1: 4 - 9). In this preset, image contrast was highest and the persistence  
238 (i.e. temporal compounding) seemed minimized. In the musculoskeletal preset, persistence was high,  
239 resulting in the visualization of artificial aponeuroses and fascicles, due to averaging of previous  
240 frames (Fig. 1: 1 & 2). In the vascular preset, the persistence was high, the contrast was relatively low,  
241 and the proximal aponeurosis was hyper-echoic, hampering functional analysis (Fig. 1: 3).

#### 242 Image quality

243 The image quality was quantified by estimation of the probe-skin contact preservation and  
244 field-of-view stability.

245 Probe-skin contact was preserved for the full duration of the measurements in four volunteers. In the  
246 other five included volunteers, some probe-skin contact loss was observed, which occurred cyclically  
247 during part of the gait cycle (Fig. 3b). The degree of this contact loss ranged from 6 - 57 % of the gait  
248 cycle (Fig. 3c).

249

250 The field-of-view stability was measured using the CW-SSIM. For each acquisition, a representative  
251 CW-SSIM index was computed (Fig. 4). The CW-SSIM indices with respect to the first acquisition  
252 reduced slightly over time (Fig. 4a). The difference in CW-SSIM index between the last and second  
253 acquisition was  $0.09 \pm 0.06$ . The average difference between the first and second acquisition was  
254 largest, being  $0.21 \pm 0.12$ . In runners 1 and 2, the CW-SSIM indices were relatively lower, which were  
255 acquired using the musculoskeletal preset.

256 The CW-SSIM indices with respect to the previous acquisitions were roughly constant. The average  
257 similarity with respect to the previous acquisition was quantified using a CW-SSIM index of  $0.85 \pm$   
258  $0.08$ . Again, the structural similarities of the first two volunteers were smaller due to the use of a less  
259 optimal preset.

260

261 For most acquisitions, a portion of the acquisitions was adequate for functional analysis (46

± 27 % of the full acquisition). Only in 13% of the acquisitions the image quality was sufficient to perform functional computations throughout almost the full acquisition. In most acquisitions, parts of the acquisition could not be analyzed due to inadequate image quality caused by either probe-skin contact loss (6 - 57 % of each gait cycle, see Figure 3), the presence of an artery in the imaging plane close to the posterior aponeurosis (only occurred in volunteer 1 in two acquisitions), detection of an artificial posterior aponeurosis resulting from temporal compounding (main issue in subjects 1-3), or hypo-echoicity of the posterior aponeurosis (only 1-3 frames of most gait cycles). The probe-skin contact loss, hypo-echoicity of the aponeurosis, or especially the combination of probe-skin contact loss and hypo-echoicity of the aponeurosis resulted frequently in the inability to detect the aponeuroses in the next few frames, or a full or multiple gait cycles in a row.

#### Functional evaluation

A demonstration of functional measurements during endurance running is shown by measuring the thickness of the *vastus lateralis* muscle and its pennation angles. These dynamic functional measurements were performed for each ultrasound recording of ten seconds obtained successively after running a kilometer. Subfigures 5a and b depict an example of these dynamic functional measurements. In these subfigures, the muscle thickness is displayed using repeating segments, with each individual segment representing a single gait cycle. The pennation angle also shows variation within the 10 second interval, though the individual gait cycles are less clearly distinguishable. For each kilometer, the mean thickness and pennation angle were calculated, which are illustrated in Subfigures 5c and d. The mean muscle thickness ranged between 1.29 and 2.50 cm, and the mean pennation angles ranged between 1.3 and 12.8 degrees.

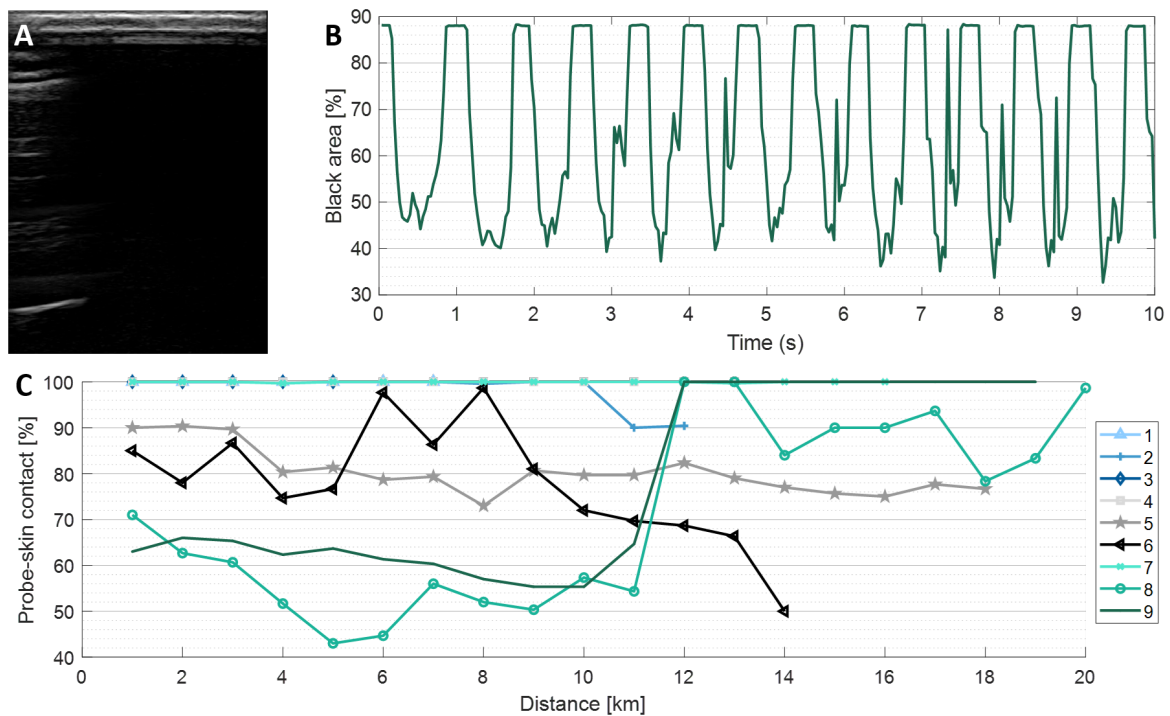
The error bars in these subfigures 5c and d are the standard deviations representing parameter variation related to the gait cycle. Hence, the bars give an impression of the muscle's contraction force of each gait cycle independently. Both the mean values and their standard deviations of these functional parameters remained approximately constant. The average fluctuation of the muscle thickness and the pennation angles over time were 0.11 cm and 0.94 degrees, respectively. The mean standard deviation of the error bars of the thickness and pennation angle were 0.038 cm and 0.41 degrees, respectively.

## 4. Discussion

The introduction of portable ultrasound systems and ultrasound transducer fixation devices has made dynamic evaluation of the skeletal muscles possible. The feasibility of short-term dynamic ultrasound acquisitions has already been demonstrated previously in cycling exercise in ultrasonography of skeletal muscles and in echocardiography [18,27]. In this study, the feasibility of long-term dynamic functional measurements has been investigated in ten endurance runners. Endurance runners were selected as participants for this research, since their labor is relatively invariable and there is no danger of fixated transducer motion as a consequence of external forces (e.g. contact with other athletes, attributes, or the ground). In addition, the forces that are generated when the feet come into contact with the ground might also have an effect on the feasibility of long-term dynamic acquisitions during endurance running.

When using an ultrasound transducer designed for smart mobile usage, usually only the preset, gain, and power can be modified. In this study, a linear array Philips Lumify L12-4 was used. For this transducer, five presets were available (i.e. lung, musculoskeletal, soft tissue, superficial, and vascular), each optimized for their specific application. The musculoskeletal preset was most likely optimized for static acquisitions, since it has a high persistence (i.e. temporal compounding). A high persistence in static musculoskeletal acquisitions will lead to an augmented contrast and a reduction in noise. However, in dynamic measurements high persistence results in the materialization of artificial





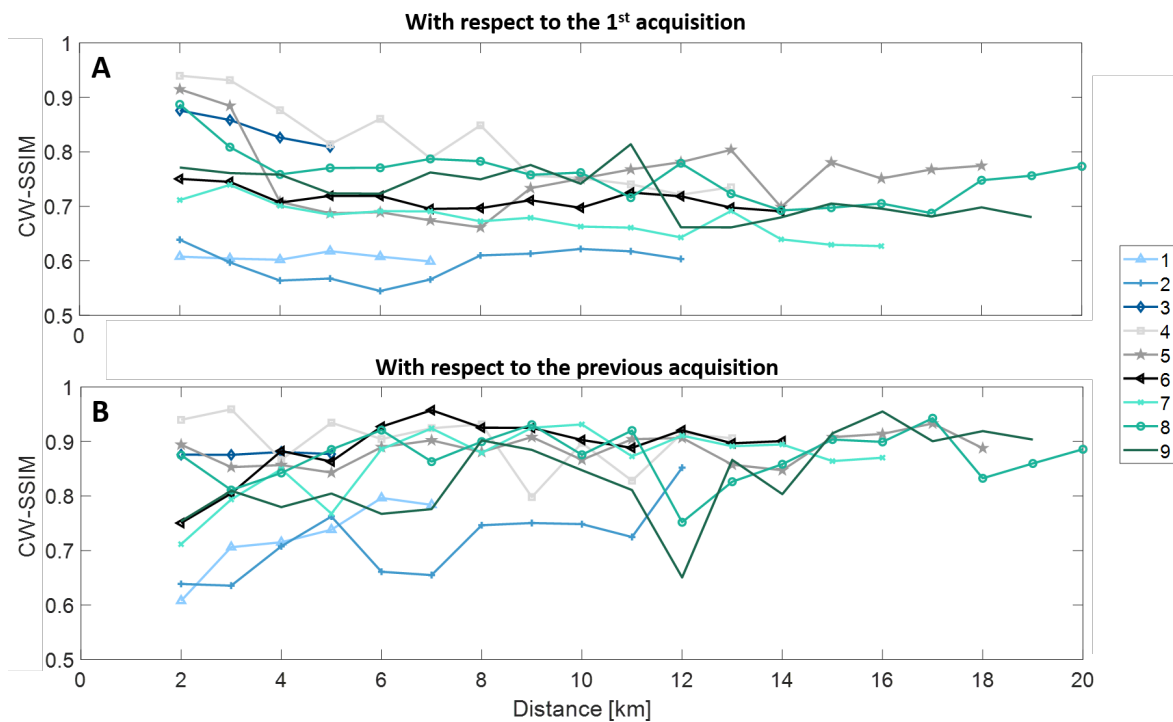
**Figure 3.** Probe-skin contact. (a) An example of an ultrasound image obtained during probe-skin contact loss. The right part of the frame shows a total reflection artifact, caused by a big difference in acoustic impedance between the ultrasound probe and the air. At the left side some probe-skin contact is still preserved. (b) A representative example of an acquisition during which probe-skin contact loss occurred. Probe-skin contact was defined as an ultrasound frame consisting of less than 80% black pixels. This example was acquired during the first kilometer of volunteer 9. As shown in the subfigure, contact loss occurs cyclically during the same phase of the gait cycle, which was the case in all volunteers with probe-skin contact loss. (c) The percentage of frames within the acquisition that was obtained with preserved probe-skin contact. In four subject, probe-skin contact was preserved during the entire measurement. In the other five volunteers, the probe was in contact with the skin during 43 - 100 % of the gait cycle.

310 posterior aponeuroses. Therefore, the musculoskeletal preset is deficient for dynamic measurements.  
 311 In the vascular preset, the persistence appeared to be higher and the contrast lower in comparison  
 312 to the musculoskeletal preset. Consequently, the aponeuroses detection algorithm failed to track  
 313 the posterior aponeurosis during the gait cycle. Hence, this dataset was excluded from functional  
 314 evaluation. The lung preset was most suitable for these dynamic measurements, since the contrast was  
 315 sufficient and no temporal compounding seemed to be applied.

316

317 The image quality was evaluated by quantification of probe-skin contact preservation and  
 318 the field-of-view stability. In four volunteers, the probe-skin contact was preserved during the entire  
 319 measurement. However, in five volunteers, temporary probe-skin contact loss occurred for some  
 320 or all acquisitions. Probe-skin contact loss could be a result of gel loss caused by sweating, a slight  
 321 probe displacement, muscle deformation during contraction, or by probe dislocation induced by  
 322 gravitational pull or inertia of the probe motion countered by the ground impact forces. Within  
 323 an acquisition, probe-skin contact loss occurred during part of the gait, which was approximately  
 324 identical for each gait cycle captured within the acquisition. Although functional analysis of the  
 325 complete gait cycle was impossible in these acquisitions, functional parameter alterations within these  
 326 gait sections over time still contain valuable information.

327 The field-of-view stability was estimated using the CW-SSIM. The initial CW-SSIM index drop  
 328 was highest, which could be caused by a dislocation of the transducer, or by a general temporal



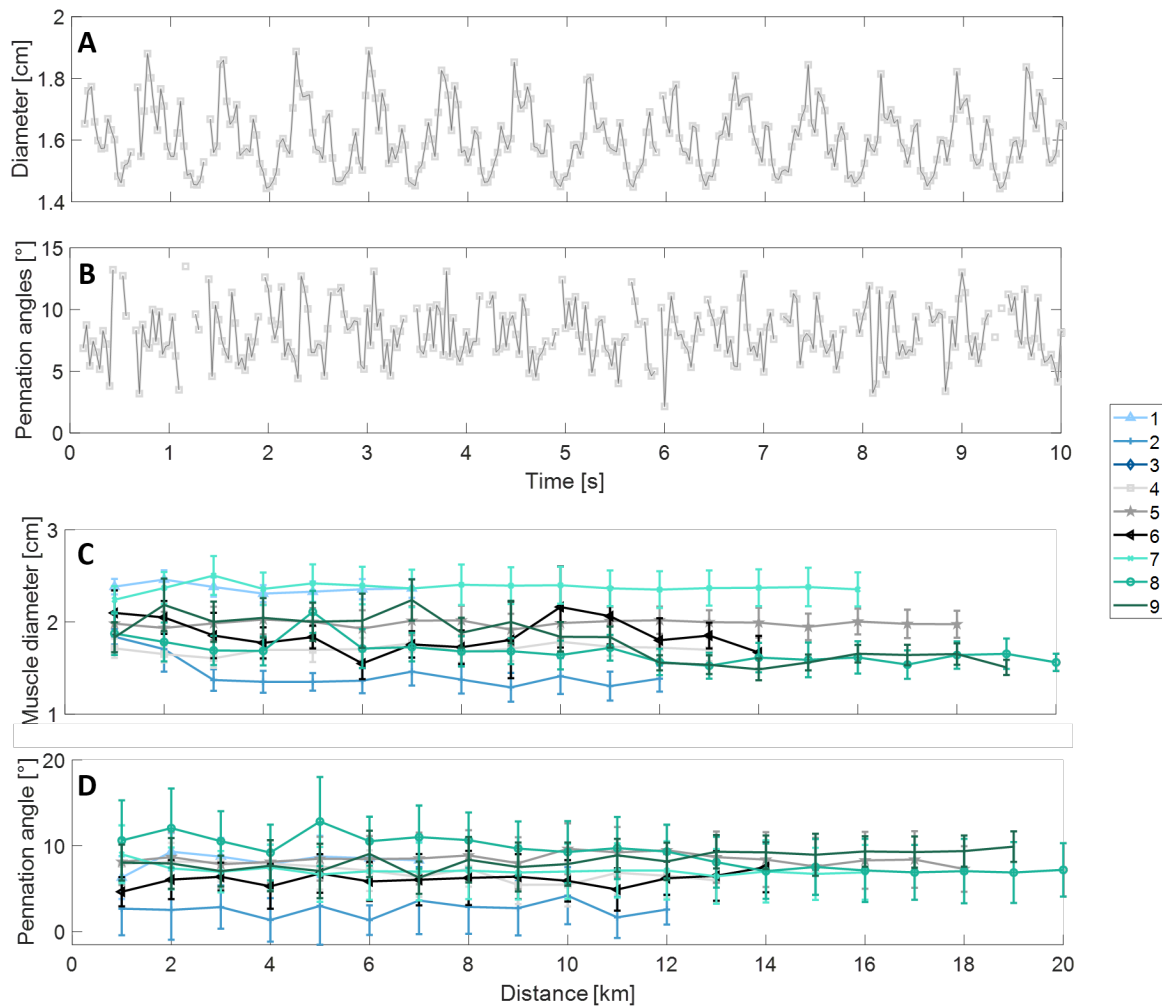
**Figure 4.** Field-of-view stability. (a) The complex-wavelet structural similarity index method values of each acquisition with respect to the first acquisition obtained after the first kilometer. The difference between CW-SSIM indices between the last and second acquisition is on average 0.09. (b) The CW-SSIM indices with respect to the previous acquisition, which was on average 0.85. The CW-SSIM indices of volunteer 1 and 2 are relatively lower, which were acquired using a different preset.

329 decorrelation of the ultrasound images provoked by noise and/or slight out-of-imaging-plane motion.  
 330 A dislocation of the transducer would result in a relatively big alteration in the measured functional  
 331 parameters. However, the difference in muscle thickness and pennation angle between the first and  
 332 second kilometer is comparable to the average variation of these functional parameters. Accordingly,  
 333 the initial drop in CW-SSIM indices is expected to be caused by temporal decorrelation.

334

335 The functional parameters in this study consisted of the muscle thickness and pennation angles of the  
 336 fascia with respect to the posterior aponeurosis. In eight out of nine runners, a sufficient portion of  
 337 gait cycle could be analyzed. The excluded dataset was acquired using the vascular preset resulting in  
 338 poor image contrast, and the display of extra artificial posterior aponeuroses, as explained previously.  
 339 The average values of the functional parameters remained fairly constant throughout the race, which  
 340 is expected based on literature studies examining alterations in muscle thickness and pennation angles  
 341 in endurance runners and resistance training [29–31]. In these studies, the muscle thickness and  
 342 pennation angles are measured statically prior and post training. These studies showed no adaptations  
 343 in muscle thickness and pennation angle after 10 weeks of endurance running or after running a  
 344 marathon, whereas during resistance training augmentations of both parameters were observed.  
 345 However, it should be noted that in this study the ultrasound measurements were performed  
 346 dynamically instead of the static ultrasound measurements performed in the previously mentioned  
 347 studies. Still, the stability of both functional parameters suggests the preservation of field-of-view  
 348 throughout the race.

349 The functional parameter fluctuations observed throughout the gait cycles are a consequence of muscle  
 350 contraction. Moreover, during contraction, out-of-plane motion occurred to some degree in all runners.  
 351 The muscle contraction-related variations are similar in all endurance runners and remained roughly  
 352 constant over time.



**Figure 5.** Dynamic functional measurements. For all acquisitions, the thickness of the muscle and the pennation angle of the fascicles are computed. (a) and (b) are examples of these computations. These two examples were derived from the ultrasound images obtained at the 7<sup>th</sup> kilometer in subject 4. In (a) the cyclic contraction of the muscle is visible, whereas the pennation angles contain relatively more noise. (c) and (d) display the mean muscle thickness and the pennation angle for all kilometers. The error bars show the standard deviation of each acquisition, representing the variation within the gait cycle, which is a result from muscle contraction. The muscle thickness and pennation angle are roughly constant over time.

353

354 The feasibility of long-term dynamic ultrasound image acquisition and functional evaluation  
 355 of the *vastus lateralis* has been demonstrated. However, some limitations were observed in this  
 356 study. The main limiting factor was the inability to acquire functional and architectural information  
 357 throughout the complete gait cycle in most subjects, which was mainly caused by probe-skin contact  
 358 loss. However, probe-skin contact loss could be overcome by the incorporation of a dedicated gel patch  
 359 during the acquisitions or by further optimization of the probe fixation device. The frequency and the  
 360 impact of the issues hampering posterior aponeurosis detection (e.g. hypo-echoicity of aponeurosis)  
 361 are expected to decrease largely once the probe-skin contact loss has been minimized. Additionally,  
 362 the currently used algorithm could be improved further by taking into account an estimation of the  
 363 aponeurosis motion during a gait cycle based on the successfully analyzed frames of (other) gait cycles.  
 364 Alternatively, deep learning models could be used for feature detection [8,37].  
 365 3-D acquisitions could further improve the dynamic functional evaluation. In 3-D ultrasound,  
 366 out-of-plane motions can be tracked and stabilized during post-processing. Furthermore, feature

367 detection and functional assessment of architectural and mechanical parameters is expected to be more  
368 robust. Therefore, local functional analysis will also be improved in 3-D. However, the effect of the  
369 spatial and temporal resolution reduction on the performance of the dynamic functional measurements  
370 should be analyzed. Moreover, there are no 3-D portable US systems on the market, which is due to  
371 the higher level of complexity in both hardware and software. Additionally, the use of ultrafast imaging  
372 would be beneficial for the analyses proposed, but an ultrafast portable solution is also unavailable.

373

374 The results observed in this study are expected to be applicable to other muscles situated in  
375 the leg or arm. Hands-free, continuous ultrasound acquisitions are applicable in the field of sports  
376 to analyze and improve muscle activation and motion, and gait. Monitoring of the muscles during  
377 exercise could also aid in the creation of optimized training schemes, or in the assessment of the  
378 athlete's fitness level.

379 Another application of hands-free, continuous ultrasound evaluation of the muscle is during the  
380 revalidation process after a muscle injury. The acquisitions could help to determine when it is safe to  
381 return to play with minimal chance of injury repetition.

382 In other ultrasound fields, the application of hands-free, continuous acquisitions could also be  
383 beneficial. In echocardiography, upright, continuous, hands-free stress echocardiography could be  
384 performed, leading to a reduction in image plane variation between exercise levels. Additionally, this  
385 method could be applied for continuous cardiac monitoring in the intensive care, or during operations,  
386 since transthoracic echocardiography has shown to be able to detect ischemic events that are difficult  
387 to recognize using ECG or other widely used hemodynamic monitoring parameters [38].

388 Furthermore, the use of a fixation device could reduce the prevalence of work-related musculoskeletal  
389 disorders amongst sonographers. The high quantity of ultrasound exams performed resulted in  
390 repetitive strain injury symptoms to be experienced by ninety percent of the sonographers despite  
391 corrections in their posture and the use of an adjustable working space [39,40]. In echocardiography,  
392 probe fixation has shown to reduce muscle contraction in the forearm and total shoulder abduction  
393 time, without extending the exam duration [28].

394

395 In future studies, a larger group of endurance runners should be included. Once the current  
396 limitations are overcome, functional parameters can be measured during the full gait cycle. These  
397 continuous functional measurements may aid in the detection of gait cycle modifications resulting  
398 from fatigue. Alternatively, differences in gait between trained and untrained runners, or during  
399 different stages of the revalidation process might be detected. These differences in gait might be used  
400 for gait correction, which may aid in the prevention of injury or avoid injury repetition. In addition,  
401 the combined acquisition of ultrasound and electromyography, could lead to additional relevant  
402 dynamic information of muscle activation during exercise.

403 This study encourages the dynamic computation of local functional parameters (e.g. individual  
404 pennation angles, fascia lengths, local strain and strain rates). Global functional assessment is limited  
405 by the independency between muscle architecture and activity. Additionally, various disorders  
406 manifest themselves locally [4,41]. Furthermore, muscles contain different fiber types of which the  
407 response varies with exercise intensity and duration [41]. Local parameters might provide a more  
408 profound insight in musculoskeletal disorders and facilitate monitoring of training progression in  
409 athletes.

410 Future research using dynamic, hands-free ultrasound might provide identification markers for  
411 fatigue (e.g. pennation angle increase, reduction in motor unit recruitment, local alterations in muscle  
412 stiffness), which can contribute to injury or musculoskeletal disorder prevention, and may help  
413 drafting optimal practice schemes for professional athletes. Furthermore, local, dynamic monitoring of  
414 muscle architecture and characteristics might provide an indication when a patient or injured athlete  
415 is able to perform exercise again with a low risk of re-injury, or the injury becoming chronic [42]. It  
416 is unclear which rehabilitation program is most successful for different types of injuries and how

417 much effect the local muscle characteristics have on injury risks. Therefore, further research on these  
418 parameters in the rehabilitation using dynamic ultrasound could be valuable.

## 419 5. Conclusions

420 The feasibility of functional measurements in the *vastus lateralis* muscle has been demonstrated  
421 during endurance running. After running the first kilometer, the field-of-view stability remained high  
422 during the remainder of the race. Although probe-skin contact loss was the study's main limiting  
423 factor, a section or the complete gait cycle could be visualized and analyzed in all endurance runners in  
424 all obtained ultrasound acquisitions. Computation of the pennation angle and muscle thickness were  
425 successful in part of or almost the full gait cycle. These functional parameters remained approximately  
426 stable throughout the measurement. These findings are expected to be extendable to the application  
427 on other muscles.

428  
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430 B.T. and R.L.; software: M.S.; validation: M.S.; formal analysis: M.S.; investigation: B.T., C.C. and A.M. ; resources:  
431 B.T., A.M., F.V. and R.L.; data curation: M.S., C.C., B.T. and A.M.; writing—original draft preparation: M.S.;  
432 writing—review and editing: M.S., C.C., A.M., B.T., F.V. and R.L.; visualization: M.S.; supervision: C.C. and R.L.;  
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435 **Institutional Review Board Statement:** The study was conducted according to the guidelines  
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439 12, 2018, and N19.076, September 16, 2019). In 2017, the study involved measurements with CE  
440 marked devices on endurance runners, who were not specifically recruited and asked to participate  
441 in a professionally organized endurance running event for this study. These three runners gave their  
442 written informed consent for the ultrasound measurements during the endurance running event. For  
443 this purpose, protocol validation by a METC Committee was not best practice at the time. For all  
444 volunteers written informed consent was obtained.

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## 451 Abbreviations

452 The following abbreviation is used in this manuscript:

453  
454 CW-SSIM complex-wavelet structural similarity index method

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